



HY10P40

Datasheet

8-Bit RISC-like Mixed Signal Microcontroller
Embedded 24-Bit $\Sigma\Delta$ ADC

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1. 特点

- 8-Bit RISC-like 微控制器，具有 46 条高性能指令集 H08B
- 24-Bit $\Sigma \Delta$ ADC 模拟数字转换器
 - 梳状滤波器采二阶设计，转换频率达 1.95Ksps
 - 取样频率 250KHz
 - 超取样频率设置 128~32768
 - 全差动输入信号与测量范围的零点调整
 - 信号放大
x1/4,x1/2,x1,x2,x4,x8,x16
 - 测量信号输入信道 8ch
 - 低温飘系数
- 内部电源系统
 - 内置 LDO 线性稳压电源 VDDA
 - ◆ 内部模拟电路或外部传感器电压源
 - ◆ 输出可设置 2.4/2.7/3.0V, 可外灌输入电压
 - ◆ 低操作功耗与低温飘系数
 - 内置参考电压源 ACM
 - ◆ 模拟电路参考电压源(1.2V)
 - ◆ 低操作功耗与低温飘系数
- 定时器
 - Watch Dog
 - ◆ 复位事件与中断事件
 - 8-bit Timer
 - ◆ 中断事件
 - 16-bit Timer
 - ◆ 16-Bit PWM 输出
 - ◆ 两个 8-Bit PWM 输出
 - ◆ 中断事件
- 工作电压与操作温度范围
 - V_{DD}: 2.2V ~ 3.6V
 - -40°C ~ 85°C
- 工作频率
 - 内建高精度 HAO 震荡器
2MHz/4MHz/8MHz
 - 内建低功耗 LPO 震荡器 14KHz
- 记忆体型式
 - 2KW OTP 程序内存
 - 128B 数据存储器
 - 6 层堆栈
 - Build-In EPROEM
 - ◆ V_{PP} 工作电压 6.0V
 - ◆ 64W EPROM 内存
- 引脚特色
 - 具 10mA 驱动能力
 - 自定义功能模块输出引脚设计
- 复位机制
 - Power On Reset
 - Brown Out Reset
 - Watch Dog Reset
- I²C 通讯接口

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2. 引脚定义

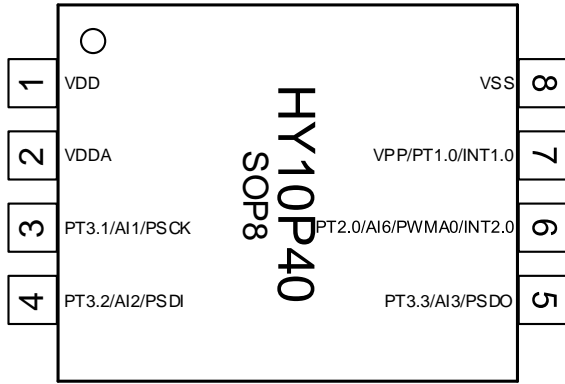


图 2-1 HY10P40 SOP8 引脚图

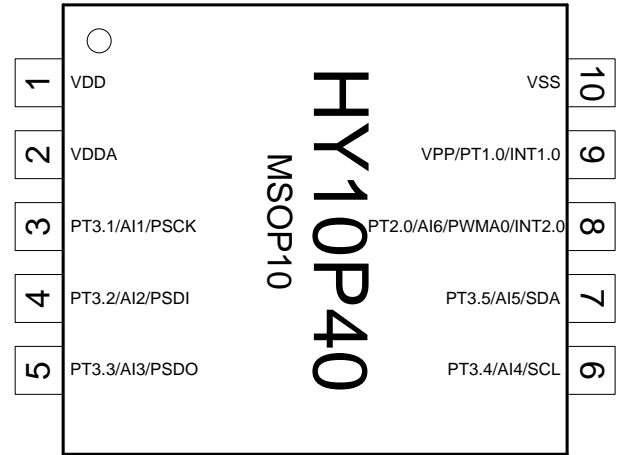


图 2-2 HY10P40 MSOP10 引脚图

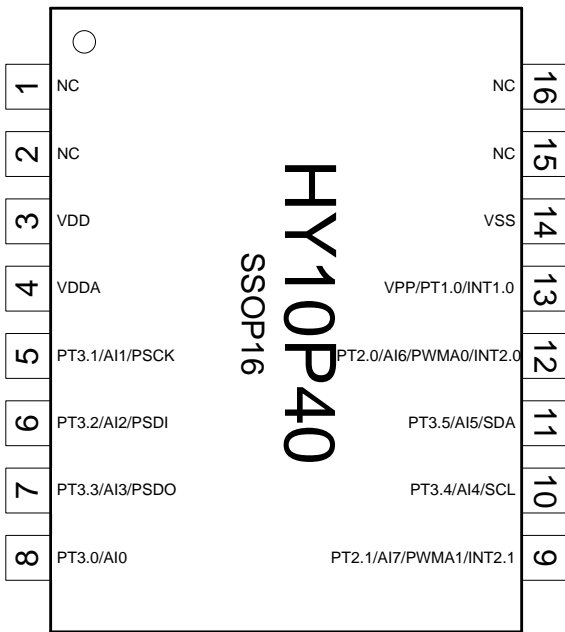


图 2-3 HY10P40 SSOP16 引脚图

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2.1. 引脚定义说明

“脚定：输入,输入义：输出,输出义：模拟, 比义说：史密斯触发, 密斯触：CMOS I/O,SOP：电压源,电压源：或,或压源：可忽略

封装			引脚名称	设计		描述
SSOP16	MSOP10	SOP8		型式	缓冲	
1	-	-	NC	X	X	-
2	-	-	NC	X	X	-
3	1	1	VDD	P	P	芯片工作电压源接引脚
4	2	2	VDDA	P	P	LDO 线性稳压电源输出引脚
5	3	3	PT3.1	I/O	S/C	数字输入 / 输出引脚
			AI1	A	A	模拟输入通道
			PSCK	I	S	OTP 读/写界面 PSCK 接口
6	4	4	PT3.2	I/O	C	数字输入 / 输出引脚
			AI2	A	A	模拟输入通道
			PSDI	I	S	OTP 读/写界面 PSDI 接口
7	5	5	PT3.3	I/O	C	数字输入 / 输出引脚
			AI3	A	A	模拟输入通道
			PSDO	I/O	S	OTP 读/写界面 PSDO 接口
8	-	-	PT3.0	I/O	C	数字输入 / 输出引脚
			AI0	A	A	模拟输入通道
9	-	-	PT2.1	I/O	C	数字输入 / 输出引脚
			AI7	A	A	模拟输入通道
			PWMA1	O	C	TMB1 的 PWM1 输出引脚
INT2.1	I	S	外部中断源(Falling Edge Trigger Interrupt)			
10	6	-	PT3.4	I/O	C	数字输入 / 输出引脚
			AI4	A	A	模拟输入通道
			SCL	I/O	S	I2C 通讯接口引脚
11	7	-	PT3.5	I/O	C	数字输入 / 输出引脚
			AI5	A	A	模拟输入通道
			SDA	I/O	S	I2C 通讯接口引脚
12	8	6	PT2.0	I/O	C	数字输入 / 输出引脚
			AI6	A	A	模拟输入通道
			PWMA0	O	C	TMB1 的 PWM0 输出引脚
INT2.0	I	S	外部中断源(Falling Edge Trigger Interrupt)			
13	9	7	PT1.0	I	S	数字输入
			VPP	P	P	OTP 烧录电压引脚
INT1.0	I	S	外部中断源			
14	10	8	VSS	P	P	芯片工作电压源接地端引脚
15	-	-	NC	X	X	-
16	-	-	NC	X	X	-

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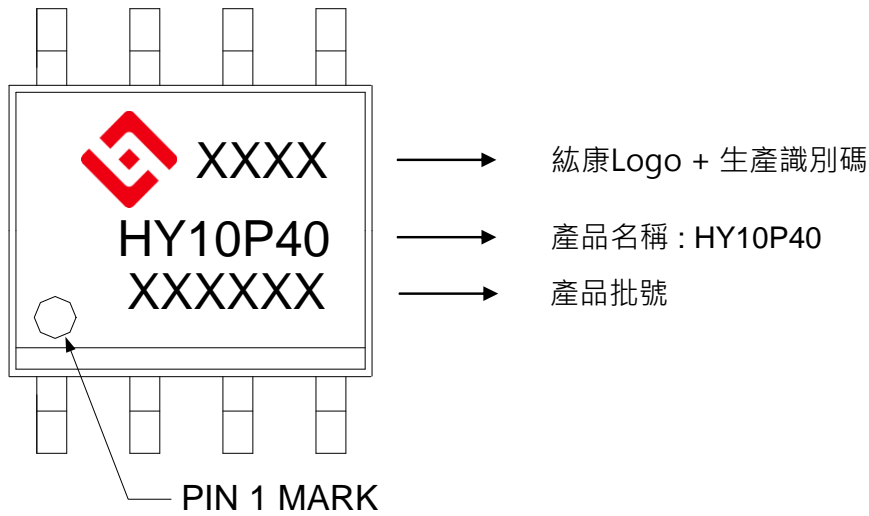
表 2-1 引脚定义与功能说明

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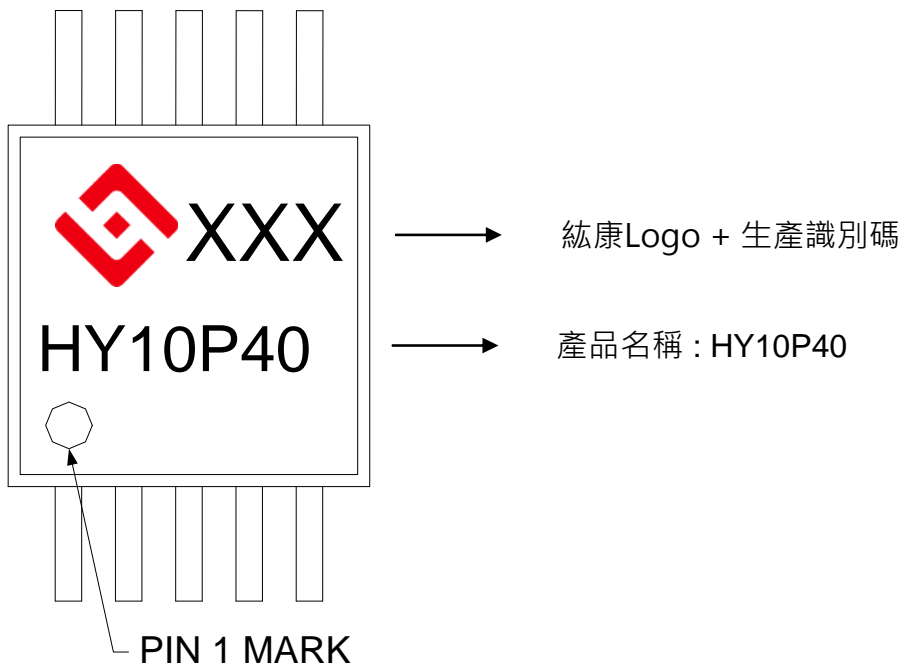
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2.1.1. SOP8 封装片标记信息



2.1.2. MSOP10 封装片标记信息

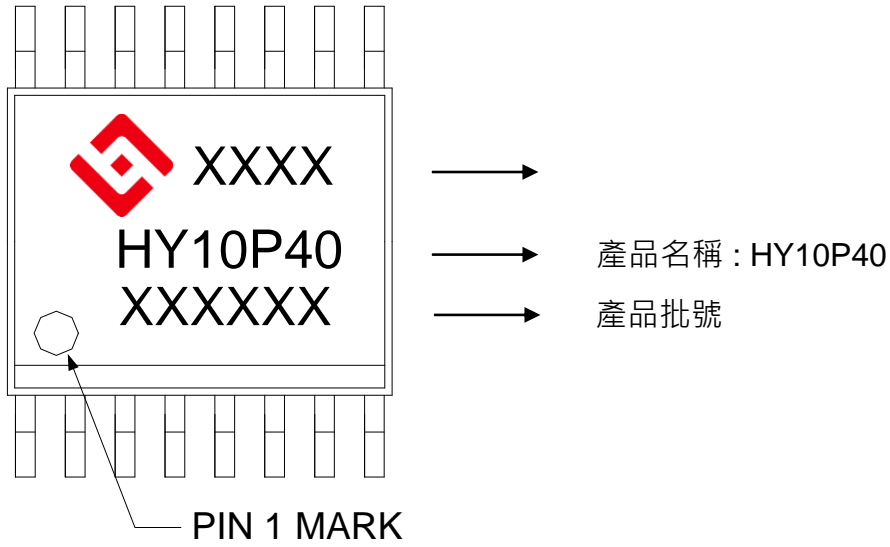


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2.1.3. SSOP16 封装片标记信息



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3. 应用电路

3.1. PIR application (Pyroelectric infrared-detector)

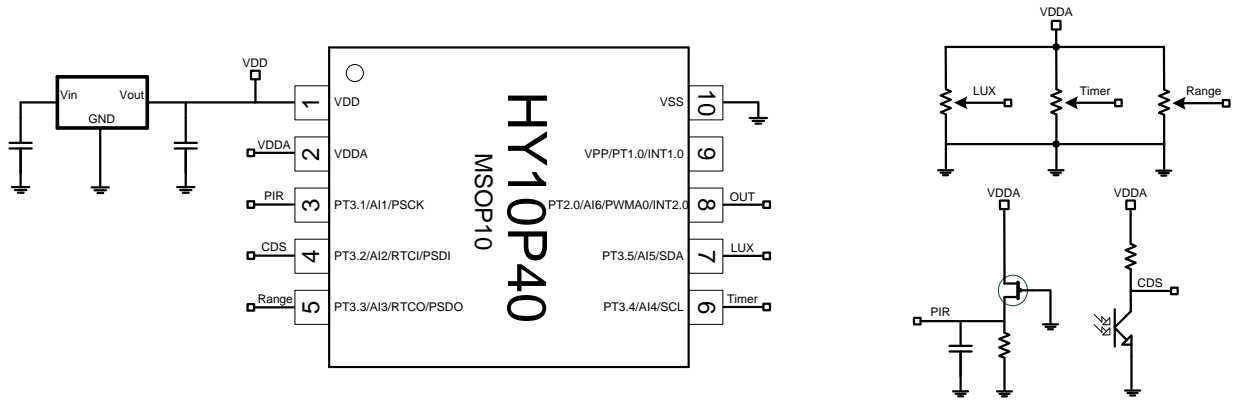


图 3-1 PIR 应用电路

3.2. Smart Pressure sensor application

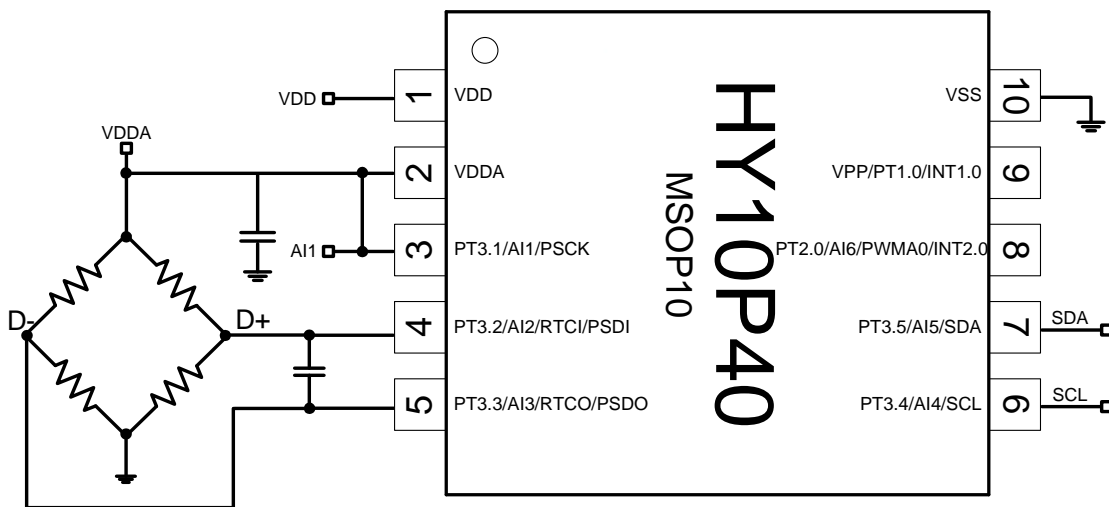


图 3-2 Smart Pressure Sensor 应用电路

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4. 功能概述

4.1. 内部方块图

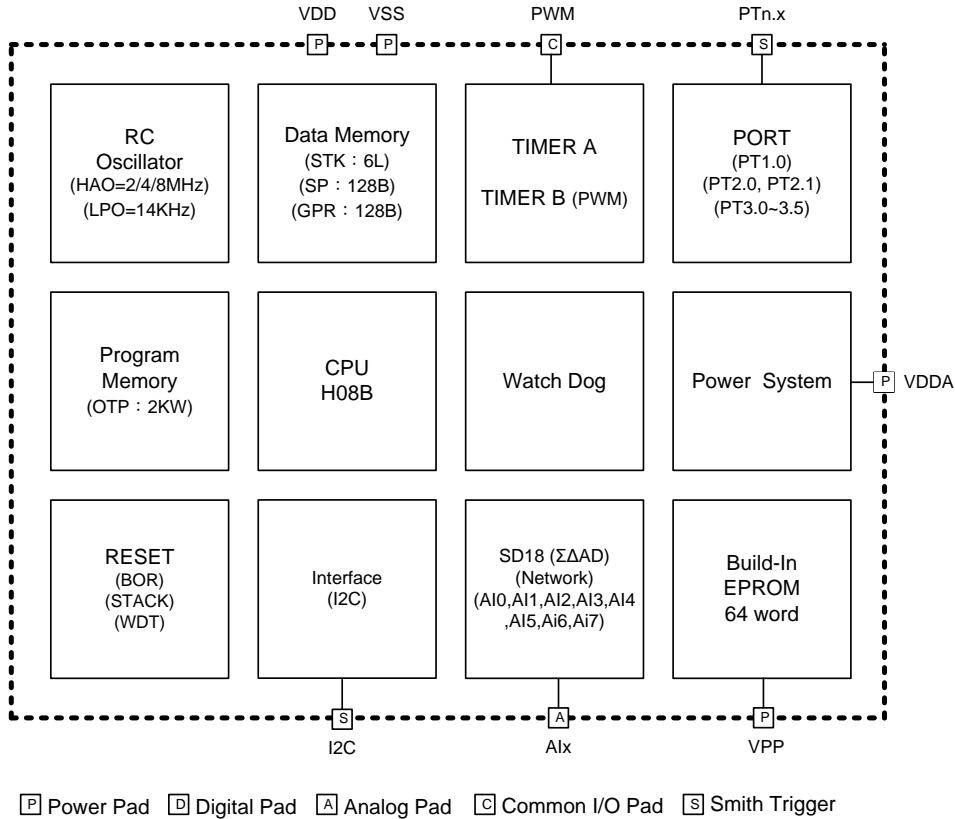


图 4-1 HY10P40 内部方块图

4.2. 相关说明与支持文件

芯片功能相关使用说明书

DS-HY10P40

HY10P40 说明书

UG-HY10SXX

HY10Pxx 系列使用说明书

APD-CORE003-Vxx

H08B 指令说明书

开发工具相关使用说明书

APD-HYIDE00X-Vxx

HY10xxx 系列开发工具软件使用说明书

APD-HYIDE00X-Vxx

HY10xxx 系列开发工具硬件使用说明书

APD-OTP001-Vxx

OTP 产品烧录引脚说明书

产品生产相关使用说明书

APD-HYIDE004-Vxx

HY1xxxx 系列生产线专用烧录器说明书

BDI-HY10P40-Vxx

HY10P40 个别产品的裸片打线信息

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4.3. SD18 Network

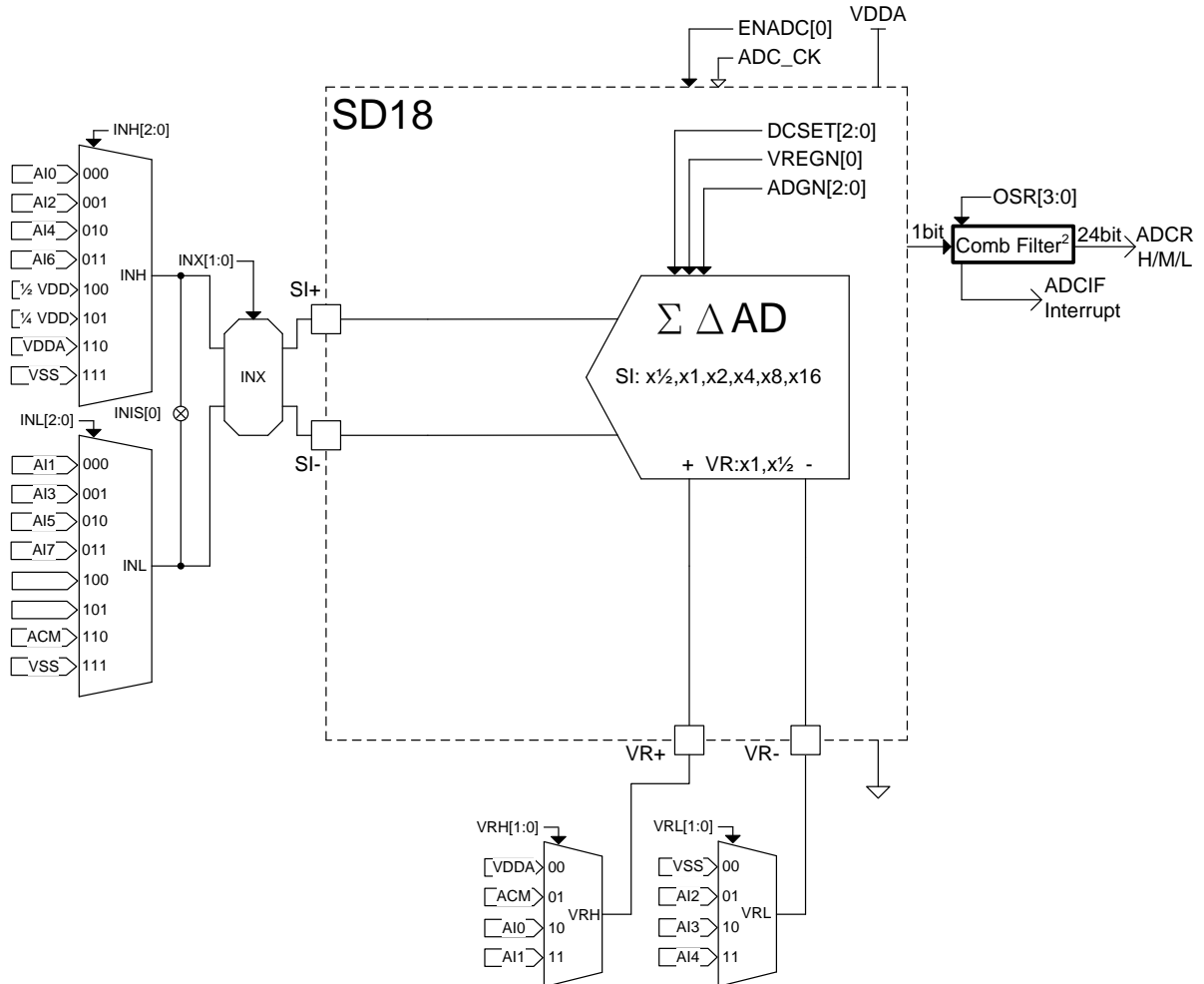


图 4-2 SD18 Network

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5. 缓存器列表

“-”no use, “r”read/write, “w”write, “r”read, “r0”only read 0, “r1”only read 1, “w0”only write 0, “w1”only write 1
“\$”for event status, “.”unimplemented bit, “x”unknown, “u”unchanged, “d”depends on condition

地址	名称	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	A-RESET	I-RESET	R/W
000h	INDF0	Contents of FSR0 to address data memory—value of FSR0 not changed								xxxx xxxx	uuuu uuuu	*****
001h	POINC0	Contents of FSR0 to address data memory—value of FSR0 post-incremented								xxxx xxxx	uuuu uuuu	*****
002h	PODEC0	Contents of FSR0 to address data memory—value of FSR0 post-decremented								xxxx xxxx	uuuu uuuu	*****
003h	PRINC0	Contents of FSR0 to address data memory—value of FSR0 pre-incremented								xxxx xxxx	uuuu uuuu	*****
004h	PLUSW0	Contents of FSR0 to address data memory—value of FSR0 offset by W								xxxx xxxx	uuuu uuuu	*****
010H	FSR0L	Indirect Data Memory Address Pointer 0 Low Byte,FSR0[7:0]								xxxx xxxx	uuuu uuuu	*****
016h	TOSH	-	-	-	-	-	TOS[10]	TOS[9]	TOS[8]	... xxxx	... uuuu*
017h	TOSL	Top-of-Stack Low Byte (TOS<7:0>)								xxxx xxxx	uuuu uuuu	*****
018h	STKPTR	SKFL	SKUN	SKOV	-	-	SKPRT[2:0]		000. 000	u\$. .\$\$\$	rw0,rw0,rw0,-,*	
01Ah	PCLATH	-	-	-	-	-	PC[10]	PC[9]	PC[8] 0000 0000*
01Bh	PCLATL	PC Low Byte for PC<7:0>								0000 0000	0000 0000	*****
023h	INTE0	GIE	ADIE	E21IE	WDTIE	TB1IE	TMAIE	E20IE	E10IE	0000 0000	0uuu uuuu*
024h	INTE1	-	-	-	-	I2CERIE	I2CIE	-	-	0000 0000	uuuu uuuu	*****
026h	INTF0	-	ADIF	E21IF	WDTIF	TB1IF	TMAIF	E20IF	E10IF	.000 0000	.uuu uuuu*
027h	INTF1	-	-	-	-	I2CERIF	I2CIF	-	-	0000 0000	uuuu uuuu*
029h	WREG	Working Register								xxxx xxxx	uuuu uuuu	*****
02Bh	STATUS	-	-	-	C	-	-	-	Z	...x xxxx	...u uuuu*
02Ch	PSTATUS	BOR	PD	TO	IDL	-	SKERR	-	-	\$000 \$00.	uu\$u u\$u.	rw0,rw0,rw0,rw0,rw0,rw0,-
02Eh	BIECN	-	-	-	-	VPPHV	-	BIEWR	BIERD	1... \$.00	1... \$.uu	r1,.....*
02Fh	BIEARH	ENBIE	-	-	-	-	11-bit look-up Table as BIEAH[2:0]		0... xxxx	u... uuuu*	
030h	BIEARL	BIE Address Register as BIEAL[5:0] or 11-bit look-up Table as BIEAL[7:0]								xxxx xxxx	uuuu uuuu	*****
031h	BIEDRH	BIE High Byte Data Register								xxxx xxxx	uuuu uuuu	*****
032h	BIEDRL	BIE Low Byte Data Register								xxxx xxxx	uuuu uuuu	*****
033h	PWRCN	ENLDO[1:0]		VDDAX[1:0]		-	-	ADRST	CSFON	0000 0000	uuuu u00u*,wr0,wr0,*
034h	OSCCN0	OSCS[1:0]		DHS[1:0]		DMS[2:0]		CPUS	0000 0000	uuuu uuuu	*****	
035h	OSCCN1	-	-	ADCS[2:0]			DTMB[1:0]	TMBS	0000 0000	uuuu uu.*	
036h	OSCCN2	-	-	-	-	HAOM[1:0]	ENHAO	LPO	.000 0011	.uuu uu11*	
037h	WDCN	-	-	-	-	ENWDT	DWDWT[2:0]		0000 0000	uuuu \$000*rw1,*	
038h	TMACN	ENTMA	TMACL	TMAS	DTMA[2:0]		-	-	0000 00..	u0uu uu..*,rw1,*	
039h	TMAR	TMA counter Register								0000 0000	uuuu uuuu	rw0,rw0,rw0,rw0,rw0,rw0,rw0
041h	CSFCN0	SKRST	-	HAOTR[5:0]					0.10 0000	u.uu uuuu*	
043h	ADCRH	ADC conversion memory HighByte								xxxx xxxx	uuuu uuuu	r,r,r,r,r,r,r,r
044h	ADCRM	ADC conversion memory Middle Byte								xxxx xxxx	uuuu uuuu	r,r,r,r,r,r,r,r
045h	ADCRL	ADC conversion memory Low Byte								xxxx xxxx	uuuu uuuu	r,r,r,r,r,r,r,r
046h	ADCCN1	ENADC	ENHIGN	ENCHP	-	-	ADGN[2:0]		0000 0000	0000 0000	*****	
047h	ADCCN2	-	-	-	-	VREGN	DCSET[2:0]	 0000 0000*	

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048h	ADCCN3	OSR[3:0]				-	-	-	-	000...0.	000...0.	*****
049h	AINET1	INH[2:0]			INL[2:0]			INIS	-	0000 000.	0000 000.	*****
04Ah	AINET2	-	VRH[1:0]		INX[1:0]		VRL[1:0]		-	.000 000.	.000 000.	*****
04Eh	TB1Flag	-	-	PWM6A	PWM5A	PWM4A	PWM3A	PWM2A	PWM1A	..00 0000	..uu uuuu	..,.,.,.,.,.,.
04Fh	TB1CN0	ENTB1	TB1M[1:0]		TB1RT[1:0]		TB1CL	-	-	0000 0000	uuuu u0uu	*****,"rw1,"*
050h	TB1CN1	PA1IV	PWMA1[2:0]			PA0IV	PWMA0[2:0]			0000 0000	uuuu uuuu	*****
051h	TB1RH	TimerB1 counter Register [15:8]								xxxx xxxx	uuuu uuuu	r,r,r,r,r,r,r,r
052h	TB1RL	TimerB1 counter Register [7:0]								xxxx xxxx	uuuu uuuu	r,r,r,r,r,r,r,r
053h	TB1C0H	TimerB1 counter Condition Register [15:8]								xxxx xxxx	uuuu uuuu	*****
054h	TB1C0L	TimerB1 counter Condition Register [7:0]								xxxx xxxx	uuuu uuuu	*****
055h	TB1C1H	TimerB1 counter Condition Register [15:8]								xxxx xxxx	uuuu uuuu	*****
056h	TB1C1L	TimerB1 counter Condition Register [7:0]								xxxx xxxx	uuuu uuuu	*****
057h	TB1C2H	TimerB1 counter Condition Register [15:8]								xxxx xxxx	uuuu uuuu	*****
058h	TB1C2L	TimerB1 counter Condition Register [7:0]								xxxx xxxx	uuuu uuuu	*****
061h	CFG	Rsv.					I2CRST	ENI2CT	ENI2C 000 uuu	*****
062h	ACT	SLAVE	-	-	I2CER	START	STOP	I2CINT	ACK	0000 0000	uuuu uuuu	*****
063h	STA	MACTF	SACTF	RDBF	RWF	DFF	ACKF	GCF	ARBF	0001 0000	uuuu uuuu	*****
064h	CRG	CRG[7:0]								0000 0000	uuuu uuuu	*****
065h	TOC	I2CTF	DI2C[2:0]			I2CTLT[3:0]			0000 0000	uuuu uuuu	*****	
066h	RDB	RDB[7:1]							RDB[0]	xxxx xxxx	uuuu uuuu	*****
067h	TDB0	TDB0[7:1]							TDB[0]	xxxx xxxx	uuuu uuuu	*****
068h	SID0	SID[7:1],The corresponding address of the 7-bit mode							SIDV[0]	0000 0000	uuuu uuuu	*****
070h	PT1	-	-	-	-	-	-	-	PT10	xx...xx	xx...xx	*****
071h	TRISC1	-	-	-	-	-	-	-	-	0000 0000	uuuu uuuu	*****
072h	PT1DA	-	-	-	-	-	-	-	-	0000 0000	uuuu uuuu	*****
073h	PT1PU	-	-	-	-	-	-	-	-	0000 0000	uuuu uuuu	*****
074h	PT1EG	-	-	FPWMA1	FPWMA0	-	-	EOEG[1:0]	 0000 uuuu	*****
075h	PT2	-	-	-	-	-	-	PT21	PT20xxxx	*****
076h	TRISC2	-	-	-	-	-	-	TC21	TC2000uu	*****
077h	PT2DA	-	-	-	-	-	-	DA21	DA2000uu	*****
078h	PT2PU	-	-	-	-	-	-	PU21	PU2000uu	*****
079h	PT3	-	-	PT35	PT34	PT33	PT32	PT31	PT30	..xx xxxx	..xx xxxx	*****
07Ah	TRISC3	-	-	TC35	TC34	TC33	TC32	TC31	TC30	..00 0000	..uu uuuu	*****
07Bh	PT3DA	-	-	DA35	DA34	DA33	DA32	DA31	DA30	..00 0000	..uu uuuu	*****
07Ch	PT3PU	-	-	PU35	PU34	PU33	PU32	PU31	PU30	..00 0000	..uu uuuu	*****
080h - 0FFh	GPR0	General Purpose Register as 128Byte								uuuu uuuu	uuuu uuuu	*****

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8-Bit RISC-like Mixed Signal Microcontroller



6. 电器特性

6.1. Recommended operating conditions

$T_A = -40^{\circ}\text{C} \sim 85^{\circ}\text{C}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V _{REGVSS}	Supply Voltage	Connect to VSS	0		0	
V _{DD}	Supply Voltage	All digital peripherals and CPU	2.2		3.6	V
		Analog peripherals	2.4		3.6	
V _{SS}	Supply Voltage		0		0	

6.2. Internal RC Oscillator

$T_A = 25^{\circ}\text{C}$, $V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
HAO(2.0MHz)	High Speed Oscillator frequency	ENHAO[0]=1	1.8	2.0	2.2	MHz
HAO(3.8MHz)	High Speed Oscillator frequency		3.42	3.8	4.18	MHz
HAO(7.0MHz)	High Speed Oscillator frequency		6.3	7.0	7.7	MHz
LPO	Low Power Oscillator frequency	V _{DD} supply voltage be enable LPO		14		KHz

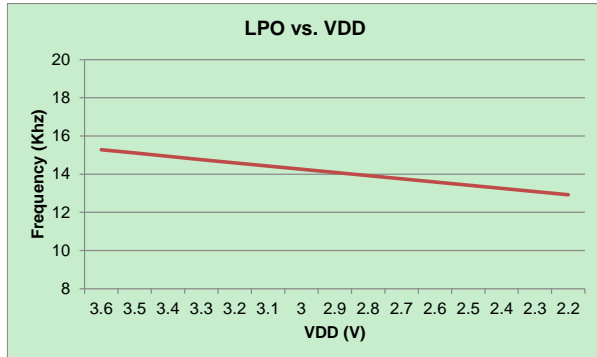


Figure 6.2-1 LPO vs. VDD

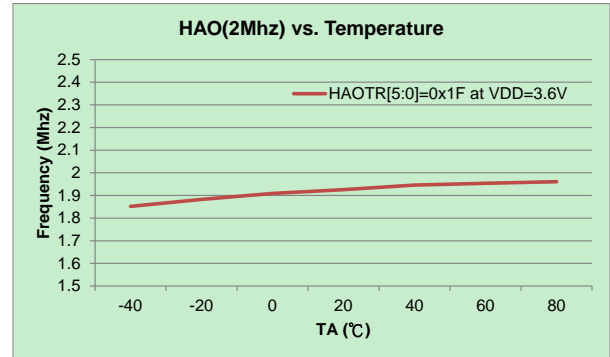


Figure 6.2-3 HAO(2.0MHz) vs. Temperature

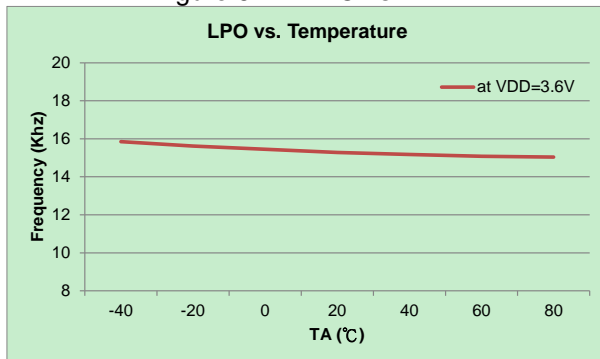


Figure 6.2-2 LPO vs. Temperature

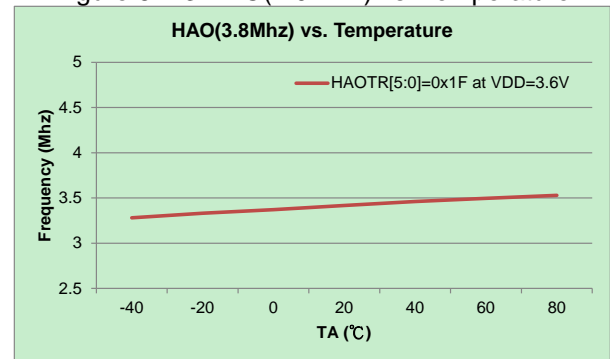


Figure 6.2-4 HAO(3.8MHz) vs. Temperature

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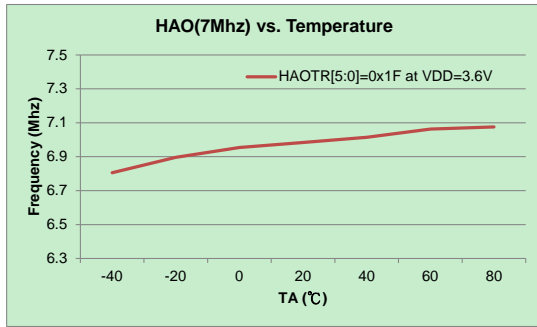


Figure 6.2-5 HAO(7.0MHz) vs. Temperature

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6.3. Supply current into VDD excluding peripherals current

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, \text{OSC_LPO} = 14\text{KHz}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
I _{AM1}	Active mode 1	OSC_CY = off, OSC_HAO = 8MHz, CPU_CK = 8MHz		0.78		mA
I _{AM2}	Active mode 2	OSC_CY = off, OSC_HAO = 4MHz, CPU_CK = 4MHz		0.43		mA
I _{AM3}	Active mode 3	OSC_CY = off, OSC_HAO = 2MHz, CPU_CK = 2MHz		0.24		mA
I _{AM4}	Active mode 4	OSC_CY = off, OSC_HAO = 2MHz, CPU_CK = 1MHz		0.14		mA
I _{LP1}	Low Power 1	OSC_CY = off, OSC_HAO = off, CPU_CK = LPO,		2.5		uA
I _{LP2}	Low Power 2	OSC_CY = off, OSC_HAO = off, CPU_CK = LPO, Idle state		1.2		uA
I _{LP3}	Low Power 3	OSC_CY = off, OSC_HAO = off, CPU_CK = off, Sleep state		0.6		uA

OSC_HAO: Internal High Accuracy Oscillator frequency.

CPU_CK: CPU core work frequency.

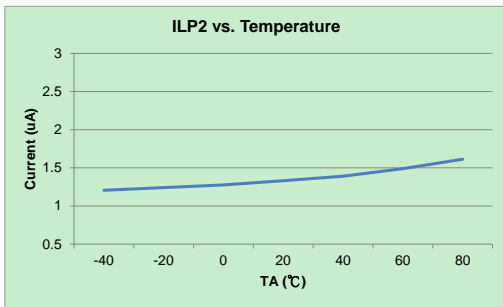


Figure 6.3-1 ILP2 vs. Temperature

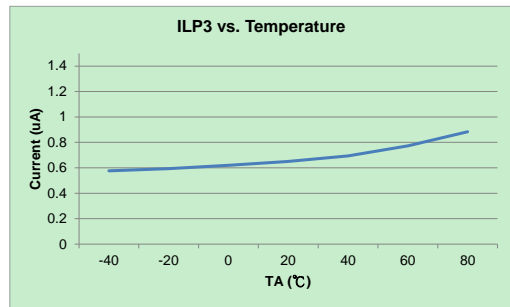


Figure 6.3-2 ILP3 vs. Temperature

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6.4. Port1~3

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
Input voltage and Schmitt trigger and leakage current and timing						
V_{IH}	High-Level input voltage		$0.7 \cdot V_{DD}$		V_{DD}	V
V_{IL}	Low-Level input voltage		V_{SS}		$0.3 \cdot V_{DD}$	
V_{hys}	Input Voltage hysteresis($V_{IH} - V_{IL}$)			0.8		V
I_{LKG}	Leakage Current				0.1	μA
R_{PU}	Port pull high resistance			180		$\text{k}\Omega$
Output voltage and current and frequency						
V_{OH}	High-level output voltage	$I_{OH}=10\text{mA}$	$V_{DD} - 0.3$			V
V_{OL}	Low-level output voltage	$I_{OL}=-10\text{mA}$			$V_{SS} + 0.3$	

6.5. Rest(Brownout)

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
BOR	Pulse length needed to accepted reset internally, t_{d-LVR}		2			μs
	V_{DD} Start Voltage to accepted reset internally (L→H), V_{LVR}		1.6	1.85	2.1	V
	Hysteresis, $V_{HYS-LVR}$		70			mV

BOR: Brownout Reset
 LVR: Low Voltage Reset of BOR

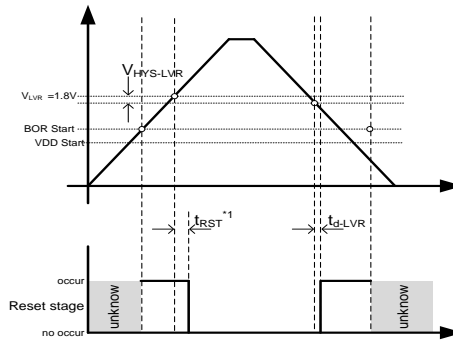


Figure6.5-1 BOR reset diagram

*1 rRST: Please see BOR Introduce of HY10Pxx series User’s Guide (UG-HY10S00-Vxx).

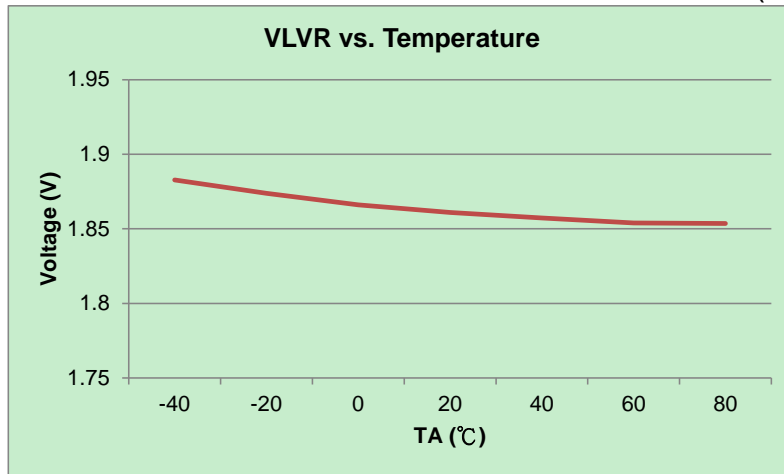


Figure6.5-3 LVR vs. Temperature

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6.6. Power System

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	Unit
VDDA	VDDA operation current, I_{VDDA}	$I_L = 0\text{mA}$	ENLDO[1:0]=11b		13		μA
	Select VDDA output voltage	$I_L = 0.1\text{mA}$, $V_{DD} \cong V_{DDA} + 0.2\text{V}$	VDDAX[1:0]=01b		3.0		V
			VDDAX[1:0]=10b		2.7		
			VDDAX[1:0]=11b		2.4		
	Dropout voltage	$I_L = 10\text{mA}$	VDDAX[1:0]=01b			150	
VDDAX[1:0]=10b					165		
VDDAX[1:0]=11b					180		
Temperature drift	ENLDO[1:0]=11b,	$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$		50		ppm/ $^\circ\text{C}$	
V_{DD} Voltage drift	$I_L = 0.1\text{mA}$	$V_{DD} = 2.5\text{V} \sim 3.6\text{V}$		± 0.2		%/V	
ACM	Analog Common Mode Voltage, V_{ACM}	ENADC[0]=1	$I_L = 0\mu\text{A}$		1.2		V
	Analog Common Mode Voltage with Load			$I_L = \pm 200\mu\text{A}$	0.98	1.02	V_{ACM}
	Temperature drift	ENADC[0]=1,	$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$		50		ppm/ $^\circ\text{C}$
	VDDA Voltage drift	$I_L = 10\mu\text{A}$			100		$\mu\text{V}/\text{V}$

VDDA: Adjust Voltage Regulator
ACM: Analog Common Mode Voltage

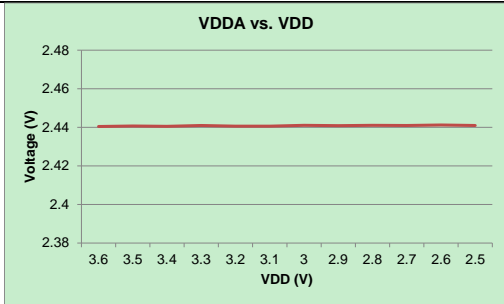


Figure 6.6-1 VDDA vs. VDD

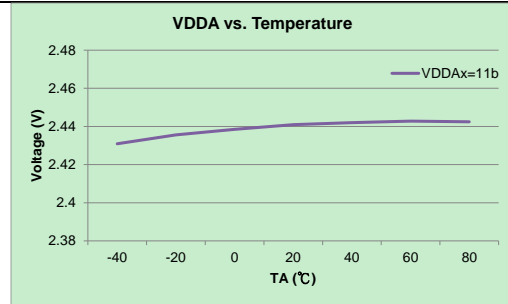


Figure 6.6-2 VDDA vs. Temperature

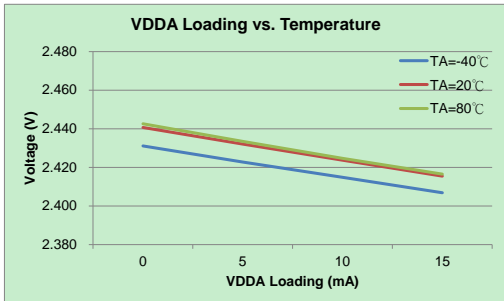


Figure 6.6-3 VDDA Loading vs. Temperature

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6.7. SD18, Power Supply and recommended operating conditions

$T_A = 25^\circ\text{C}$, $V_{DD} = 3.0\text{V}$, $V_{DDA} = 2.4\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	Unit
V_{SD18}	Supply Voltage at VDDA	ENVDDA[0]=0		2.4		3.6	V
f_{SD18}	Modulator sample frequency, ADC_CK			25	250	300	KHz
	Over Sample Ratio, OSR			128 ^{*1}		32768	
I_{SD18}	Operation supply current without PGA	ENADC[0]=1	GAIN =4, ADC_CK=250KHz		120		uA
<p>*1, OSR=128, setting by ADCCN3[OSR[3]] bit. OSR[3:0]=1010, OSR=128; OSR[3:0]=0xxx, OSR=256 ~ 32768</p>							

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6.7.1. SD18, performance($f_{SD18}=250\text{KHz}$)

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA}=3.0\text{V}, V_{VR}=1.0\text{V}, \text{GAIN}=1$ without PGA, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
INL	Integral Nonlinearity(INL)	$V_{DDA}=2.4\text{V}, V_{VR}=1.0\text{V}, \Delta\text{SI}=\pm 450\text{mV}$		± 0.003	± 0.01	%FSR
	No Missing Codes ³	$\text{ADC_CK}=250\text{KHz}, \text{OSR}[2:0]=010\text{b}$	23			Bits
G_{SD18}	Temperature drift Gain 1~x16		$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$	5		ppm/ $^\circ\text{C}$
E_{OS}	Offset error of Full Scale Rang input voltage range with Chopper without PGA	$\Delta\text{AI}=0\text{V}$ $\Delta\text{VR}=0.9\text{V}$ $\text{DCSET}[2:0]=<000>$ * ΔAI is external short	Gain=2		1	%FSR
	Offset temperature drift with chopper without PGA		GAIN=1		2	uV/ $^\circ\text{C}$
			GAIN=2		1	
			GAIN=4		0.5	
CM_{SD18}	Common-mode rejection	$V_{CM}=0.7\text{V to } 1.7\text{V}, V_{VR}=1.0\text{V}, \text{without PGA}$	$V_{SI}=0\text{V}, \text{GAIN}=1$		90	dB
		$V_{CM}=0.7\text{V to } 1.7\text{V}, V_{VR}=1.0\text{V},$	$V_{SI}=0\text{V}, \text{GAIN}=16$		75	
PSRR	DC power supply rejection	$V_{DDA}=3.0\text{V}, \Delta V_{DDA}=\pm 100\text{mV}, V_{VR}=1.0\text{V}, V_{SI}=V_{SL}=1.2\text{V},$	GAIN=1 PGA=off		75	dB
			GAIN=16			

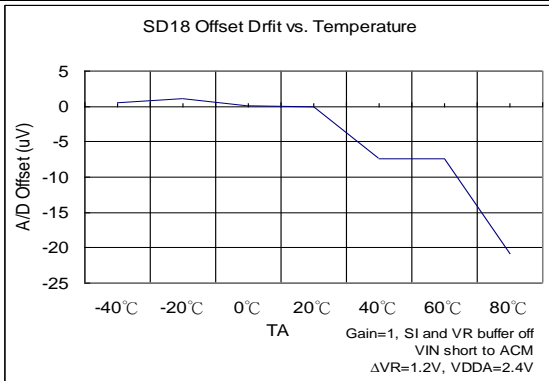


Figure6.7-1(a) SD18 Offset Temperature drift

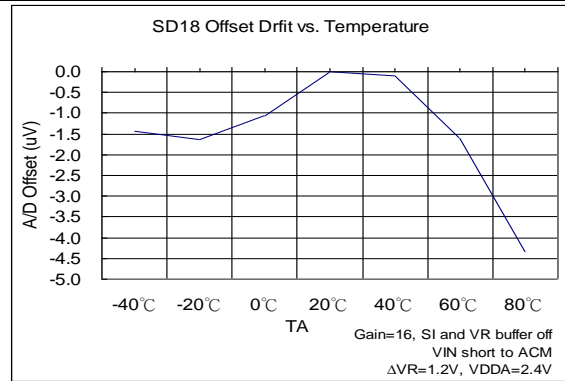


Figure6.7-1(b) SD18 Offset Temperature drift

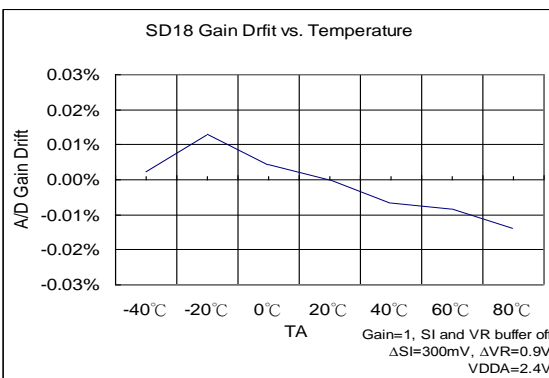


Figure6.7-2(a) SD18 Gain drift with Temperature

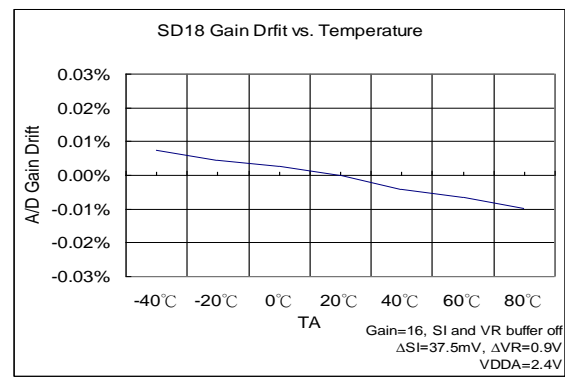


Figure6.7-2(b) SD18 Gain drift with Temperature

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6.7.2. SD18 Noise Performance

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA} = 2.4\text{V}$, unless otherwise noted

HY10P40 针对 SD18 提供了重要的输入噪声规格。Table6.7-4(a), Table6.7-4(b) 列出典型的噪声规格表与 Gain, Output rate, 及单端最大输入电压等关系。测试条件设定在外部输入讯号短路, ADC 参考电压源为使用外部 VDDA 及外部 VSS 当参考电压源网络, 等效参考电压为 1.2V, 取样 1024 笔数据。

ENOB(RMS) with OSR/GAIN at A/D Clock=250Khz, VDDA=2.4V, VREF=1.2V														
Max. Vin(mV) =0.9*VREF ⁽¹⁾	OSR					128	256	512	1024	2048	4096	8192	16384	32768
	Output rate(HZ)					1953	977	488	244	122	61	31	15	8
	Gain	=	PGA	x	ADGN									
±2160	0.5	=	1	x	0.5	14.39	16.14	16.96	17.27	17.44	17.66	18.08	19.52	19.73
±1080	1	=	1	x	1	14.38	16.04	16.85	17.18	17.42	17.76	18.89	19.85	20.22
±540	2	=	1	x	2	14.4	16.01	16.79	17.03	17.31	17.53	18.02	19.55	20.1
±270	4	=	1	x	4	14.42	15.91	16.57	16.94	17.14	17.39	17.69	18.61	19.81
±135	8	=	1	x	8	14.34	15.66	16.24	16.64	17.01	17.4	17.99	19.05	19.52
±68	16	=	1	x	16	14.22	15.3	15.88	16.34	16.85	17.41	17.85	18.53	19.01

(1) Max. Vin (mV) is the max. input voltage of single end to ground (VSS).

Table6.7-4(a) SD18 ENOB Table

RMS Noise(uV) with OSR/GAIN at A/D Clock=250Khz, VDDA=2.4V, VREF=1.2V														
Max. Vin(mV) =0.9*VREF	OSR					128	256	512	1024	2048	4096	8192	16384	32768
	Output rate(HZ)					1953	977	488	244	122	61	31	15	8
	Gain	=	PGA	x	ADGN									
±2160	0.5	=	1	x	0.5	226.11	67.48	38.23	30.84	27.40	23.43	17.59	6.46	5.58
±1080	1	=	1	x	1	113.68	36.14	20.60	16.42	13.86	10.94	5.00	2.58	1.99
±540	2	=	1	x	2	56.28	18.46	10.69	9.06	7.49	6.40	4.58	1.58	1.09
±270	4	=	1	x	4	27.72	9.85	6.25	4.82	4.20	3.53	2.88	1.52	0.66
±135	8	=	1	x	8	14.67	5.85	3.92	2.98	2.30	1.75	1.17	0.56	0.40
±68	16	=	1	x	16	7.95	3.76	2.52	1.83	1.29	0.87	0.64	0.40	0.29

Table6.7-4(b) SD18 RMS Noise Table

The RMS noise are referred to the input. The Effective Number of Bits (ENOB(RMS Bit)) is defined as:

$$\text{ENOB(RMS)} = \frac{\ln\left(\frac{\text{FSR}}{\text{RMS Noise}}\right)}{\ln(2)}$$

$$\text{RMS Noise} = \frac{\left(2 \times \text{VREF} \times \sqrt{\sum_{k=1}^{1024} (\text{ADO}[k] - \text{Average})^2}\right)}{2^{23}}$$

Where FSR (Full - Scale Range) = $2 \times \text{VREF}/\text{Gain}$.

$$\text{Average} = \frac{\sum_{k=1}^{1024} (\text{ADO}[k])}{1024}$$

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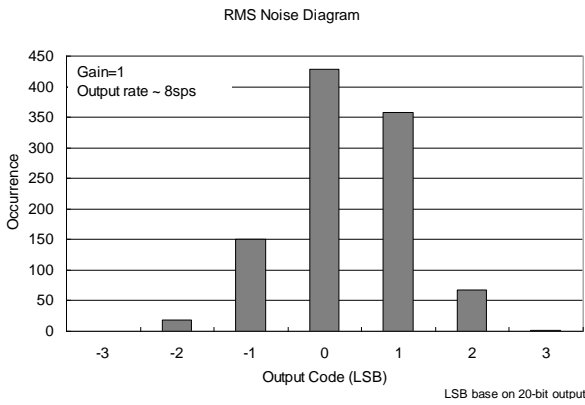


Figure6.7-4(a) RMS Noise Diagram

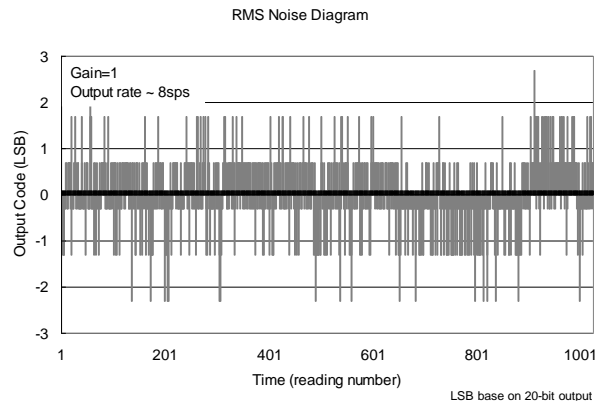


Figure6.7-4(b) Output Code Diagram

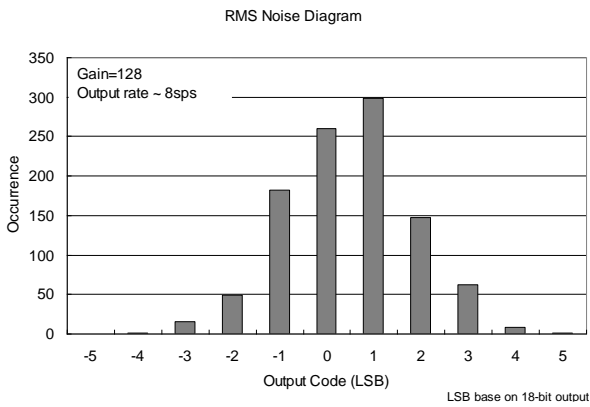


Figure6.7-4(c) RMS Noise Diagram (Gain=16)

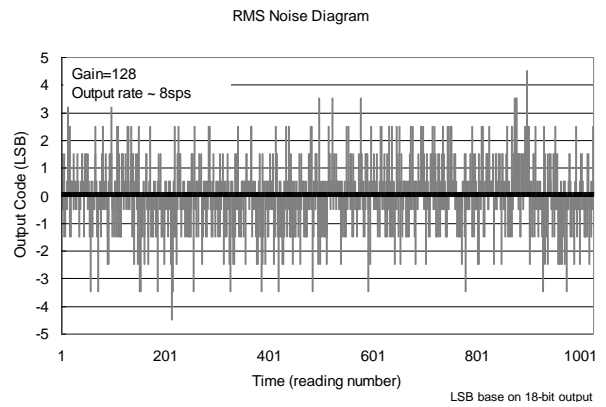


Figure6.7-4(d) Output Code Diagram (Gain=16)

6.8. Build-In EPROM(BIE)

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V_{BIE}	Supply Voltage			6.0	6.5	V
I_{BIE}	Operation supply current			5		mA
V_{SS}	Supply Voltage			0		V

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7. 订货信息

下单品名 ¹	封装型式	引脚数	封装型式		程序代码 编号 ²	出货 包装形式	个装 数量	材料 组成	MSL ³
			描述方式						
HY10P40-D000	Die	-	D	000	000	-	250	Green ⁴	-
HY10P40-S008	SOP	8	S	008	000	Tube	100	Green ⁴	MSL-3
HY10P40-S008	SOP	8	S	008	000	Tape & Reel	2500	Green ⁴	MSL-3
HY10P40-M010	MSOP	10	M	010	000	Tube	80	Green ⁴	MSL-3
HY10P40-M010	MSOP	10	M	010	000	Tape & Reel	3000	Green ⁴	MSL-3
HY10P40-E016	SSOP	16	E	016	000	Tube	100	Green ⁴	MSL-3
HY10P40-E016	SSOP	16	E	016	000	Tape & Reel	2500	Green ⁴	MSL-3

¹ 产品名称 - 封装型式描述方式 - 程序代码编号 (空白片 / 标准品 / 代客烧录码)

例如：您的代客烧录服务申请的程序代码编号为 007，且需要的产品是裸片出货。

则下单品名为 HY10P40-D000-007

例如：您的需求是不带程序代码的空白片且需要的产品是裸片出货。则下单品名为 HY10P40-D000

例如：您的需求是不带程序代码的空白片且需要的产品是封装片 SSOP16 出货，则下单品名为 HY10P40-E016，且需以 Tape & Reel 出货，则除下单品名外，请特别注明出货包装形式为 Tape & Reel

例如：您的代客烧录服务申请的程序代码编号为 008，而需求的产品是封装片 SOP8 出货，则下单品名为 HY10P40-S008-008，且需以 Tape & Reel 出货，则除下单品名外，请特别注明出货包装形式为 Tape & Reel

例如：您的代客烧录服务申请的程序代码编号为 009，而需求的产品是封装片 MSOP10 出货，则下单品名为 HY10P40-M010-009，且需以 Tube 出货，则除下单品名外，请特别注明出货包装形式为 Tube

² 程序代码编号

“001”~“999” 为标准品或代客烧录申请的程序代码编号，而空白芯片不带此码。

³ MSL:

湿度敏感性等级系依据 IPC/JEDEC J-STD-020 的规范加以试验分级，并参考 IPC/JEDEC J-STD-033 的标准处理、包装、运输与使用。

⁴ Green (RoHS & no Cl/Br)

HYCON 产品皆为 Green Product，符合 RoHS 指令，REACH 高关注物质(SVHC) 以及无卤素相关规定。

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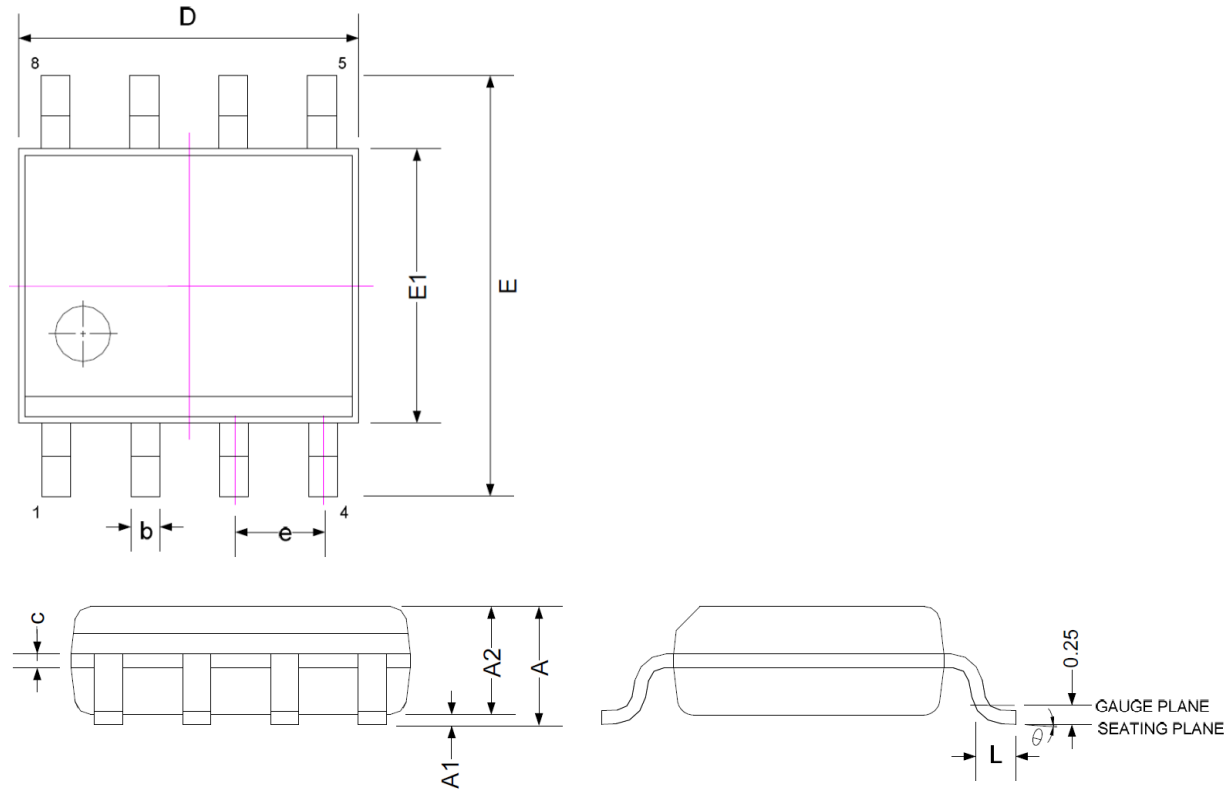
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8. 封装型式信息

8.1. SOP8(S008)

8.1.1. Package Dimensions SOP8(150mil)



SYMBOLS	MIN	NOM	MAX
A	-	-	1.75
A1	0.10	-	0.25
A2	1.25	-	-
b	0.31	-	0.51
c	0.10	-	0.25
D	4.90 BSC		
E1	3.90 BSC		
E	6.00 BSC		
L	0.40	-	1.27
e	1.27 BSC		
θ°	0	-	8

Note:

1. All dimensions refer to JEDEC OUTLINE MS-012.
2. Do not include Mold Flash or Protrusions.
3. Unit: mm.

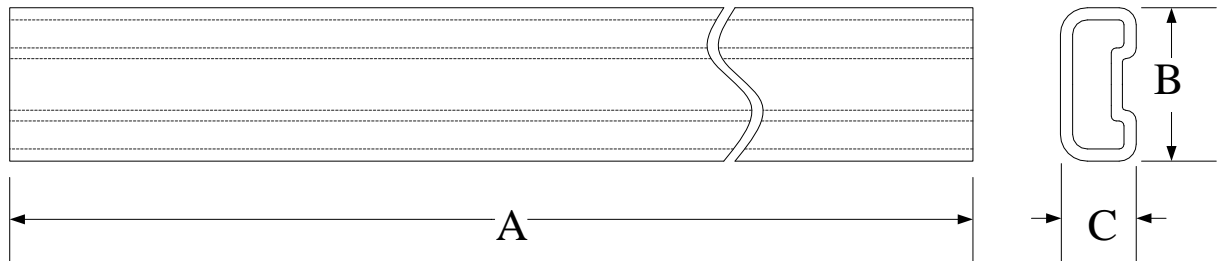
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8.1.2. Tube Dimensions SOP8(150mil)

Unit : mm



Type 1:

SYMBOLS	A	B	C
Spec.	521.0±1.0	7.747±0.15	3.810±0.15

Type 2:

SYMBOLS	A	B	C
Spec.	521.0±1.0	7.874 REF.	3.810 REF.

HY10P40

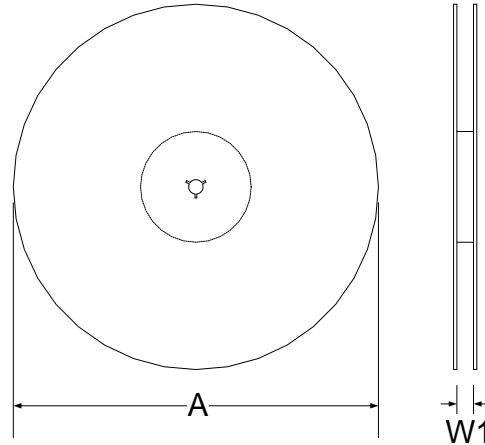
Embedded 24-Bit $\Sigma \Delta$ ADC

8-Bit RISC-like Mixed Signal Microcontroller

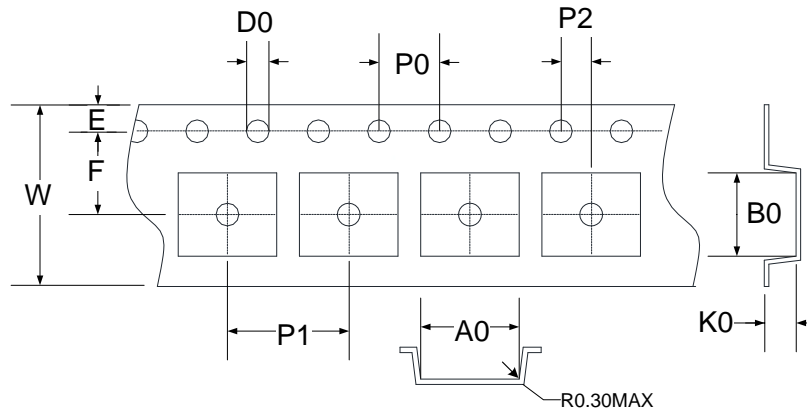
8.1.3. Tape & Reel Information

8.1.3.1. Reel Dimensions-Type1

Unit : mm



8.1.3.2. Carrier Tape Dimensions

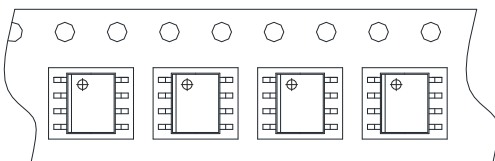


SYMBOLS	Reel Dimensions		Carrier Tape Dimensions									
	A	W1	A0	B0	K0	P0	P1	P2	E	F	D0	W
Spec.	330	12.5	6.90	5.40	2.00	4.00	8.00	2.00	1.75	5.50	1.50	12.00
Tolerance	+6/-3	+1.5/-0	±0.10	±0.10	±0.10	±0.10	±0.10	±0.10	±0.05	±0.10	±0.05	+0.1/-0 ±0.30

Note: 10 Sprocket hole pitch cumulative tolerance is ± 0.20 mm.

Unit : mm

8.1.3.3. Pin1 direction



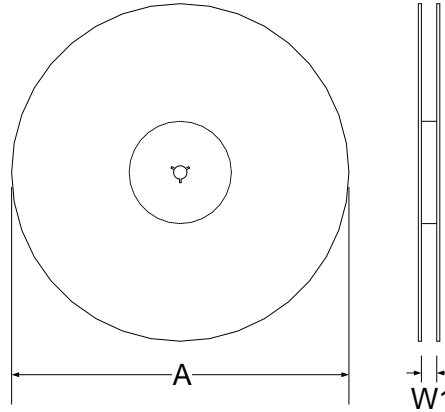
HY10P40

Embedded 24-Bit $\Sigma \Delta$ ADC
8-Bit RISC-like Mixed Signal Microcontroller

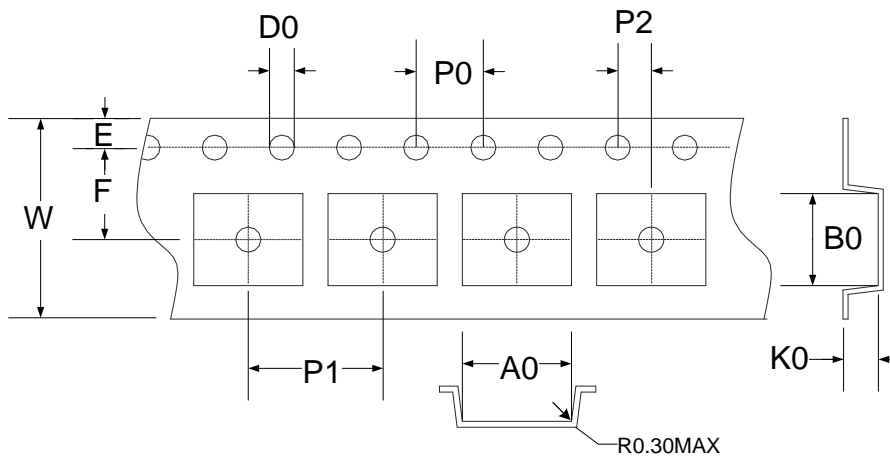


8.1.3.4. Reel Dimensions –Type2

Unit : mm



8.1.3.5. Carrier Tape Dimensions

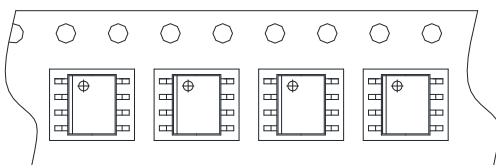


SYMBOLS	Reel Dimensions		Carrier Tape Dimensions										
	A	W1	A0	B0	K0	P0	P1	P2	E	F	D0	W	
Spec.	330	12.5	6.50	5.20	2.10	4.00	8.00	2.00	1.75	5.50	1.50	12.00	
Tolerance	+6/-3	+1.5/-0	±0.10	±0.10	±0.10	±0.10	±0.10	±0.10	±0.05	±0.10	±0.05	+0.1/-0	±0.30

Note: 10 Sprocket hole pitch cumulative tolerance is ± 0.20 mm.

Unit : mm

8.1.3.6. Pin1 direction



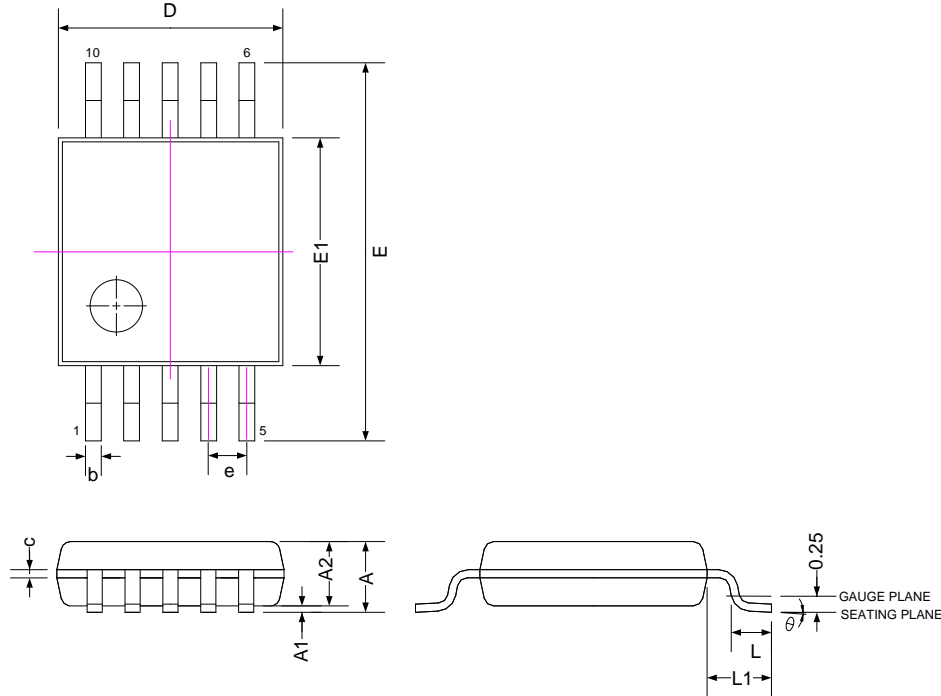
HY10P40

Embedded 24-Bit $\Sigma \Delta$ ADC

8-Bit RISC-like Mixed Signal Microcontroller

8.2. MSOP10(M010)

8.2.1. Package Dimensions



SYMBOLS	MIN	NOM	MAX
A	-	-	1.10
A1	0.00	0.10	0.15
A2	0.75	0.85	0.95
b	0.17	0.20	0.27
c	0.08	0.15	0.23
D	3.00 BASIC		
E1	3.00 BASIC		
E	4.90 BASIC		
L	0.40	0.60	0.80
L1	0.95 REF		
e	0.50 BASIC		
θ°	0	-	8

Note:

1. All dimensions refer to JEDEC OUTLINE MO -187.
2. Do not include Mold Flash or Protrusions.
3. Unit: mm.

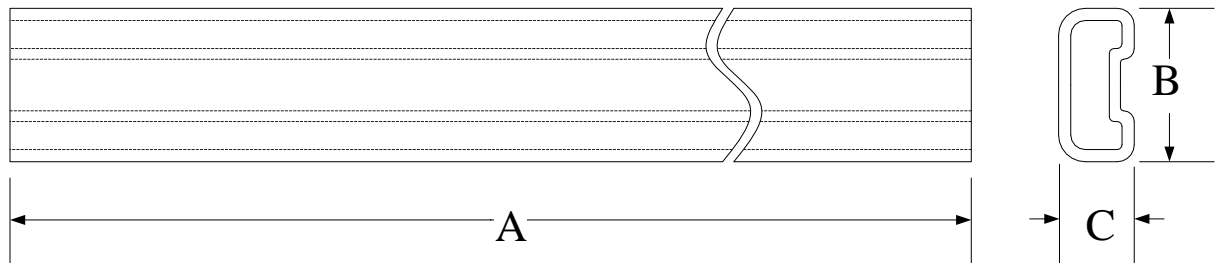
HY10P40

Embedded 24-Bit $\Sigma \Delta$ ADC

8-Bit RISC-like Mixed Signal Microcontroller

8.2.2. Tube Dimensions MSOP10(M010)

Unit : mm



SYMBOLS	A	B	C
Spec.	270.0±1.3	6.55±0.1	3.0±0.1

HY10P40

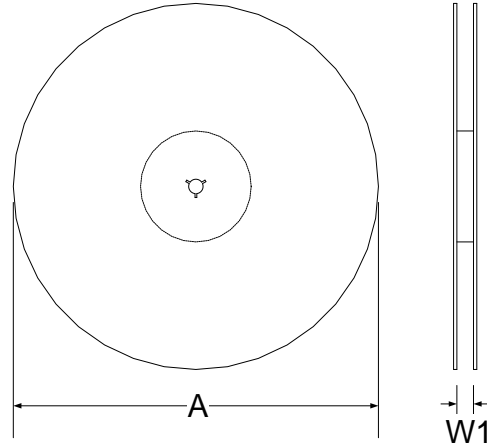
Embedded 24-Bit $\Sigma \Delta$ ADC

8-Bit RISC-like Mixed Signal Microcontroller

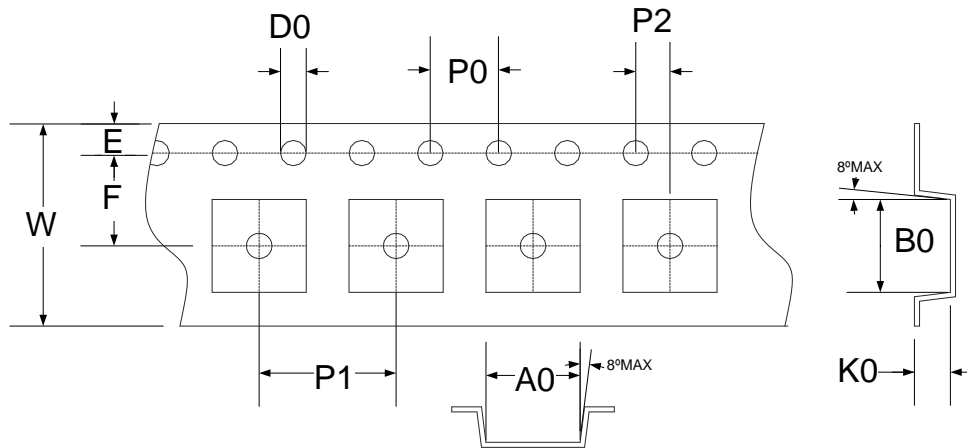
8.2.3. Tape & Reel Information

8.2.3.1. Reel Dimensions - Type1

Unit : mm



8.2.3.2. Carrier Tape Dimensions

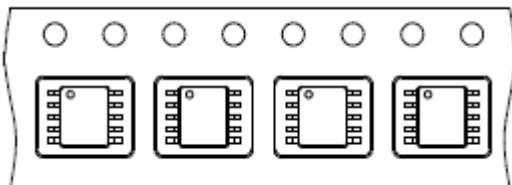


SYMBOLS	Reel Dimensions		Carrier Tape Dimensions										
	A	W1	A0	B0	K0	P0	P1	P2	E	F	D0	W	
Spec.	330	12.5	5.30	3.40	1.40	4.00	8.00	2.00	1.75	5.50	1.50	12.00	
Tolerance	±2.00	±1.50	±0.10	±0.10	±0.10	±0.10	±0.10	±0.10	±0.05	±0.10	±0.05	+0.1/-0	±0.20

Note: 10 Sprocket hole pitch cumulative tolerance is ±0.20mm.

Unit : mm

8.2.3.3. Pin1 direction



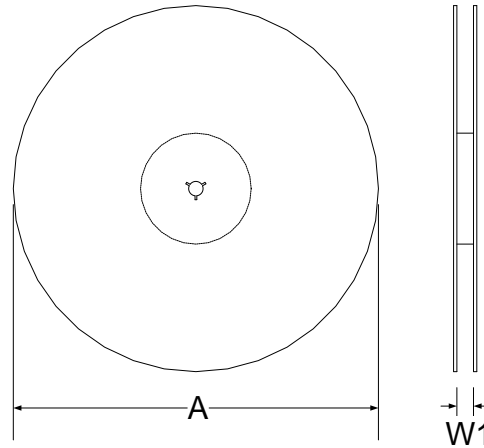
HY10P40

Embedded 24-Bit $\Sigma \Delta$ ADC
 8-Bit RISC-like Mixed Signal Microcontroller

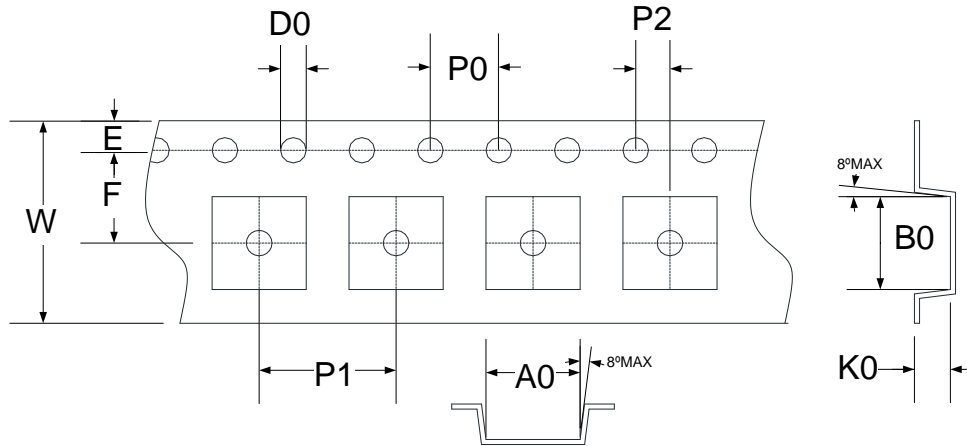


8.2.3.4. Reel Dimensions - Type2

Unit : mm



8.2.3.5. Carrier Tape Dimensions

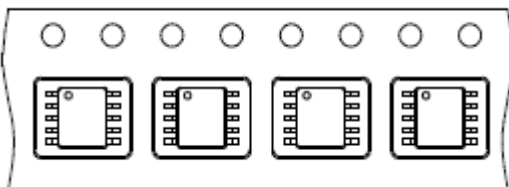


SYMBOLS	Reel Dimensions		Carrier Tape Dimensions										
	A	W1	A0	B0	K0	P0	P1	P2	E	F	D0	W	
Spec.	330	12.5	5.20	3.30	1.20	4.00	8.00	2.00	1.75	5.50	1.50	12.00	
Tolerance	±2.00	±1.50	±0.10	±0.10	±0.10	±0.10	±0.10	±0.10	±0.05	±0.10	±0.05	+0.1/-0	±0.30

Note: 10 Sprocket hole pitch cumulative tolerance is ±0.20mm.

Unit : mm

8.2.3.6. Pin1 direction



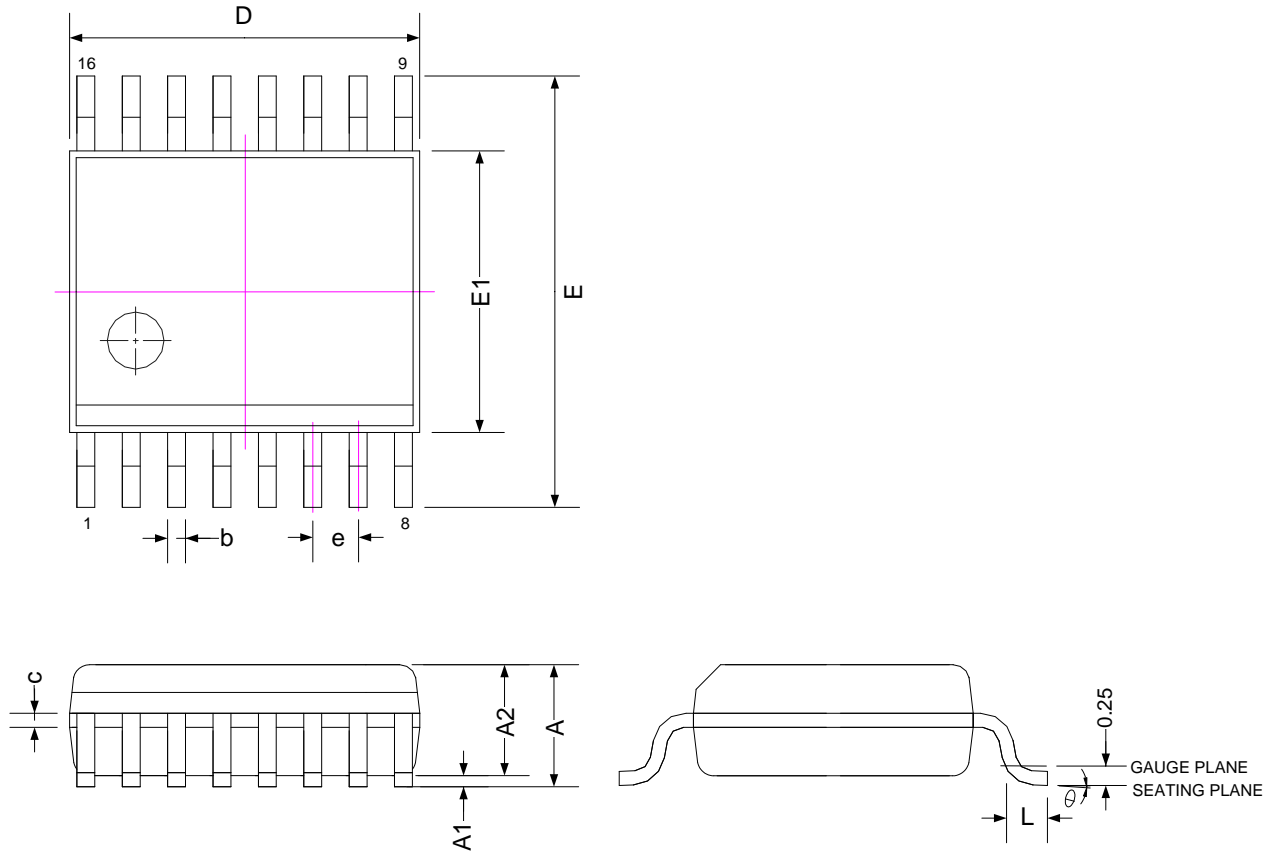
HY10P40

Embedded 24-Bit $\Sigma \Delta$ ADC

8-Bit RISC-like Mixed Signal Microcontroller

8.3. SSOP16(E016)

8.3.1. Package Dimensions



SYMBOLS	MIN	NOM	MAX
A	-	-	1.75
A1	0.10	0.15	0.25
A2	-	-	1.50
b	0.20	-	0.30
c	0.18	-	0.25
D	4.80	4.90	5.00
E1	3.81	3.91	3.99
E	5.79	5.99	6.20
L	0.41	-	1.27
e	0.635 BASIC		
θ°	0	-	8

Note:

1. All dimensions refer to JEDEC OUTLINE MO-137.
2. Do not include Mold Flash or Protrusions.
3. Unit : mm.

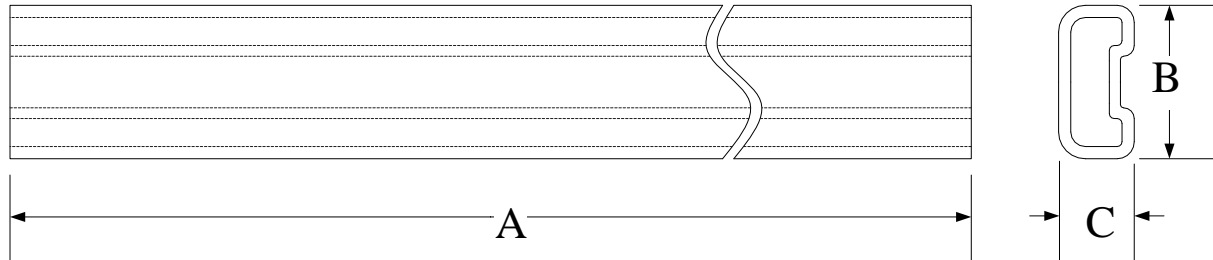
HY10P40

Embedded 24-Bit $\Sigma \Delta$ ADC

8-Bit RISC-like Mixed Signal Microcontroller

8.3.2. Tube Dimensions SSOP16(E016)

Unit : mm



Type 1:

SYMBOLS	A	B	C
Spec.	521.0±1.0	7.747±0.15	3.810±0.15

Type 2:

SYMBOLS	A	B	C
Spec.	521.0±1.0	7.874 REF.	3.810 REF.

HY10P40

Embedded 24-Bit $\Sigma \Delta$ ADC

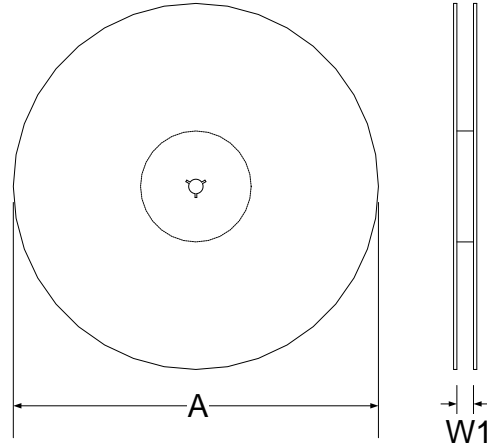
8-Bit RISC-like Mixed Signal Microcontroller



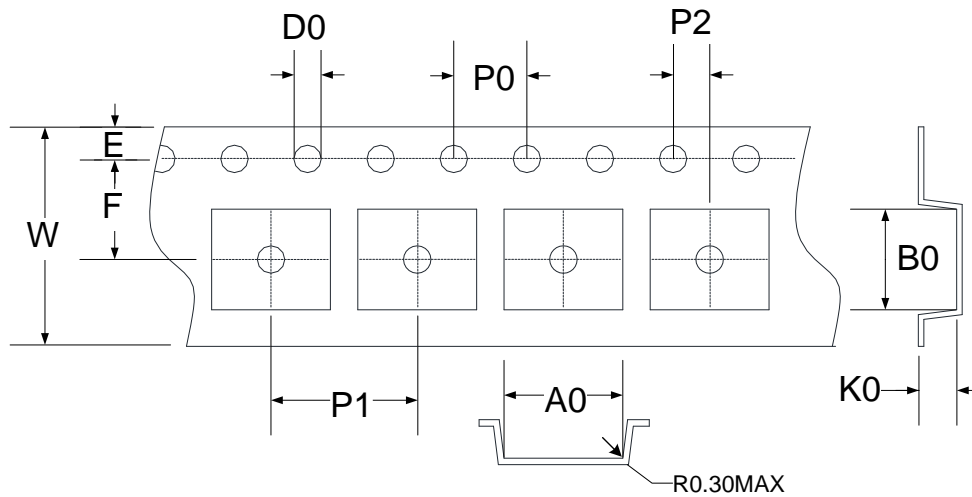
8.3.3. Tape & Reel Information

8.3.3.1. Reel Dimensions - Type1

Unit : mm



8.3.3.2. Carrier Tape Dimensions

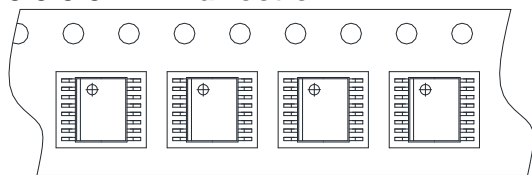


SYMBOLS	Reel Dimensions		Carrier Tape Dimensions									
	A	W1	A0	B0	K0	P0	P1	P2	E	F	D0	W
Spec.	330	12.5	6.90	5.40	2.00	4.00	8.00	2.00	1.75	5.50	1.50	12.00
Tolerance	+6/-3	+1.5/-0	±0.10	±0.10	±0.10	±0.10	±0.10	±0.05	±0.10	±0.05	+0.1/-0	±0.30

Note: 10 Sprocket hole pitch cumulative tolerance is ± 0.20 mm.

Unit : mm

8.3.3.3. Pin1 direction



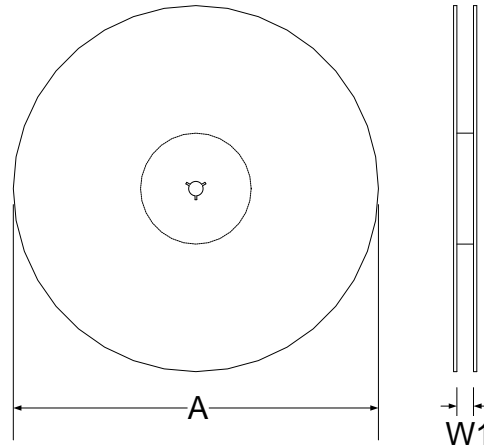
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Embedded 24-Bit $\Sigma \Delta$ ADC
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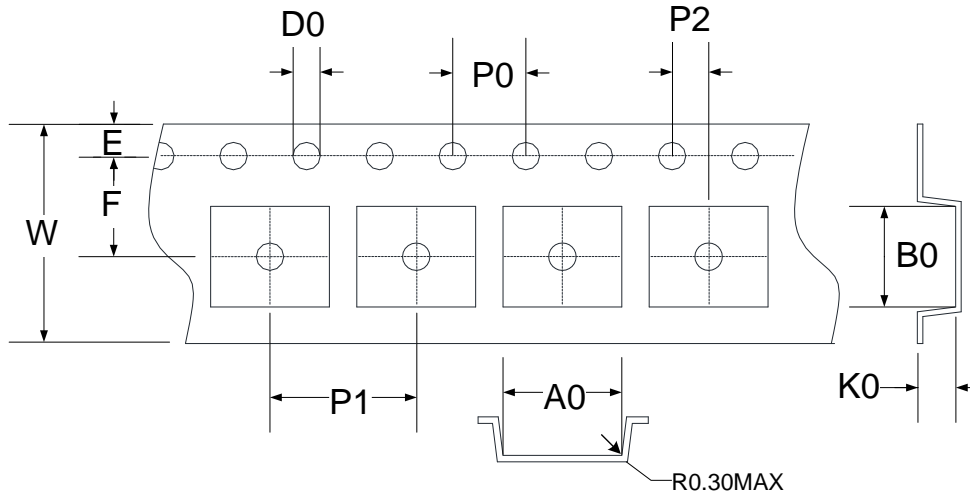


8.3.3.4. Reel Dimensions - Type2

Unit : mm



8.3.3.5. Carrier Tape Dimensions

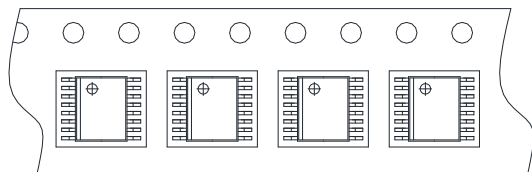


SYMBOLS	Reel Dimensions		Carrier Tape Dimensions										
	A	W1	A0	B0	K0	P0	P1	P2	E	F	D0	W	
Spec.	330	12.5	6.50	5.20	2.10	4.00	8.00	2.00	1.75	5.50	1.50	12.00	
Tolerance	+6/-3	+1.5/-0	±0.10	±0.10	±0.10	±0.10	±0.10	±0.10	±0.05	±0.10	±0.05	+0.1/-0	±0.30

Note: 10 Sprocket hole pitch cumulative tolerance is ± 0.20 mm.

Unit : mm

8.3.3.6. Pin1 direction



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Embedded 24-Bit $\Sigma \Delta$ ADC

8-Bit RISC-like Mixed Signal Microcontroller



9. 修订记录

以下描述本文件差异较大的地方，而标点符号与字形的改变不在此描述范围。

文件版次	页次	日期	摘要
V09	All	2023/08/09	初版发行