



HY11P13

Datasheet

**8-Bit RISC-like Mixed Signal Microcontroller
Embedded 4x20 LCD Driver
Low Noise Amplifier
18-Bit $\Sigma\Delta$ ADC**

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1. Features

- 8-bit RISC, 66 instructions included.
- Operating voltage range: 2.2V to 3.6V, operation temperature range: -40°C~85°C.
- External Crystal Oscillator and Internal High Precision RC Oscillator, 6 CPU clock rates enable users to have the most power-saving plan.
 - Active Mode 300uA@2MHz
 - Standby Mode 3uA@32KHz
 - Sleep Mode 1uA
- 4K Word OTP (One Time Programmable) Type program memory, 256 Byte Data Memory.
- Brownout detector and Watch dog Timer, prevents CPU from Crash.
- 18-bit fully differential input Sigma-Delta Analog-to-Digital Converter (A/D)
 - Build-in PGA (Programmable Gain Amplifier) 1/4x · 1/2x · 1x ... 128x, 10 input signal gain selection.
 - Build-in Input zero adjustment can increase measurement range according to different application.
 - Built-in high impedance input buffer (Not suitable for 32x or upwards input gain).
 - Built-in absolute temperature sensor
- Ultra-Low Input Noise (<1uVpp) OP provides high output impedance, small signal amplification and low current voltage transformation.
- 1.0 V internal analog circuit common ground that equips with Push-Pull drive ability to provide sensor driving voltage.
- LVD low voltage detection function has 14 steps of voltage detection configuration and external input voltage detection function.
- VDDA can select 4 different output voltage that equips with 10mA low dropout regulator function.
- 4x20 LCD driver
 - Static · 1/2 · 1/3 · 1/4 Duty and 1/3 Bias programmable option.
 - Built-in Charge Pump regulated circuit, providing 4 LCD Bias voltage.
- 8-bit Timer A
- 16-bit Timer B module has Capture/ Compare function.
- 8-bit Timer C module can generate PWM/PFD waveform.
- Serial communication SPI module
- Support 6 stack level

Function List

| Model No. | VDD | System Clock | Program Memory (word) | SRAM (byte) | ADC ENOB (bit x ch) | Sample Rate (sps) | TPS | OPAMP (type x ch.) | I/O | LCD (com x seg) | Package |
|-----------|-----------|--------------|-----------------------|-------------|---------------------|-------------------|------------------|--------------------|-------------|------------------|---------|
| | | | | | | | RTC | | | Timer (bit x ch) | |
| | | | | | | | Serial Interface | | | PWM (bit x ch) | |
| HY11P13 | 2.2V~3.6V | 28KHz~2MHz | 4K | 256 | 20-bit x 8 | 8~977 | Yes | LAN x1 | 4x1 + 10xIO | 4 x 20 | LQFP64 |
| | | | | | | | Y | | | 8-bit x 2 | |
| | | | | | | | SPI | | | 16-bit x 1 | |
| | | | | | | | | | | 8-bit x 1 | |

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2. Pin Definition

2.1. 64PIN Diagram LQFP64

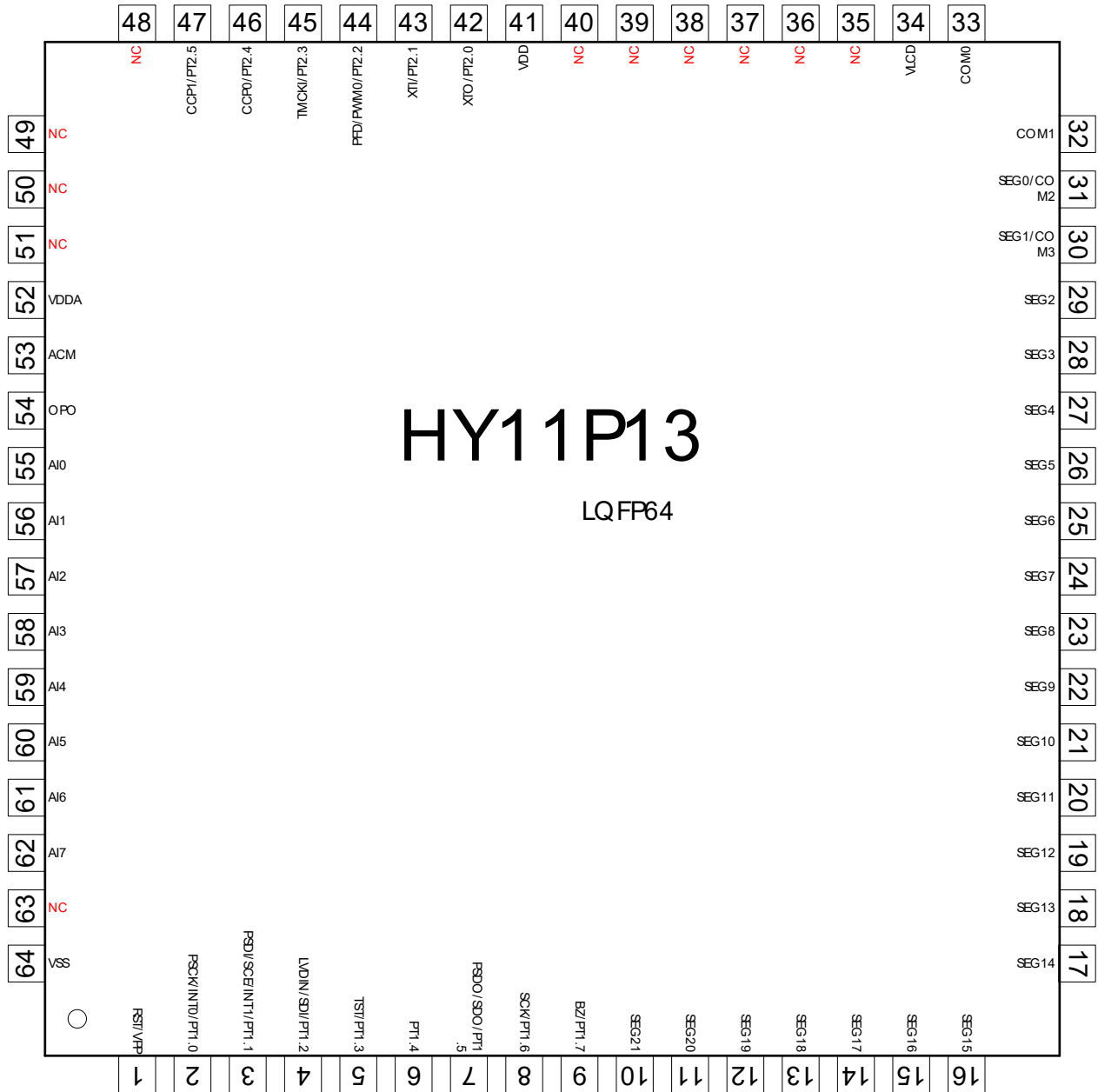


Figure 2-1 HY11P13 LQFP64 Pin Diagram

Note 1 : VPP and RST use the same pin. Input voltage cannot exceed 5.8V when not programming EPROM.

Note 2 : TST and PT1.3 use the same pin. Input voltage cannot exceed Vdd+0.3V while operating.

Note 3 : If PT1.3 is not configured as external button pin, the anti-interference ability will be enhanced.

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2.2. LQFP64 Pinout I/O Description

"I/O" input/output, "I" input, "O" output, "S" Smith Trigger, "C" CMOS features compatible input/output, "P" power supply, "A" analog channel

| NO. | Pin Name | Pin Characteristic | | Description |
|-----|----------|--------------------|--------|-------------------------------------|
| | | Pin | Buffer | |
| | | Type | Type | |
| 1 | RST | I | S | Reset IC |
| | VPP | P | P | EPROM programming voltage input |
| 2 | PT1.0 | I | S | Digital input |
| | INT0 | I | S | Interrupt input INT0 |
| | PSCK | I | S | OTP programming interface SCK |
| 3 | PT1.1 | I | S | Digital input |
| | INT1 | I | S | Interrupt input INT 1 |
| | PSDI | I | S | OTP programming interface SDI |
| | SCE | I | S | SPI communication interface SCE |
| 4 | PT1.2 | I | S | Digital input |
| | SDI | I/O | S | SPI communication interface SDI |
| | LVDIN | A | A | LVD external signal input interface |
| 5 | PT1.3 | I | S | Digital input |
| | TST | I | S | Test Mode input pin (invalid) |
| 6 | PT1.4 | I/O | S | Digital output |
| 7 | PT1.5 | I/O | S | Digital I/O |
| | PSDO | O | C | OTP programming interface SDO |
| | SDO | I/O | S | SPI communication interface SDO |
| 8 | PT1.6 | I/O | S | Digital input/output |
| | SCK | I/O | S | SPI communication interface SCK |
| 9 | PT1.7 | I/O | S | Digital I/O |
| | BZ | O | C | Buzzer output |
| 10 | SEG21 | O | A | Segment output for LCD |

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| | | | | | |
|----|-----------|-------|-----|-------------------------------|----------------------------|
| 11 | SEG20 | O | A | Segment output for LCD | |
| 12 | SEG19 | O | A | Segment output for LCD | |
| 13 | SEG18 | O | A | Segment output for LCD | |
| 14 | SEG17 | O | A | Segment output for LCD | |
| 15 | SEG16 | O | A | Segment output for LCD | |
| 16 | SEG15 | O | A | Segment output for LCD | |
| 17 | SEG14 | O | A | Segment output for LCD | |
| 18 | SEG13 | O | A | Segment output for LCD | |
| 19 | SEG12 | O | A | Segment output for LCD | |
| 20 | SEG11 | O | A | Segment output for LCD | |
| 21 | SEG10 | O | A | Segment output for LCD | |
| 22 | SEG9 | O | A | Segment output for LCD | |
| 23 | SEG8 | O | A | Segment output for LCD | |
| 24 | SEG7 | O | A | Segment output for LCD | |
| 25 | SEG6 | O | A | Segment output for LCD | |
| 26 | SEG5 | O | A | Segment output for LCD | |
| 27 | SEG4 | O | A | Segment output for LCD | |
| 28 | SEG3 | O | A | Segment output for LCD | |
| 29 | SEG2 | O | A | Segment output for LCD | |
| 30 | COM3/SEG1 | O | A | COM/segment output for LDO | |
| 31 | COM2/SEG0 | O | A | COM/segment output for LDO | |
| 32 | COM1 | O | A | COM output for LDO | |
| 33 | COM0 | O | A | COM output for LDO | |
| 34 | VLCD | P | P | Power supply for LDO | |
| 35 | NC | - | - | Unused | |
| 36 | NC | - | - | Unused | |
| 37 | NC | - | - | Unused | |
| 38 | NC | - | - | Unused | |
| 39 | NC | - | - | Unused | |
| 40 | NC | - | - | Unused | |
| 41 | VDD | P | P | Power supply for IC operation | |
| 42 | PT2.0/XTO | PT2.0 | I/O | S | Digital I/O |
| | | XTO | A | A | External oscillator output |
| 43 | PT2.1/XTI | PT2.1 | I/O | S | Digital I/O |
| | | XTI | A | A | External oscillator input |

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| | | | | | |
|----|----------------|-------|-----|---|---------------------------|
| 44 | PT2.2/PWM0/PFD | PT2.2 | I/O | C | Digital I/O |
| | | PWM0 | O | C | PWM output |
| | | PFD | O | C | PFD output |
| 45 | PT2.3/TMCKI | PT2.3 | I/O | S | Digital I/O |
| | | TMCKI | I | S | TIMERC clock source input |
| 46 | PT2.4/CCP0 | PT2.4 | I/O | S | Digital I/O |
| | | CCP0 | I | S | CCP mode signal interface |
| 47 | PT2.5/CCP1 | PT2.5 | I/O | S | Digital I/O |
| | | CCP1 | I | S | CCP mode signal interface |
| 48 | NC | - | - | Unused | |
| 49 | NC | - | - | Unused | |
| 50 | NC | - | - | Unused | |
| 51 | NC | - | - | Unused | |
| 52 | VDDA | P | P | Regulator output Analog circuit voltage source | |
| 53 | ACM | P | P | Internal analog circuit common ground pin | |
| 54 | OPO | A | A | OP output | |
| 55 | AI0 | A | A | Analog channel pin | |
| 56 | AI1 | A | A | Analog channel pin | |
| 57 | AI2 | A | A | Analog channel pin | |
| 58 | AI3 | A | A | Analog channel pin | |
| 59 | AI4 | A | A | Analog channel pin | |
| 60 | AI5 | A | A | Analog channel pin | |
| 61 | AI6 | A | A | Analog channel pin | |
| 62 | AI7 | A | A | Analog channel pin | |
| 63 | NC | - | - | Unused | |
| 64 | VSS | P | P | Grounding pin for IC operation voltage | |

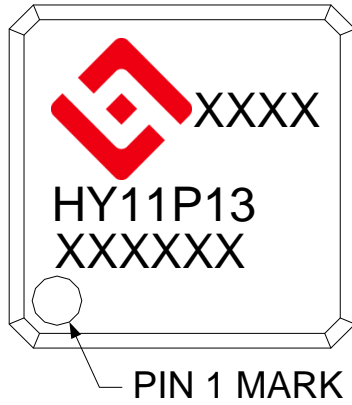
Table 2-1 Pin Definition and Function Description

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2.2.1. LQFP package marker information



→ HYCON's Logo + Traceability code

→ Product Name : HY11P13

→ Product Lot No.

3. Application Circuit

3.1. Bridge Sensor I

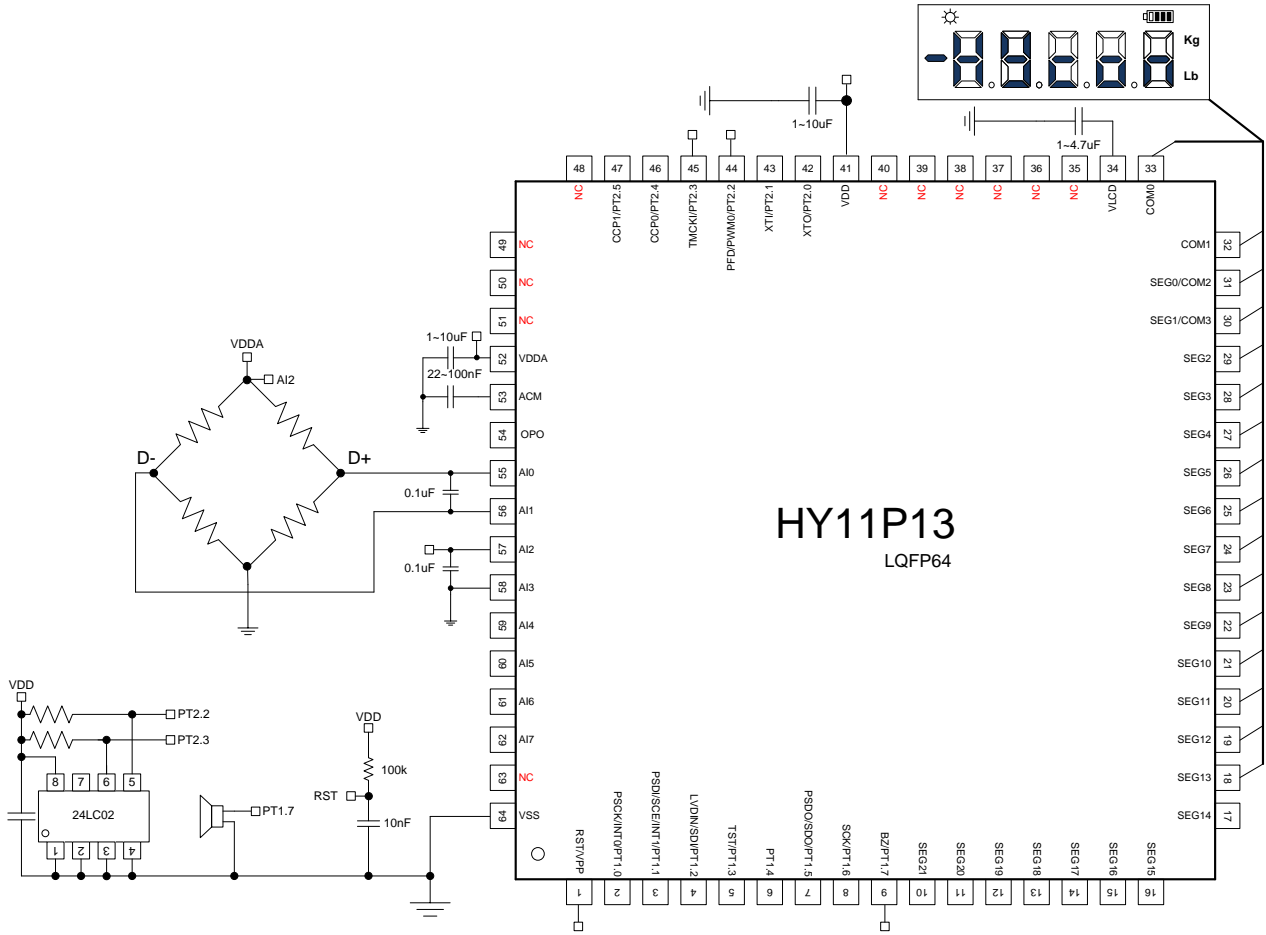


Figure 3-1 Bridge Sensor Application Circuit

Note 1 : DCSET[2:0] can conduct bias adjustment of Load Cell zero point voltage address

3.2. Bridge Sensor II

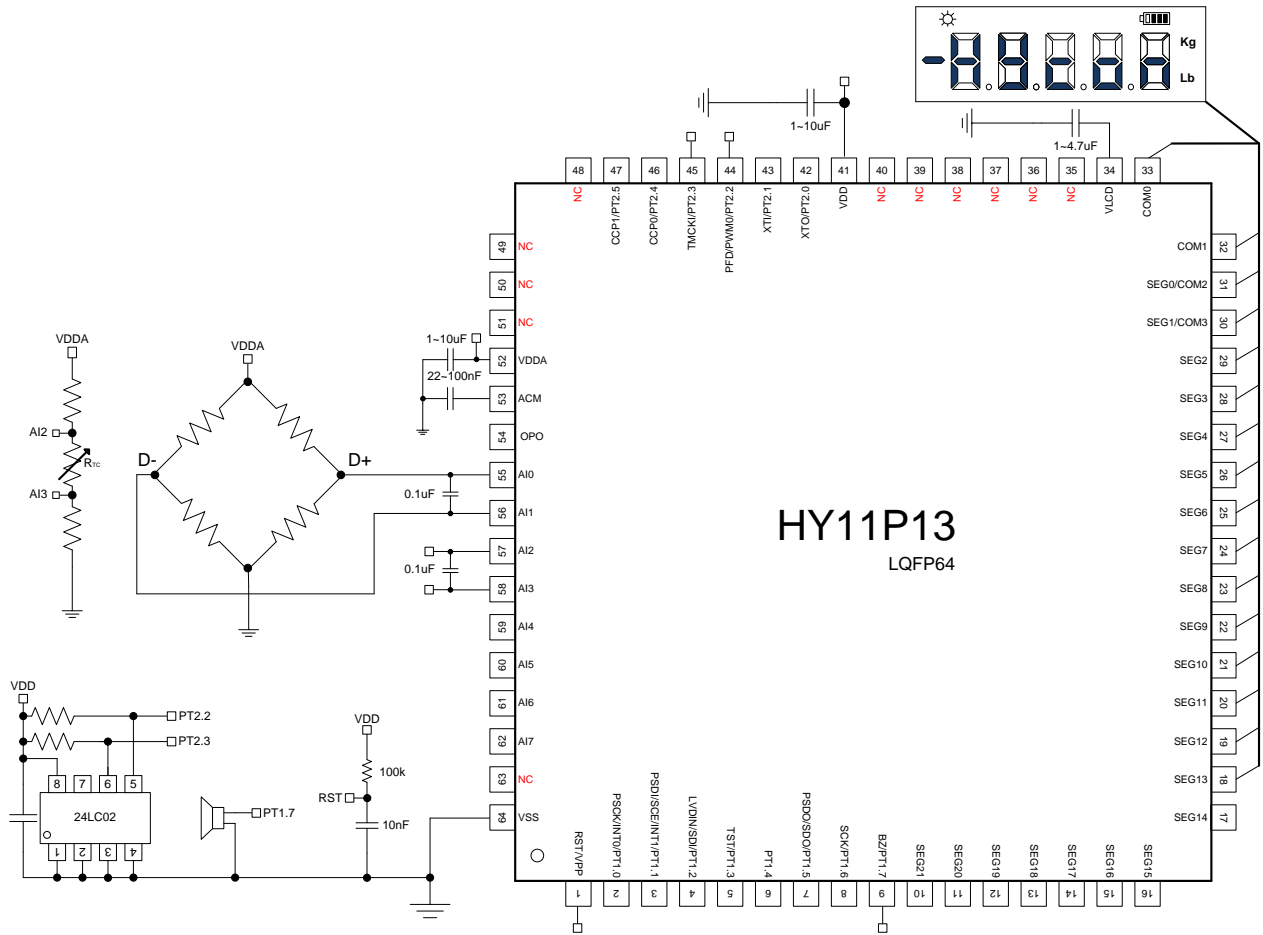


Figure 3-2 Application Circuit of Temperature Compensation Bridge Sensor

Note 1 : Using temperature compensation resistor NTC basic circuit

Note 2 : DCSET[2:0] can conduct bias adjustment of Load Cell zero point voltage address

3.3. Bridge Sensor (Pressure Sensor)

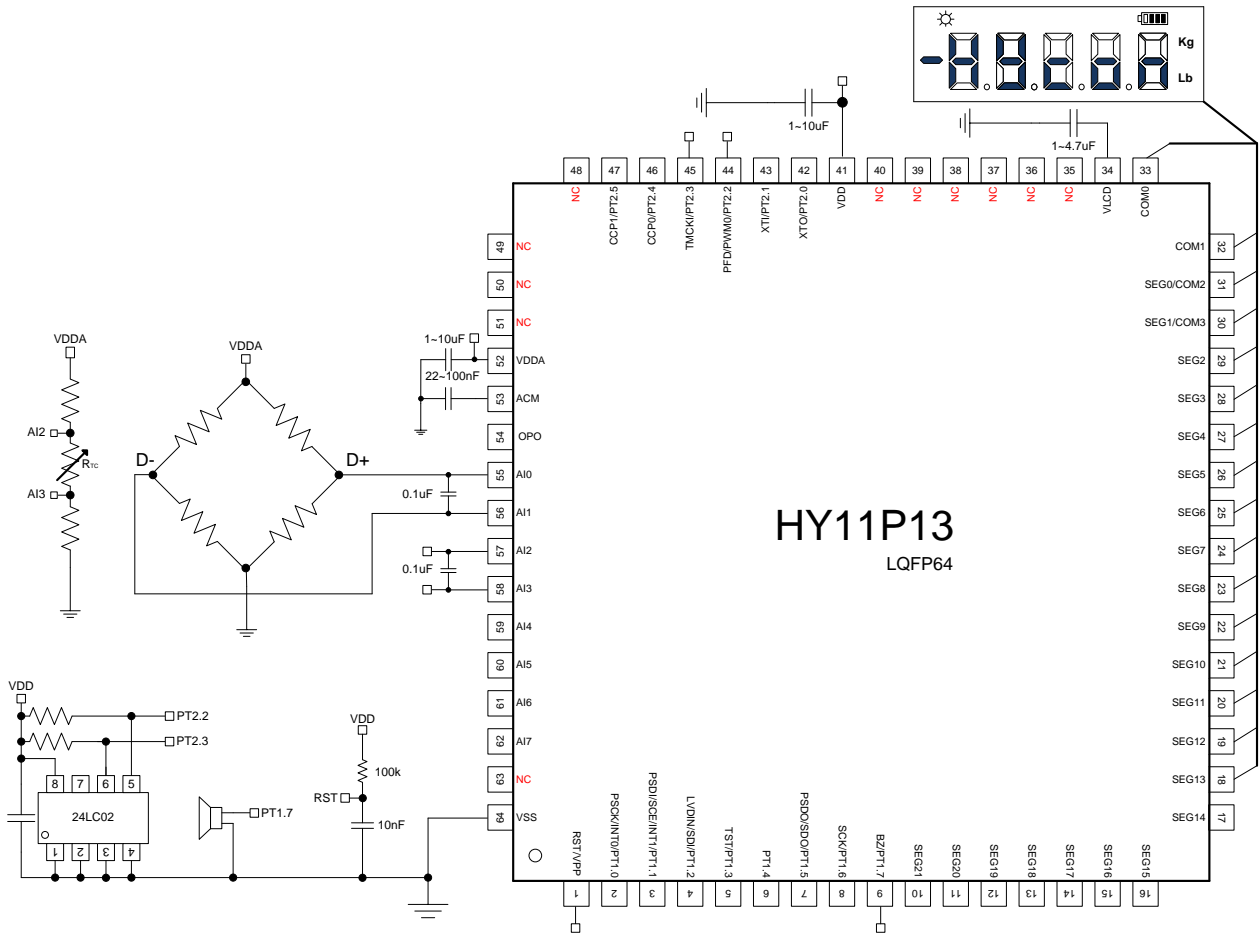


Figure 3-3 Temperature Compensative Bridge Sensor Application Circuit (wo/ internal PGA amplification)

Note 1 : Using temperature compensation resistor NTC basic circuit

Note 2 : Pressure sensor zero point voltage address can be configured through DCSET[2:0] bias adjustment.

3.4. IR Sensor

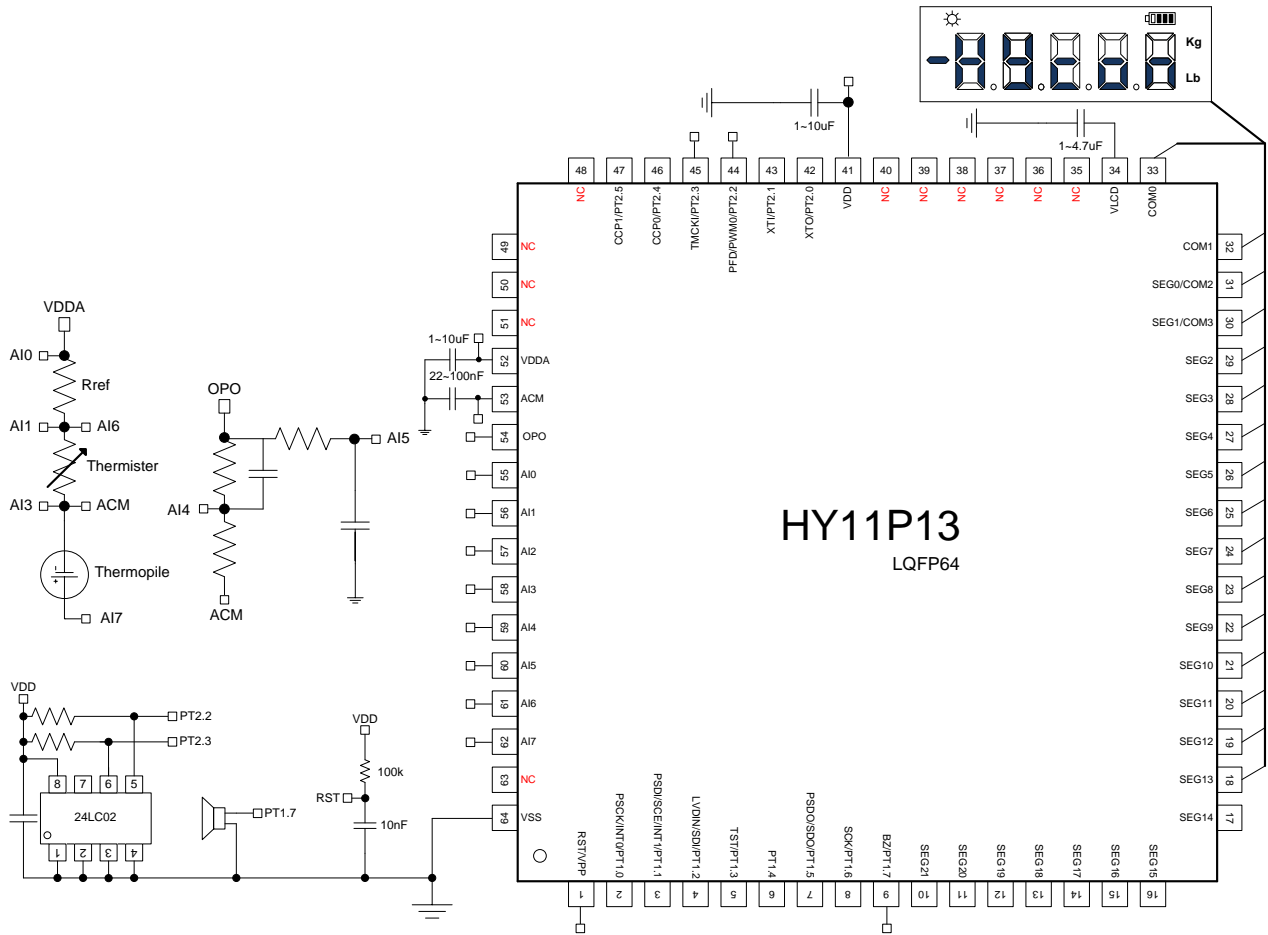


Figure 3-4 IR Sensor Application Circuit

3.5. 4-20mA Current Panel Meter (Two-wire Type)

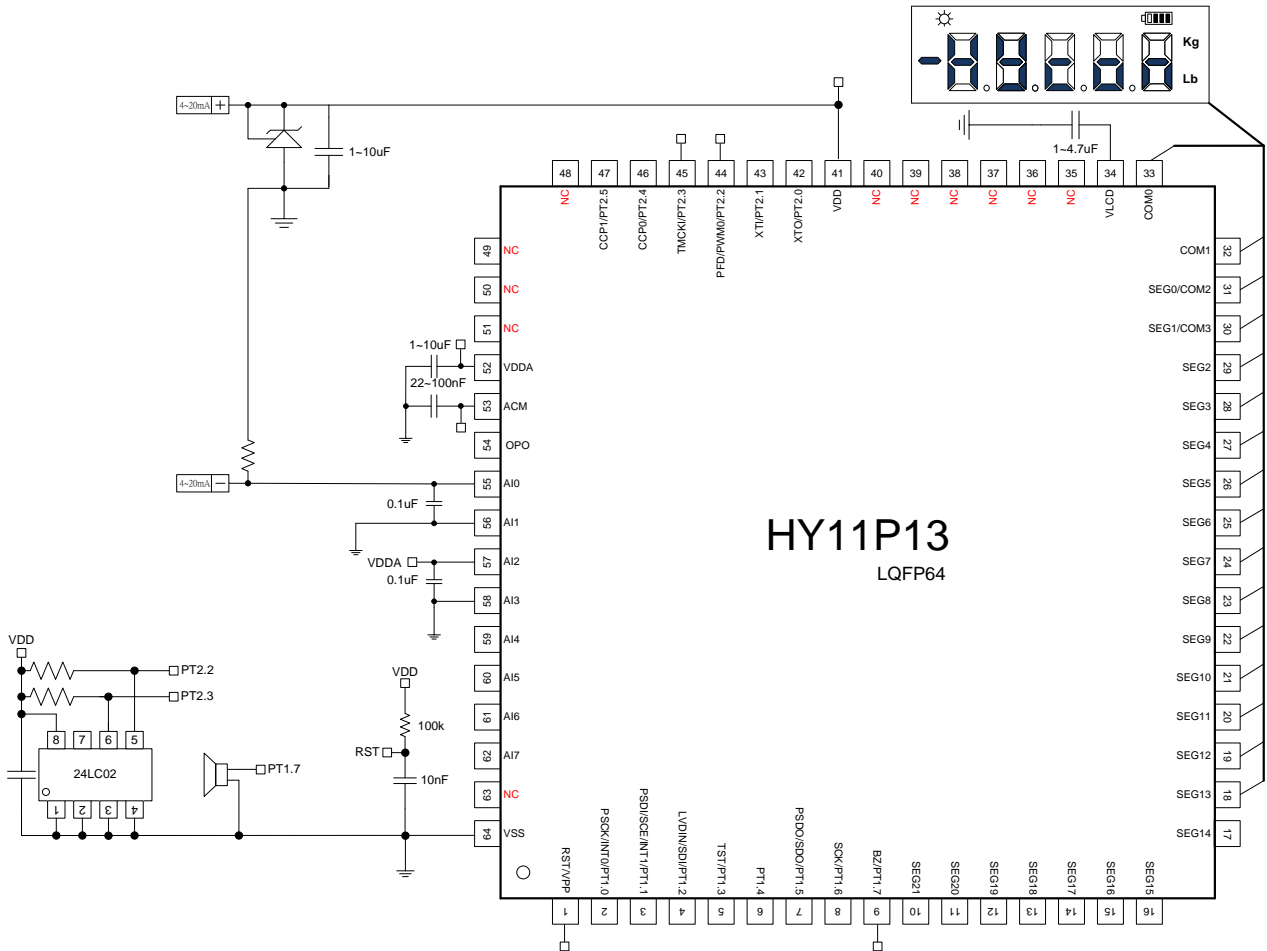
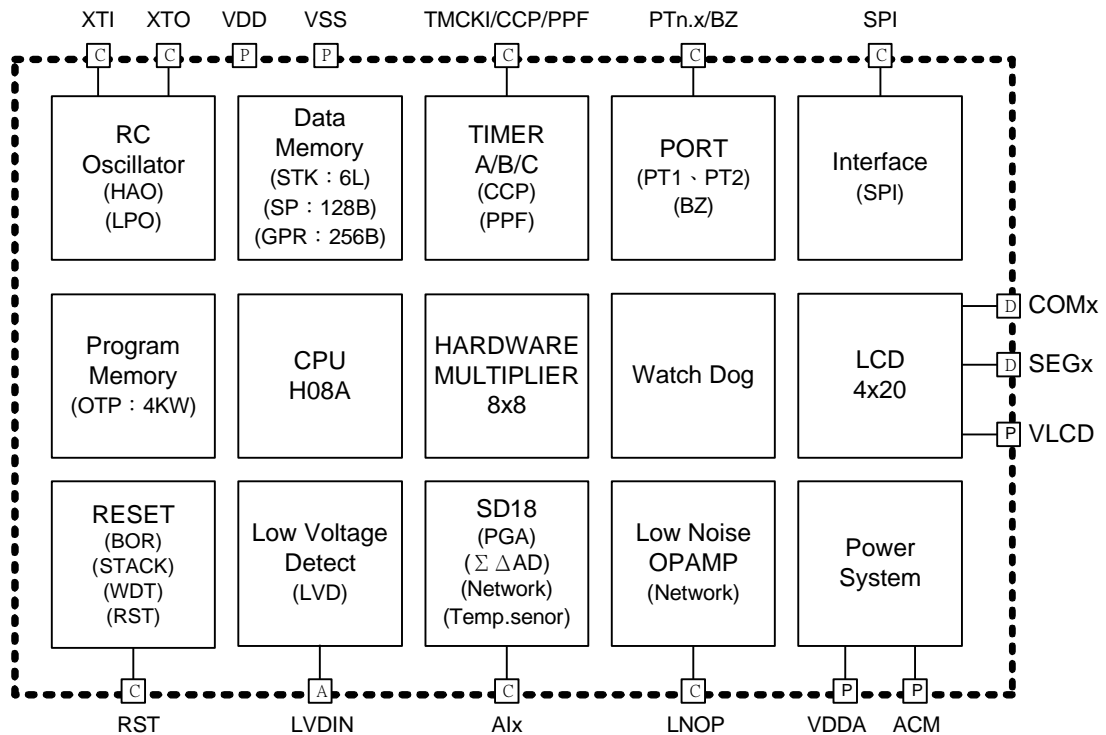


Figure 3-5 4-20mA Panel Meter that Unneeded to Connect External Power Supply

4. Function Outline

4.1. Internal Block Diagram



P Power Pad
 D Digital Pad
 A Analog Pad
 C Common I/O Pad

Figure 4-1 HY11P13 Internal Block Diagram

4.2. Related Description and Supporting Documents

IC Function Related Operating Instruction

| | |
|-----------------|------------------------------|
| DS-HY11P13-Vxx | HY11P13 Data Sheet |
| UG-HY11S14-Vxx | HY11P Series Users' Manual |
| APD-CORE002-Vxx | H08A Instruction Description |

Development Tool Related Operating Instruction

| | |
|------------------|---|
| APD-HYIDE006-Vxx | HY11xxx Series Development Tool Software Instruction Manual |
| APD-HYIDE005-Vxx | HY11xxx Series Development Tool Hardware Instruction Manual |
| APD-OTP001-Vxx | OTP Products Programming Pin Manual |

Product Production Related Operating Instruction

| | |
|------------------|--|
| APD-HYIDE004-Vxx | HY1xxxx Series Production Line Specialized Programmer Manual |
| BDI-HY11P13-Vxx | HY11P13 Individual Product Die Bonding Information |

4.3. SD18 Network

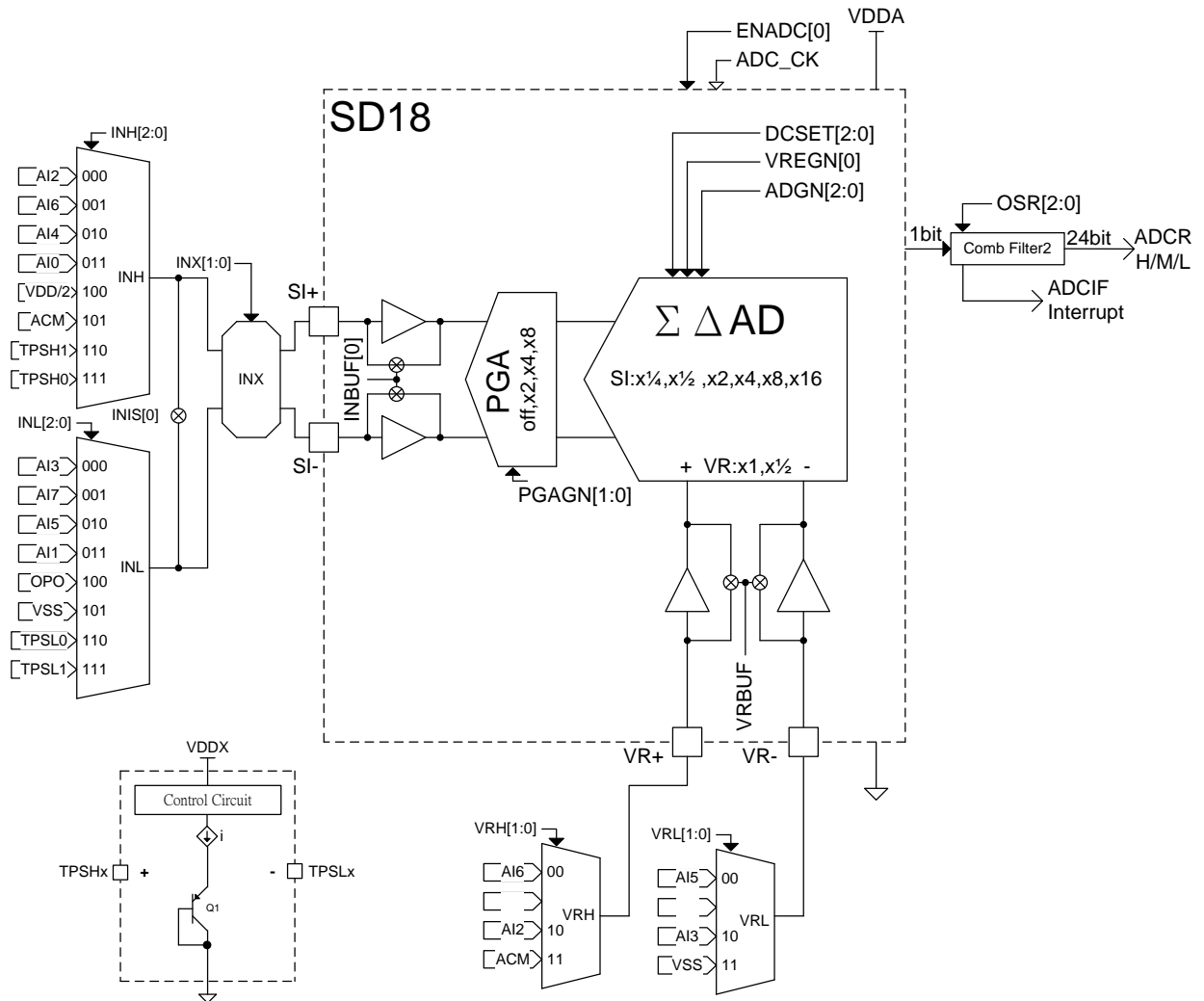


Figure 4-2 SD18 Network

4.4. Low Noise OPAMP Network

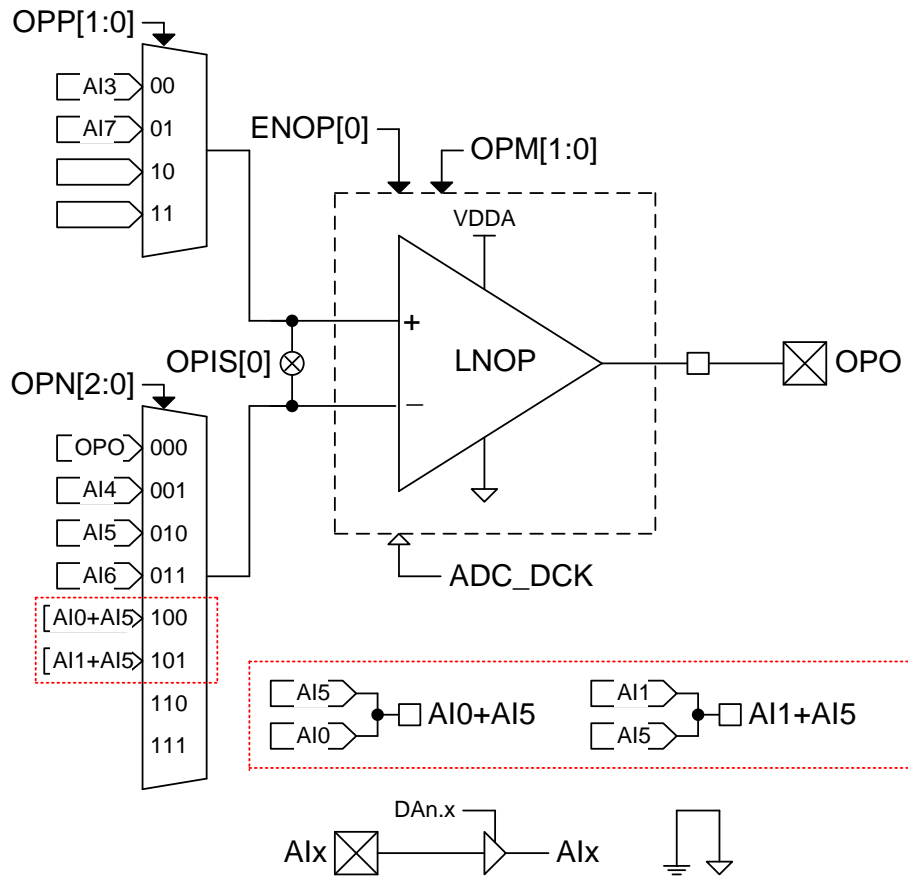


Figure 4-3 Low Noise OPAMP Network

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5. Register List

| “.”no use,“*”read/write,“w”write,“r”read,“r0”only read 0,“r1”only read 1,“w0”only write 0,“w1”only write 1 “.”unimplemented bit,“x”unknown,“u”unchanged,“d”depends on condition | | | | | | | | | | | | | |
|--|-----------|--|------------|------------|------------|------------|------------|-----------|------------|-----------|-----------|-------------------------|-----------------|
| Address | File Name | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | A-RESET | I-RESET | R/W | |
| 00H | INDF0 | Contents of FSR0 to address data memory value of FSR0 not changed | | | | | | | | | N/A | N/A | ***** |
| 01H | POINC0 | Contents of FSR0 to address data memory value of FSR0 post-incremented | | | | | | | | | N/A | N/A | ***** |
| 02H | PODEC0 | Contents of FSR0 to address data memory value of FSR0 post-decremented | | | | | | | | | N/A | N/A | ***** |
| 03H | PRINC0 | Contents of FSR0 to address data memory value of FSR0 pre-incremented | | | | | | | | | N/A | N/A | ***** |
| 04H | PLUSW0 | Contents of FSR0 to address data memory value of FSR0 offset by W | | | | | | | | | N/A | N/A | ***** |
| 05H | INDF1 | Contents of FSR1 to address data memory value of FSR0 not changed | | | | | | | | | N/A | N/A | ***** |
| 06H | POINC1 | Contents of FSR1 to address data memory value of FSR0 post-incremented | | | | | | | | | N/A | N/A | ***** |
| 07H | PODEC1 | Contents of FSR1 to address data memory value of FSR0 post-decremented | | | | | | | | | N/A | N/A | ***** |
| 08H | PRINC1 | Contents of FSR1 to address data memory value of FSR0 pre-incremented | | | | | | | | | N/A | N/A | ***** |
| 09H | PLUSW1 | Contents of FSR1 to address data memory value of FSR0 offset by W | | | | | | | | | N/A | N/A | ***** |
| 0FH | FSR0H | | | | | | | | | FSR0[8] |x |u |* |
| 10H | FSROL | Indirect Data Memory Address Pointer 0 Low Byte,FSR0[7:0] | | | | | | | | | xxxx xxxx | uuuu uuuu | ***** |
| 11H | FSR1H | | | | | | | | | FSR1[8] |x |u |* |
| 12H | FSR1L | Indirect Data Memory Address Pointer 1 Low Byte,FSR1[7:0] | | | | | | | | | xxxx xxxx | uuuu uuuu | ***** |
| 16H | TOSH | | | | | TOS[11] | TOS[10] | TOS[9] | TOS[8] | 0000 | 0000 |* | |
| 17H | TOSL | Top-of-Stack Low Byte (TOS<7:0>) | | | | | | | | | 0000 0000 | 0000 0000 | ***** |
| 18H | STKPTR | STKFL | STKUN | STKOV | | | | | STKPR[2:0] | 000. 000 | 000. 000 | r,rw0,rw0,-,r,r,r | |
| 1AH | PCLATH | | | | | PC[11] | PC[10] | PC[9] | PC[8] | 0000 | 0000 |* | |
| 1BH | PCLATL | PC Low Byte for PC<7:0> | | | | | | | | | 0000 0000 | 0000 0000 | ***** |
| 1DH | TBLPTRH | | | | | TBLPTR[11] | TBLPTR[10] | TBLPTR[9] | TBLPTR[8] | 0000 | 0000 |* | |
| 1EH | TBLPTRL | Program Memory Table Pointer Low Byte (TBLPTR<7:0>) | | | | | | | | | 0000 0000 | 0000 0000 | ***** |
| 1FH | TBLDH | Program Memory Table Latch High Byte | | | | | | | | | 0000 0000 | 0000 0000 | ***** |
| 20H | TBLDL | Program Memory Table Latch Low Byte | | | | | | | | | 0000 0000 | 0000 0000 | ***** |
| 21H | PRODH | Product Register of Multiply High Byte | | | | | | | | | xxxx xxxx | uuuu uuuu | r,r,r,r,r,r,r,r |
| 22H | PRODL | Product Register of Multiply Low Byte | | | | | | | | | xxxx xxxx | uuuu uuuu | r,r,r,r,r,r,r,r |
| 23H | INTE1 | GIE | ADCFE | TMCFE | TMBIE | TMAIE | WDTIE | E1IE | E0IE | 0000 0000 | 0000 0000 | ***** | |
| 24H | INTE2 | TXIE | RCIE | | | | SSPIE | CCP1IE | CCP0IE | 000 | 000 |* | |
| 26H | INTF1 | | ADCFIF | TMCFIF | TMBIF | TMAIF | WDTIF | E1IF | E0IF | .000 0000 | .000 0000 |* | |
| 27H | INTF2 | | | | | | SSPIF | CCP1IF | CCP0IF | 000 | 000 |* | |
| 29H | WREG | Working Register | | | | | | | | | xxxx xxxx | uuuu uuuu | ***** |
| 2AH | BSRCN | | | | | | | | | BSR[0] | 0 | 0 |* |
| 2BH | STATUS | | | | | C | DC | N | OV | Z | ...x xxxx | ...u uuuu |* |
| 2CH | PSTATUS | PD | TO | IDLE | BOR | | SKERR | | | 000d .0. | uduu .d. | rw0,rw0,rw0,rw0,-,rw0,- | |
| 2DH | LVDON | | LVDIF | LVD | LVDON | VLDX[3:0] | | | | .000 0000 | .000 uuuu |* | |
| 30H | PWRCN | ENVDDA | VDDAX[1:0] | | ENACM | | | | | 0000 | 0000 |* | |
| 31H | MCKCN1 | ADCS[2:0] | | | ADCCK | XTHSP | XTSP | ENXT | ENHAO | 0000 0001 | 0000 0001 | ***** | |
| 32H | MCKCN2 | | LSCK | HSCK | HSS[1:0] | | CPUCK[1:0] | | | .00 0000 | .00 0000 |* | |
| 33H | MCKCN3 | LCDS[2:0] | | | PERCK | BZS[2:0] | | | | 000. 0000 | 000. 0000 | ***** | |
| 37H | OPCN1 | ENOP | OPM[1:0] | | OPP[1:0] | | OPN[2:0] | | | 0000 0000 | 0000 0000 | ***** | |
| 39H | ADCRH | ADC conversion memory HighByte | | | | | | | | | xxxx xxxx | uuuu uuuu | r,r,r,r,r,r,r,r |
| 3AH | ADCRM | ADC conversion memory Middle Byte | | | | | | | | | xxxx xxxx | uuuu uuuu | r,r,r,r,r,r,r,r |
| 3BH | ADCRH | ADC conversion memory Low Byte | | | | | | | | | xxxx xxxx | uuuu uuuu | r,r,r,r,r,r,r,r |
| 3CH | ADCCN1 | ENADC | ENHIGN | ENCHP | PGAGN[1:0] | | ADGN[2:0] | | | 0000 0000 | 0000 0000 | ***** | |
| 3DH | ADCCN2 | | INBUF | VRBUF | VREGN | DCSET[2:0] | | | | .00 0000 | .00 0000 |* | |
| 3EH | ADCCN3 | OSR[2:0] | | | | | | | | 000. | 000. |* | |
| 3FH | AINET1 | INH[2:0] | | | INL[2:0] | | INIS | | OPIS | 0000 0000 | 0000 0000 | ***** | |
| 40H | AINET2 | VRH[1:0] | | INX[1:0] | | VRL[1:0] | | | .000 000. | .000 000. |* | | |
| 41H | TMACN | ENTMA | TMACK | TMAS[1:0] | | ENWDT | WDTS[2:0] | | | 0000 0000 | 0000 0000 |* w1 | |
| 42H | TMAR | TimerA data register | | | | | | | | | xxxx xxxx | uuuu uuuu | r,r,r,r,r,r,r,r |
| 43H | TMBCN | ENTMB | TMACK | TMBS[1:0] | | TMBSYC | TMBR2R | | | 0000 00. | 0000 00. |* | |
| 44H | TMBRH | TimerB High Byte data register | | | | | | | | | xxxx xxxx | uuuu uuuu | ***** |
| 45H | TMBRL | TimerB Low Byte data register | | | | | | | | | xxxx xxxx | uuuu uuuu | ***** |
| 46H | TMCCN | ENTMC | TMCCK[1:0] | | TMCS1[2:0] | | TMCS0[1:0] | | | 0000 0000 | 0000 0000 | ***** | |
| 47H | PRC | TimerC programmable register | | | | | | | | | 1111 1111 | 1111 1111 | ***** |
| 48H | TMCR | TimerC register | | | | | | | | | 0000 0000 | 0000 0000 | r,r,r,r,r,r,r,r |
| 49H | CCPCN | CCP1M[3:0] | | | | CCP0M[3:0] | | | | | 0000 0000 | 0000 0000 | ***** |
| 4AH | CCPORH | CCP0 High Byte data register | | | | | | | | | xxxx xxxx | uuuu uuuu | ***** |
| 4BH | CCP0RL | CCP0 Low Byte data register | | | | | | | | | xxxx xxxx | uuuu uuuu | ***** |
| 4CH | CCP1RH | CCP1 High Byte data register | | | | | | | | | xxxx xxxx | uuuu uuuu | ***** |
| 4DH | CCP1RL | CCP1 Low Byte data register | | | | | | | | | xxxx xxxx | uuuu uuuu | ***** |
| 4EH | PASC | PASF | PASC[1:0] | | | | | | | 0.00 | 0.00 |* | |
| 4FH | PWMCN | ENPWM | ENPFD | PWMRL[1:0] | | | | | | 0000 | 0000 | ***** | |
| 51H | PWMR | PWM MSB Byte register | | | | | | | | | xxxx xxxx | uuuu uuuu | ***** |

Table 5-1(a) HY11P13 Register List

HY11P13

Embedded 18-Bit ΣΔADC

8-Bit RISC-like Mixed Signal Microcontroller



“-”no use, “r”read/write, “w”write, “r”read, “r0”only read 0, “r1”only read 1, “w0”only write 0, “w1”only write 1
 “.”unimplemented bit, “x”unknown, “u”unchanged, “d”depends on condition

| Address | File Name | Bit7 | Bit6 | Bit5 | Bit4 | Bit3 | Bit2 | Bit1 | Bit0 | A-RESET | i-RESET | R/W |
|-----------|-----------|--|-------------|------------|----------|-------------|------------|-------------|-----------|-----------|-----------|----------------------|
| 52H | LCDCN1 | ENLCD | LC DPR | VLCDX[1:0] | | LCDBF | LCDBI[1:0] | | | 0000 000. | 0000 000. | ***** 1 1 1 1 1 1 |
| 53H | LCDCN2 | LCDBL | LC DMX[1:0] | | | | | | | 000. | 000. | ***** 1 1 1 1 1 1 |
| 54H | LCD0 | Segment SEG2@[3:0] and SEG3@[7:4] data register of LCD | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 55H | LCD1 | Segment SEG4@[3:0] and SEG5@[7:4] data register of LCD | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 56H | LCD2 | Segment SEG6@[3:0] and SEG7@[7:4] data register of LCD | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 57H | LCD3 | Segment SEG8@[3:0] and SEG9@[7:4] data register of LCD | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 58H | LCD4 | Segment SEG10@[3:0] and SEG11@[7:4] data register of LCD | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 59H | LCD5 | Segment SEG12@[3:0] and SEG13@[7:4] data register of LCD | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 5AH | LCD6 | Segment SEG14@[3:0] and SEG15@[7:4] data register of LCD | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 5BH | LCD7 | Segment SEG16@[3:0] and SEG17@[7:4] data register of LCD | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 5CH | LCD8 | Segment SEG18@[3:0] and SEG19@[7:4] data register of LCD | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 5DH | LCD9 | Segment SEG20@[3:0] and SEG21@[7:4] data register of LCD | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 5EH | SSPCON1 | SSPEN | CKP | CKE | SMP | | | | SSPM<1:0> | 0000 ..00 | uuuu ..uu | ***** 1 1 1 1 1 1 |
| 60H | SSPSTA | SSPBUY | SSPOV | | | | | | BF | 00.. ..0 | 00.. ..0 | r,r,r,r,r,r,r |
| 61H | SSPBUF | SSP Receive Buffer/Transmit Register | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 6DH | PT1 | PT1.7 | PT1.6 | PT1.5 | PT1.4 | PT1.3 | PT1.2 | PT1.1 | PT1.0 | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 6EH | TRISC1 | TC1.7 | TC1.6 | TC1.5 | TC1.4 | | | | | 0000 | 0000 | ***** 1 1 1 1 1 1 |
| 6FH | PT1DA | | | | | | DA1.2 | | |0.. |0.. | ***** 1 1 1 1 1 1 |
| 70H | PT1PU | PU1.7 | PU1.6 | PU1.5 | PU1.4 | PU1.3 | PU1.2 | PU1.1 | PU1.0 | 0000 0000 | 0000 0000 | ***** 1 1 1 1 1 1 |
| 71H | PT1M1 | | | | | INTEG1[1:0] | | INTEG0[1:0] | | 0000 | 0000 | ***** 1 1 1 1 1 1 |
| 72H | PT1M2 | | PM1.7[0] | | PM1.6[0] | | PM1.5[0] | | | .0.0 .0.. | .0.0 .0.. | ***** 1 1 1 1 1 1 |
| 74H | PT2 | | | PT2.5 | PT2.4 | PT2.3 | PT2.2 | PT2.1 | PT2.0 | ..xx xxxx | ..uu uuuu | ***** 1 1 1 1 1 1 |
| 75H | TRISC2 | | | TC2.5 | TC2.4 | TC2.3 | TC2.2 | TC2.1 | TC2.0 | ..00 0000 | ..00 0000 | ***** 1 1 1 1 1 1 |
| 77H | PT2PU | | | PU2.5 | PU2.4 | PU2.3 | PU2.2 | PU2.1 | PU2.0 | ..00 0000 | ..00 0000 | ***** 1 1 1 1 1 1 |
| 78H | PT2M1 | | | PM2.2[1] | PM2.2[0] | | | | | ..00 | ..00 | ***** 1 1 1 1 1 1 |
| 79H | PT2M2 | PWMTR[1] | PWMTR[0] | | | PM2.5[1] | PM2.5[0] | PM2.4[1] | PM2.4[0] | 00.. 0000 | 00.. 0000 | ***** 1 1 1 1 1 1 |
| 80H ~ FFH | GPR0 | General Purpose Register as 128Byte | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |
| 100H~17FH | GPR1 | General Purpose Register as 128Byte | | | | | | | | xxxx xxxx | uuuu uuuu | ***** 1 1 1 1 1 1 |

Table 5-1(b) HY11P13 Register List (continued)

HY11P13

Embedded 18-Bit $\Sigma\Delta$ ADC
8-Bit RISC-like Mixed Signal Microcontroller



6. Electrical Characteristics

Absolute maximum ratings over operating free-air temperature (unless otherwise noted)

| | |
|---|----------------------------|
| Voltage applied at V_{DD} to V_{SS} | -0.2 V to 4.0 V |
| Voltage applied to any pin. | -0.2 V to $V_{DD} + 0.3$ V |
| Voltage applied to RST/VPP pin | -0.2 V to 6.9 V |
| Voltage applied to TST/PT1.3 pin | -0.2 V to $V_{DD} + 1$ V |
| Diode current at any device terminal | ± 2 mA |
| Storage temperature, Tstg: (unprogrammed device) | -55°C to 150°C |
| (programmed device) | -40°C to 85°C |
| Total power dissipation. | 0.5w |
| Maximum output current sink by any PORT1 to PORT3 I/O Pin. | .25mA |

6.1. Recommended operating conditions

$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$, unless otherwise noted

| Sym. | Parameter | | Test Conditions | | Min. | Typ. | Max. | unit |
|----------|----------------|-------------------|---------------------------------------|-----------------------|---------|------|------|------|
| V_{DD} | Supply Voltage | | All digital peripherals and CPU | | 2.2 | | 3.6 | V |
| | | | Analog peripherals | | 2.4 | | 3.6 | |
| V_{SS} | Supply Voltage | | | | 0 | | 0 | |
| XT | External | Watch crystal | $V_{DD} = 2.2\text{V}$, ENXT[0]=1 | XTSP[0]=0, XTHSP[0]=0 | 32.768K | | Hz | |
| | Oscillator | Ceramic resonator | | XTSP[0]=1, XTHSP[0]=0 | 450K | 8M | | |
| | Frequency | Crystal | | XTSP[0]=1, XTHSP[0]=0 | 1M | 8M | | |

6.2. Internal RC Oscillator

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

| Sym. | Parameter | Test Conditions | Min. | Typ. | Max. | unit |
|------|---------------------------------|---------------------------------------|------|------|------|------|
| HAO | High Speed Oscillator frequency | ENHAO[0]=1 | 1.8 | 2.0 | 2.2 | MHz |
| LPO | Low Power Oscillator frequency | V_{DD} supply voltage be enable LPO | 22 | 28 | 35 | KHz |

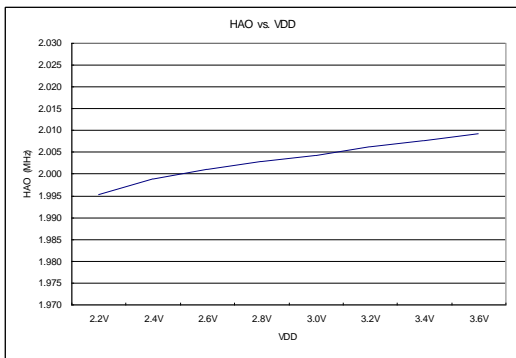


Figure 6.2-1 HAO vs. VDD

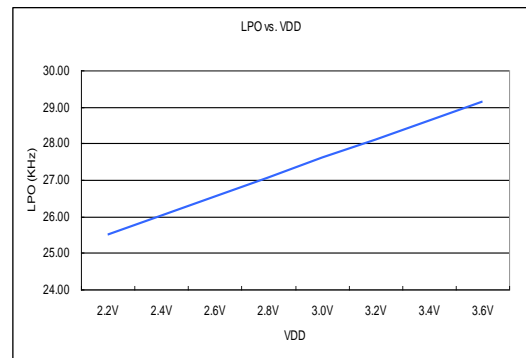


Figure 6.2-2 LPO vs. VDD

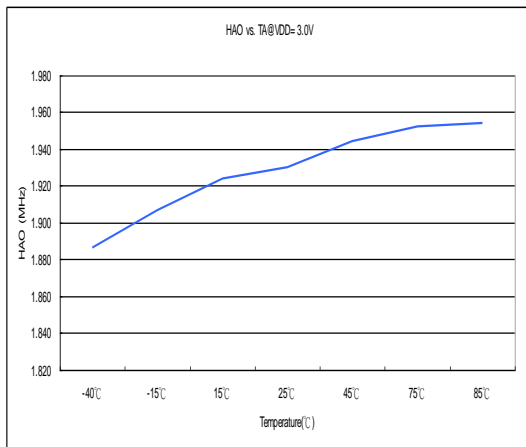


Figure 6.2-3 HAO vs. Temperature

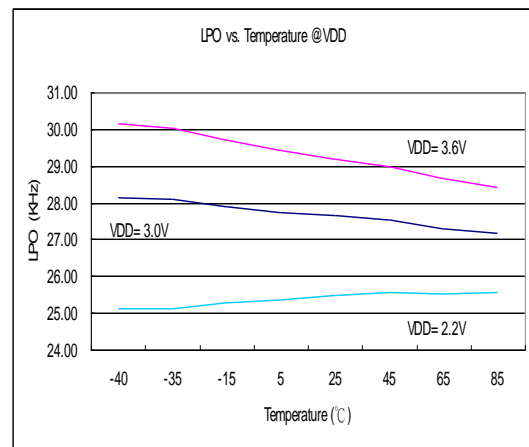


Figure 6.2-4 LPO vs. Temperature

6.3. Supply Current into VDD Excluding Peripherals Current

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, \text{OSC_LPO} = 28\text{KHz}$, unless otherwise noted

| Sym. | Parameter | Test Conditions | Min. | Typ. | Max. | unit |
|------------------|---------------|--|------|------|------|------|
| I _{AM1} | Active mode 1 | OSC_CY = 8MHz, OSC_HAO = off, CPU_CK = 8MHz | | 1.2 | 2 | mA |
| I _{AM2} | Active mode 2 | OSC_CY = off, OSC_HAO = 2MHz, CPU_CK = 2MHz | | 0.32 | 0.55 | mA |
| I _{AM3} | Active mode 3 | OSC_CY = off, OSC_HAO = 2MHz, CPU_CK = 1MHz | | 0.18 | 0.3 | mA |
| I _{LP1} | Low Power 1 | OSC_CY = 32768Hz, OSC_HAO = off, CPU_CK = 16384Hz | | 7 | 12 | uA |
| I _{LP2} | Low Power 2 | OSC_CY = off, OSC_HAO = off, CPU_CK = LPO, Idle state | | 1.65 | 3 | uA |
| I _{LP3} | Low Power 3 | OSC_CY = off, OSC_HAO = off, CPU_CK = off, Sleep state | | 0.65 | 1.2 | uA |

OSC_CY : External Oscillator frequency.

OSC_HAO : Internal High Accuracy Oscillator frequency.

CPU_CK : CPU core work frequency.

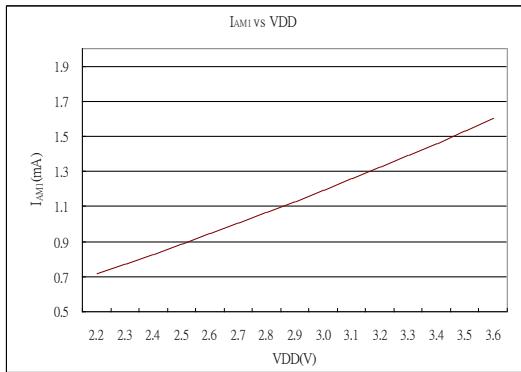


Figure 6.3-1 I_{AM1} vs. VDD

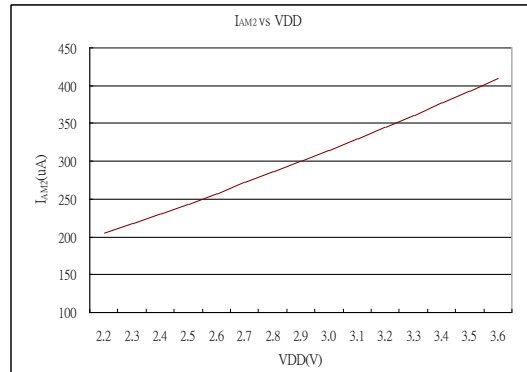


Figure 6.3-2 I_{AM2} vs. VDD

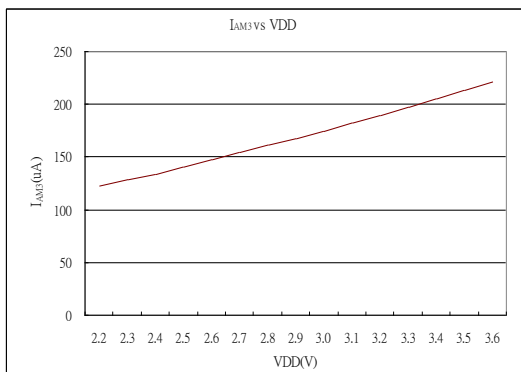


Figure 6.3-3 I_{AM3} vs. VDD

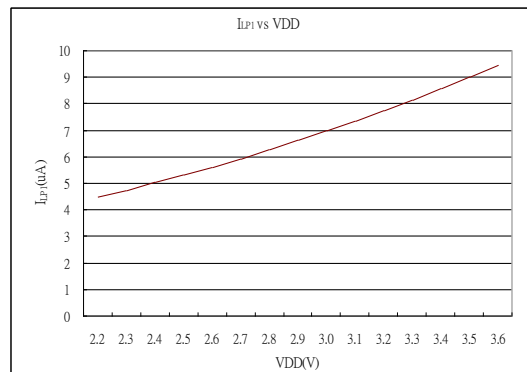


Figure 6.3-4 I_{LP1} vs. VDD

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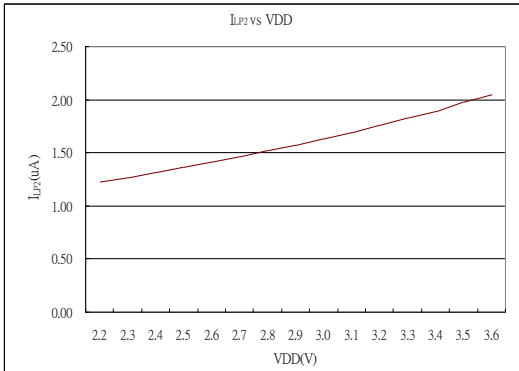


Figure 6.3-5 ILP2 vs. VDD

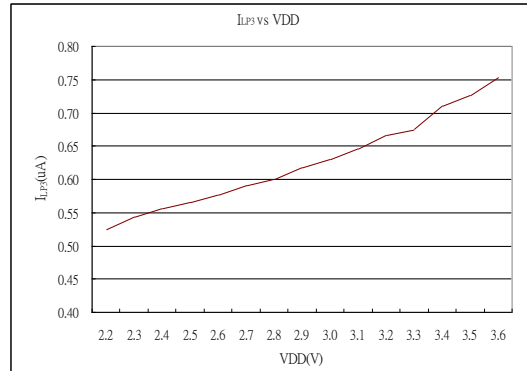


Figure 6.3-6 ILP3 vs. VDD

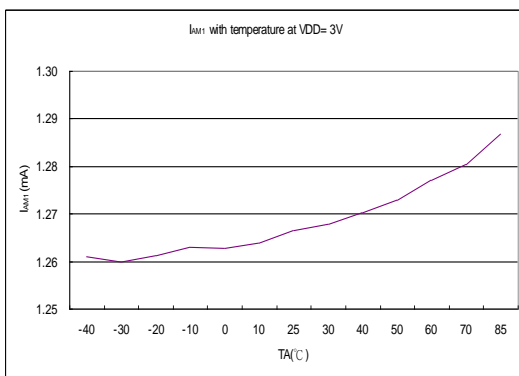


Figure 6.3-7 IAM1 vs. Temperature

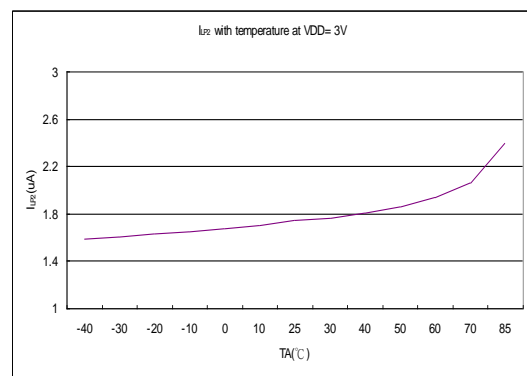


Figure 6.3-8 ILP2 vs. Temperature

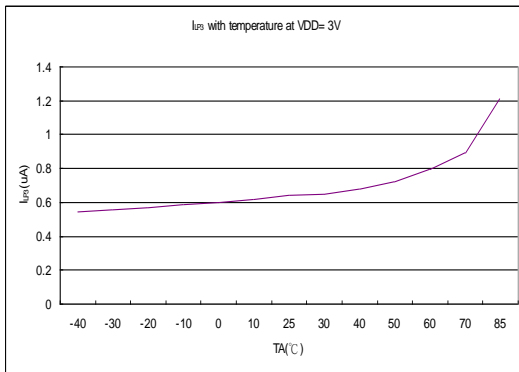


Figure 6.3-9 ILP3 vs. Temperature

6.4. Port1~2

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

| Sym. | Parameter | Test Conditions | Min. | Typ. | Max. | unit |
|---|---|-----------------------|----------------|------|----------------|------------------|
| Input voltage and Schmitt trigger and leakage current and timing | | | | | | |
| V_{IH} | High-Level input voltage | | | | 2.1 | V |
| V_{IL} | Low-Level input voltage | | 0.9 | | | |
| V_{hys} | Input Voltage hysteresis($V_{IH} - V_{IL}$) | | | 0.8 | | V |
| I_{LKG} | Leakage Current | | | | 0.1 | μA |
| R_{PU} | Port pull high resistance | | | 180 | | $\text{k}\Omega$ |
| Output voltage and current and frequency | | | | | | |
| V_{OH} | High-level output voltage | $I_{OH}=10\text{mA}$ | $V_{DD} - 0.3$ | | | V |
| V_{OL} | Low-level output voltage | $I_{OL}=-10\text{mA}$ | | | $V_{SS} + 0.3$ | |

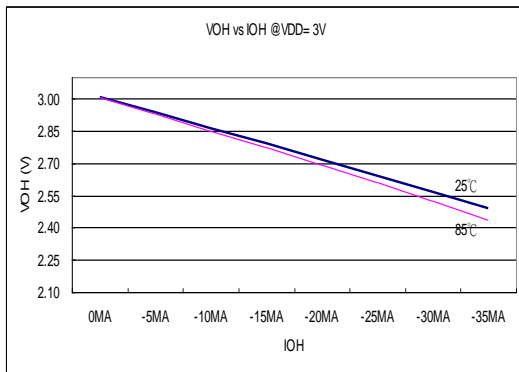


Figure 6.4-1 V_{OH} vs. I_{OH} @ $V_{DD}=3.0\text{V}$

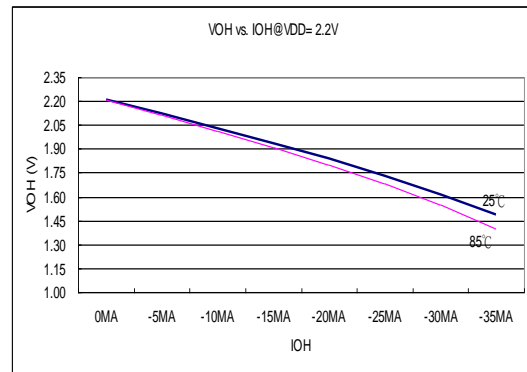


Figure 6.4-2 V_{OH} vs. I_{OH} @ $V_{DD}=2.2\text{V}$

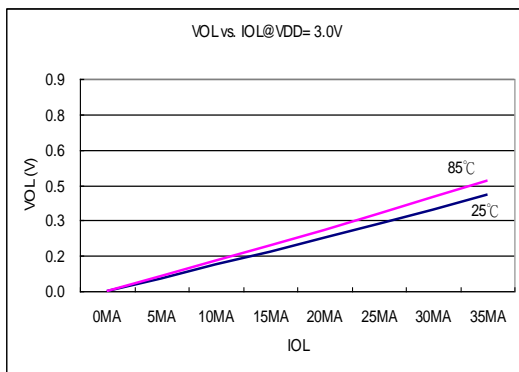


Figure 6.4-3 V_{OL} vs. I_{OL} @ $V_{DD}=3.0\text{V}$

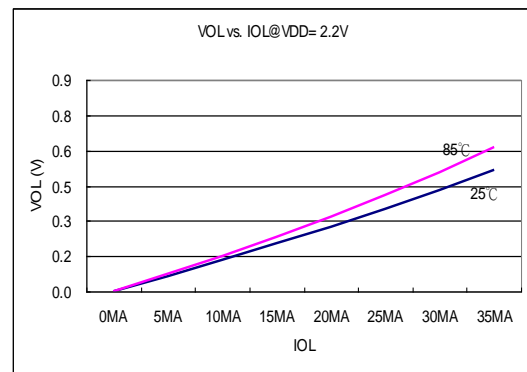


Figure 6.4-4 V_{OL} vs. I_{OL} @ $V_{DD}=2.2\text{V}$

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6.5. Reset (Brownout, External RST pin, Low Voltage Detect)

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

| Sym. | Parameter | Test Conditions | Min. | Typ. | Max. | unit | |
|--|--|---|------|------|------|-----------------------|--|
| BOR | Pulse length needed to accepted reset internally, t_{d-LVR} | | 2 | | | us | |
| | V_{DD} Start Voltage to accepted reset internally (L→H), V_{LVR} | | 1.6 | 1.85 | 2.1 | V | |
| | Hysteresis, $V_{HYS-LVR}$ | | 70 | | | mV | |
| RST | Pulse length needed as RST/VPP pin to accepted reset internally, t_{d-RST} | | 2 | | | us | |
| | Input Voltage to accepted reset internally | | 0.9 | | | V | |
| | Hysteresis, $V_{HYS-RST}$ | | 0.8 | | | V | |
| LVD | Operation current, I_{LVD} | | | 10 | 15 | uA | |
| | External input voltage to compare reference voltage | | 1.2 | | | V | |
| | Compare reference voltage temperature drift | $T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$ | 100 | | | ppm/ $^\circ\text{C}$ | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1110b$ | | 3.3 | | | V | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1101b$ | | 3.2 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1100b$ | | 3.1 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1011b$ | | 3.0 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1010b$ | | 2.9 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1001b$ | | 2.8 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1000b$ | | 2.7 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0111b$ | | 2.6 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0110b$ | | 2.5 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0101b$ | | 2.4 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0100b$ | | 2.3 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0011b$ | | 2.2 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0010b$ | | 2.1 | | | | |
| | Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0001b$ | | 2.0 | | | | |
| BOR : Brownout Reset LVR : Low Voltage Reset of BOR LVD : Low Voltage Detect RST : External Reset pin | | | | | | | |

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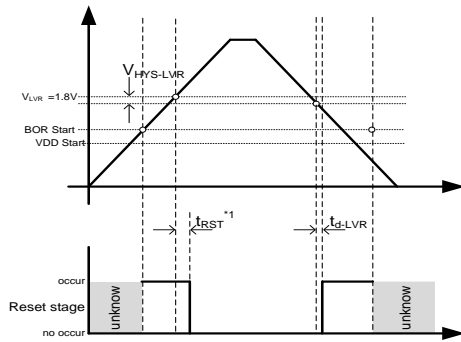


Figure 6.5-1 BOR Reset Diagram

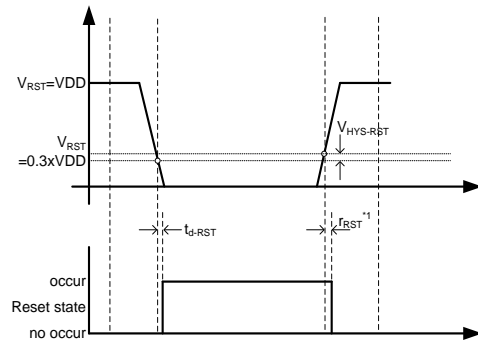


Figure 6.5-2 RST Reset Diagram

*1 t_{RST} : Please see BOR Introduce of HY11Pxx series User's Guide (UG-HY11S14-Vxx).

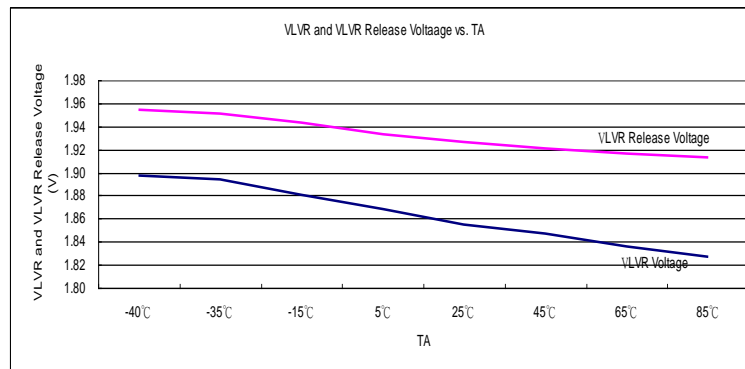


Figure 6.5-3 LVR vs. Temperature

HY11P13

Embedded 18-Bit $\Sigma\Delta$ ADC 8-Bit RISC-like Mixed Signal Microcontroller



6.6. Power System

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}$, unless otherwise noted

| Sym. | Parameter | Test Conditions | | Min. | Typ. | Max. | unit |
|------------------------|------------------------------------|--|---|------|------|------|------------------------|
| VDDA | VDDA operation current, I_{VDDA} | $I_L = 0\text{mA}$ | VDDAX[1:0]=00b | 22 | | | μA |
| | Select VDDA output voltage | $I_L = 0.1\text{mA}$, $V_{DD} \geq V_{VDDA} + 0.2\text{V}$ | VDDAX[1:0]=00b | 3.3 | | | V |
| | | | VDDAX[1:0]=01b | 2.9 | | | V |
| | | | VDDAX[1:0]=10b | 2.6 | | | V |
| | | | VDDAX[1:0]=11b | 2.4 | | | V |
| | Dropout voltage | $I_L = 10\text{mA}$ | VDDAX[1:0]=00b | 135 | | | mV |
| | | | VDDAX[1:0]=01b | 150 | | | mV |
| | | | VDDAX[1:0]=10b | 165 | | | mV |
| | | | VDDAX[1:0]=11b | 180 | | | mV |
| | Temperature drift | VDDAX[1:0]=11b | $T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$ | 50 | | | ppm/ $^\circ\text{C}$ |
| V_{DD} Voltage drift | $I_L = 0.1\text{mA}$ | $V_{DD} = 2.5\text{V} \sim 3.6\text{V}$ | ± 0.2 | | | %/V | |
| ACM | ACM operation current, I_{ACM} | $I_L = 0\text{mA}$ | | 20 | | | μA |
| | Output voltage, V_{ACM} | ENACM[0]=1 | $I_L = 0\mu\text{A}$ | 1.0 | | | V |
| | Output voltage with Load | | $I_L = \pm 200\mu\text{A}$ | 0.98 | 1.02 | | V_{ACM} |
| | Temperature drift | ENACM[0]=1, | $T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$ | 50 | | | ppm/ $^\circ\text{C}$ |
| | VDDA Voltage drift | $I_L = 10\mu\text{A}$ | | 100 | | | $\mu\text{V}/\text{V}$ |

VDDA : Adjust Voltage Regulator

ACM : Analog Common Mode Voltage

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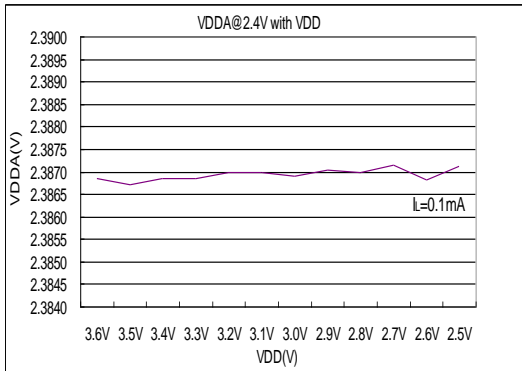


Figure 6.6-1 VDDA IL=0.1mA vs. VDD

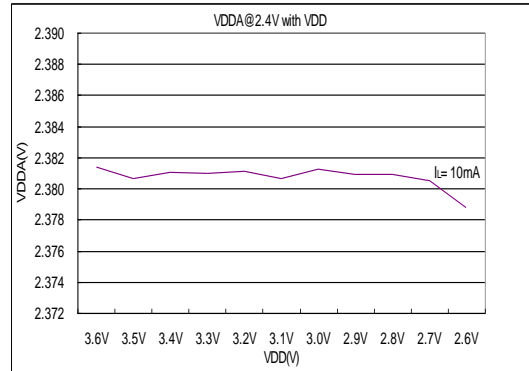


Figure 6.6-2 VDDA IL=10mA vs. VDD

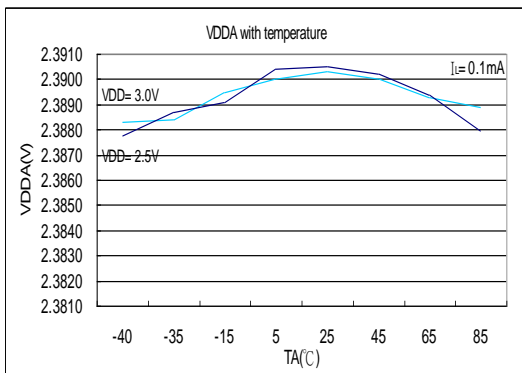


Figure 6.6-3 VDDA IL=0.1mA vs. Temperature

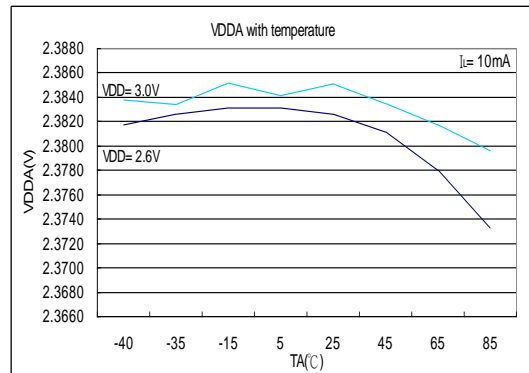


Figure 6.6-4 VDDA IL=10mA vs. Temperature

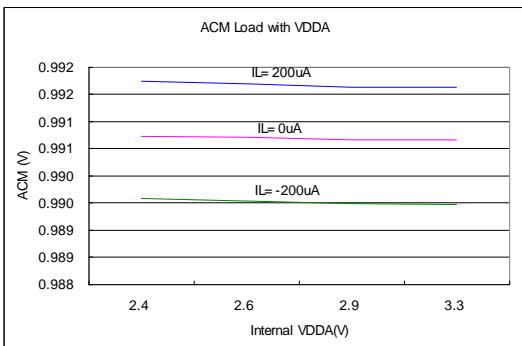


Figure 6.6-5 ACM Load vs. VDDA

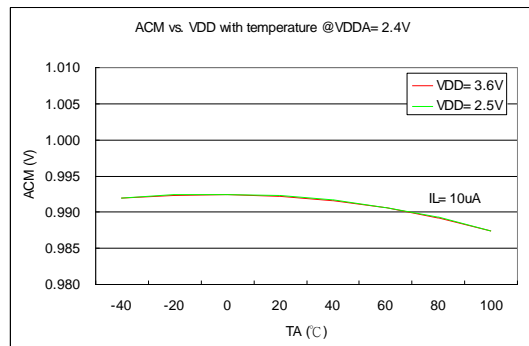


Figure 6.6-6 ACM vs. Temperature

6.7. LCD

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, C_{VLCD} = 4.7\mu\text{F}$, unless otherwise noted.

| Sym. | Parameter | Test Conditions | Min. | Typ. | Max. | unit | |
|-----------|--|--|------------------------|-------|------|------------|---|
| I_{LCD} | Operation supply current without output buffer.(all segment turn on) | LCDPR[0]=1 | $V_{DD} = 2.2\text{V}$ | 10 | | uA | |
| | | | $V_{DD} = 3.0\text{V}$ | | | | |
| VLCD | Supply Voltage at VLCD pin | LCDPR[0]=0 | 2.2 | | 3.6 | V | |
| | Embedded Charge Pump output voltage at VLCD pin | $V_{DD} = 2.2\text{V}$, LCDPR[0]=1, $C_{VLCD} = 4.7\mu\text{F}$ | VLCDX[1:0]=11b | 2.295 | 2.55 | 2.805 | V |
| | | | VLCDX[1:0]=10b | 2.52 | 2.8 | 3.08 | |
| | | | VLCDX[1:0]=01b | 2.745 | 3.05 | 3.355 | |
| | | | VLCDX[1:0]=00b | 2.97 | 3.3 | 3.63 | |
| Z_{LCD} | Output impedance with LCD buffer | $f_{LCD} = 128\text{Hz}, VLCD = 3.05\text{V}$ | | 10 | | k Ω | |

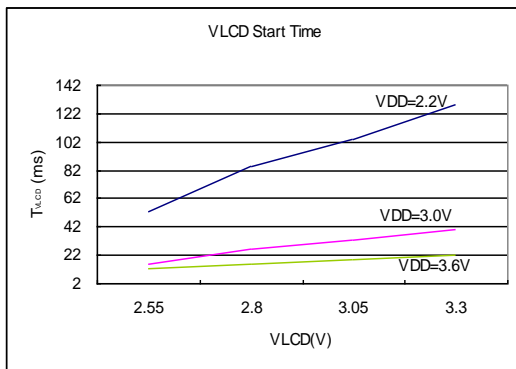


Figure 6.7-1 LCD start time

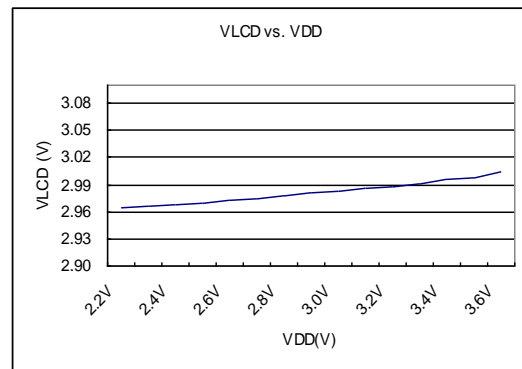


Figure 6.7-2 VLCD vs. VDD

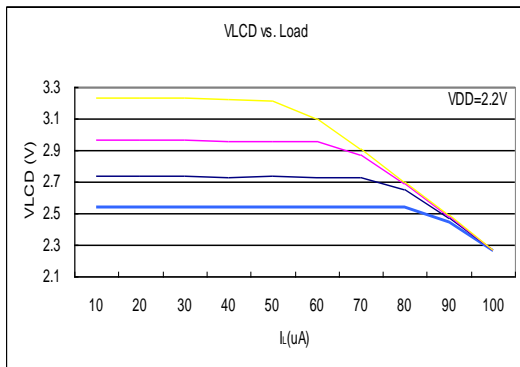


Figure 6.7-3 VLCD vs. I_L @ VDD=2.2V

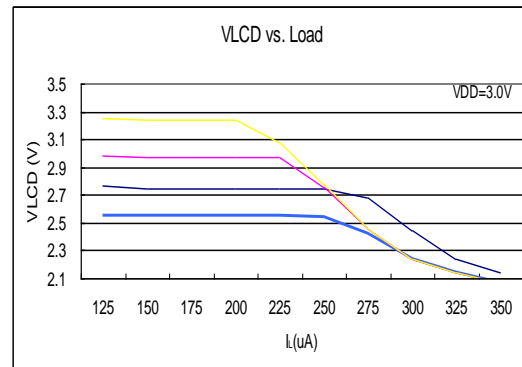


Figure 6.7-4 VLCD vs. I_L @ VDD=3.0V

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6.8. Low Noise OPAMP

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA} = 2.4\text{V}$, unless otherwise noted

| Sym. | Parameter | Test Conditions | | Min. | Typ. | Max. | unit |
|-------------|---|--|---|------|----------|-----------------|------------------------------|
| V_{LNOP} | Supply voltage at VDDA | ENVDDA[0]=0 | | 2.4 | | 3.6 | V |
| I_{LNOP} | Operation supply current | | OPM[1:0]=xxb | | 200 | | μA |
| V_{OS-OP} | Input offset voltage without chopper. | | OPM[1:0]=1xb | -2 | | 2 | mV |
| | Input offset voltage with chopper | | OPM[1:0]=0xb | | 20 | | μV |
| | Input offset voltage temperature drift. | OPM[1:0]=00b OPM[1:0]=10 | $T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$ | | 0.1 2 | | $\mu\text{V}/^\circ\text{C}$ |
| V_{OLR} | Unit gain load regulation | $V_O = 1.2\text{V}$, $V_{DDA} = 2.4\text{V}$ | $I_L = +1\text{mA}$ $I_L = -1\text{mA}$ | | 0.1 | | % V_O |
| CMVR | Common-mode voltage input range | | OPM[1:0]=xxb | 0.1 | | $V_{DDA} - 1.1$ | V |
| CMRR | Common-mode rejection ratio | | OPM[1:0]=xxb | | 90 | | dB |

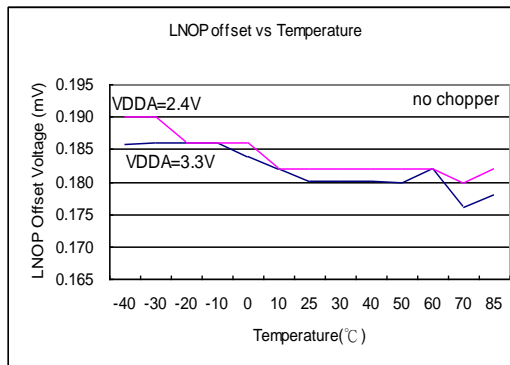


Figure 6.8-1 LNOP Offset Temperature

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6.9. SD18, Power Supply and Recommended Operating Conditions

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA} = 2.4\text{V}$, unless otherwise noted

| Sym. | Parameter | Test Conditions | | Min. | Typ. | Max. | unit |
|------------|--------------------------------------|-------------------------------------|---------------------------|------|------|-------|------|
| V_{SD18} | Supply Voltage at VDDA | ENVDDA[0]=0 | | 2.4 | | 3.6 | V |
| f_{SD18} | Modulator sample frequency, ADC_CK | | | 25 | 250 | 300 | KHz |
| | Over Sample Ratio, OSR | | | 256 | | 32768 | |
| I_{SD18} | Operation supply current without PGA | ENADC[0]=1 INBUF[0]=1,VRBUF[0]=0 | GAIN =4, ADC_CK=250KHz | 168 | | uA | |
| | | ENADC[0]=1 INBUF[0]=0,VRBUF[0]=1 | | 150 | | | |
| | | ENADC[0]=1 INBUF[0]=0,VRBUF[0]=0 | | 120 | | | |

6.9.1. PGA, Power Supply and Recommended Operating Conditions

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA} = 2.4\text{V}$, unless otherwise noted

| Sym. | Parameter | Test Conditions | | Min. | Typ. | Max. | unit |
|-----------|--------------------------|---|----------|------|------|------|--------|
| V_{PGA} | Supply Voltage at VDDA | ENVDDA[0]=0 | | 2.4 | | 3.6 | V |
| I_{PGA} | Operation supply current | PGAGN[1:0]=<01>or<1x> | | | 320 | | uA |
| G_{PGA} | Gain temperature drift | $T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$ | GAIN=128 | | 5 | | ppm/°C |

6.9.2. SD18, Performance II ($f_{SD18}=250\text{KHz}$)

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA} = 2.9\text{V}, V_{VR} = 1.0\text{V}, \text{GAIN} = 1$ without PGA, unless otherwise noted

| Sym. | Parameter | Test Conditions | | Min. | Typ. | Max. | unit |
|------------|--|---|---|-------------|------|------------|------|
| INL | Integral Nonlinearity(INL) | $V_{DDA} = 2.4\text{V}, V_{VR} = 1.0\text{V}, \Delta\text{SI} = \pm 200\text{mV}$ | | ± 0.003 | | ± 0.01 | %FSR |
| | | $V_{DDA} = 2.4\text{V}, V_{VR} = 1.0\text{V}, \Delta\text{SI} = \pm 450\text{mV}$ | | | | | |
| | No Missing Codes ³ | ADC_CK=250KHz, OSR[2:0]=010b | | 23 | | | Bits |
| G_{SD18} | Temperature drift Gain 1~x16 (INBUF[0]=0b,) Gain 1~x4 (INBUF[0]=1b,) | INBUF[0]=0b,VRBUF[0]=0b | $T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$ | 2 | | ppm/°C | |
| | | INBUF[0]=1b,VRBUF[0]=0b | | | | | |
| | | INBUF[0]=0b,VRBUF[0]=1b | | | | | |
| | | INBUF[0]=1b,VRBUF[0]=1b | | | | | |
| E_{OS} | Offset error of Full Scale Rang input voltage range with Chopper and Buffer(INBUF,VRBUF) without PGA | $\Delta\text{AI} = 0\text{V}$ $\Delta\text{VR} = 0.9\text{V}$ | Gain=2 | 1 | | %FSR | |
| | Offset error of Full Scale Rang input voltage range with Chopper without PGA and Buffer(INBUF,VRBUF) | DCSET[2:0]=<000> * ΔAI is external short | Gain=2 | 1 | | | |
| | Offset temperature drift with chopper without PGA and Buffer | | GAIN=1 | 2 | | uV/°C | |
| | | GAIN=2 | 1 | | | | |

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| | | | | | |
|--------------------|--|--|---------------------------------|------|----|
| | (INBUF,VRBUF). | | GAIN=4 | 0.5 | |
| | | | GAIN=16 | 0.15 | |
| | Offset temperature drift with chopper and Buffer (INBUF,VRBUF) without PGA. | | GAIN=1 | 2 | |
| | | | GAIN=2 | 1 | |
| | | | GAIN=4 | 0.5 | |
| | Offset temperature drift with chopper without Buffer (INBUF,VRBUF). | | GAIN=128 | 0.02 | |
| CM _{SD18} | Common-mode rejection | V _{CM} =0.7V to 1.7V, V _{VR} =1.0V, without PGA | V _{SI} =0V, GAIN=1 | 90 | dB |
| | | V _{CM} =0.7V to 1.7V, V _{VR} =1.0V, without PGA | V _{SI} =0V, GAIN=16 | 75 | |
| PSRR | DC power supply rejection | V _D DA=3.0V, Δ V _D DA=± 100mV, V _{VR} =1.0V, V _{SI} =1.2V, V _{SI} =1.2V, | GAIN=1 PGA=off | 75 | dB |
| | | | GAIN=16 PGA=8 | | |

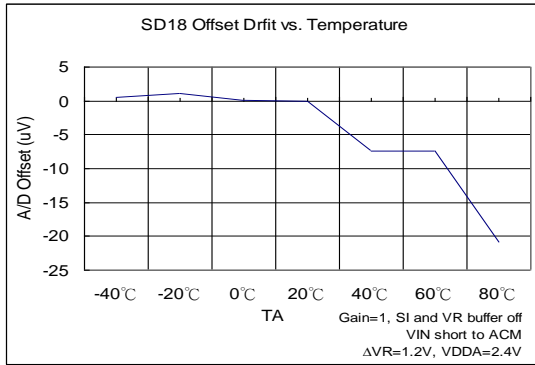


Figure 6.9-1(a) SD18 Offset Temperature Drift

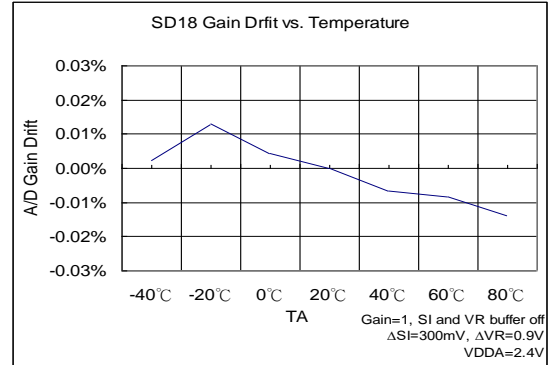


Figure 6.9-2(a) SD18 Gain Drift with Temperature

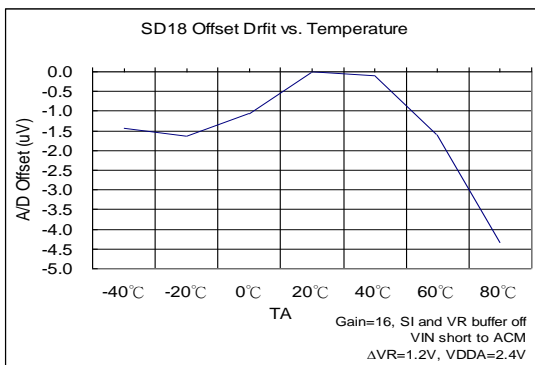


Figure 6.9-1(b) SD18 Offset Temperature Drift

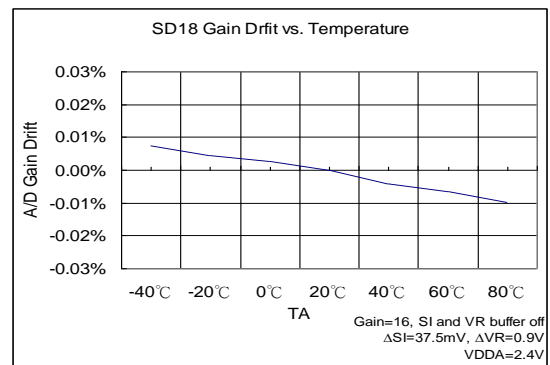


Figure 6.9-2(b) SD18 Gain Drift with Temperature

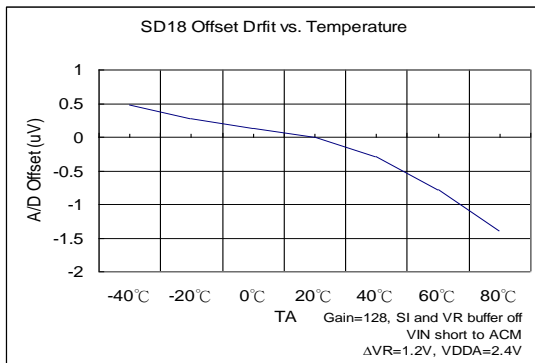


Figure 6.9-1(c) SD18 Offset Temperature Drift

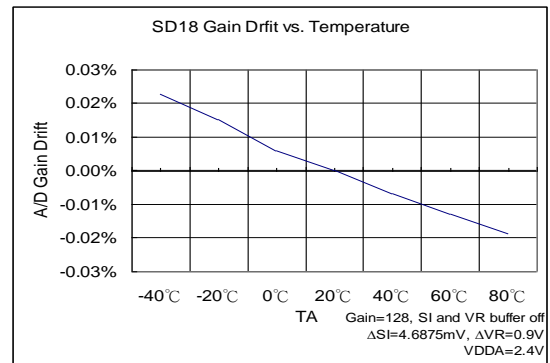


Figure 6.9-2(c) SD18 Gain Drift with Temperature

6.9.3. SD18, Temperature Sensor

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA} = 3.3\text{V}$, unless otherwise noted

| Sym. | Parameter | Test Conditions | Min. | Typ. | Max. | unit |
|-------------------|---------------------------------------|---|------|---------|------|------------------------------|
| TC _S | Sensor temperature drift | $\Delta V_R = 2.4\text{V}, V_{RGN}[0] = 1,$ INBUF[0]=1 | | 178 | | $\mu\text{V}/^\circ\text{C}$ |
| KT | Absolute Temperature Scale 0°K | | | -289 | | $^\circ\text{C}$ |
| TC _{ERR} | One point calibrate error temperature | Calibration at 25°C of -40°C~85°C | | ± 2 | | $^\circ\text{C}$ |

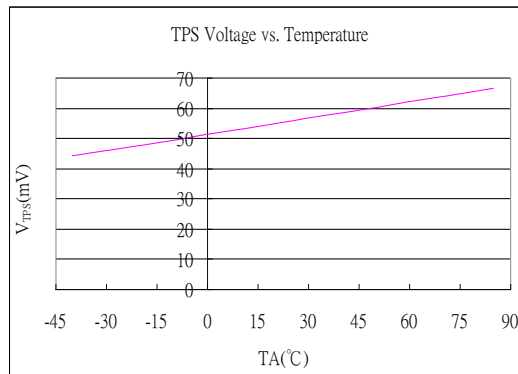


Figure 6.9-3 TPS Output Voltage vs. Temperature Drift

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6.9.4. SD18 Noise Performance

$T_A = 25^\circ\text{C}, V_{DD} = 3.0\text{V}, V_{DDA} = 2.4\text{V}$, unless otherwise noted

HY11P13 provides important input noise specification that aims at SD18. Table 6.9-4(a) and Table 6.9-4(b) lists out the relations of typical noise specification, gain, output rate and maximum input voltage of single end. Test conditions are external input signal short, voltage reference: 1.2V and 1024 records were sampled.

| ENOB(RMS) with OSR/GAIN at A/D Clock=250Khz, VDDA=2.4V, VREF=1.2V | | | | | | | | | | | | | |
|--|-----------------|---|-----|---|------|------|------|------|------|------|------|-------|-------|
| Max. Vin(mV) =0.9*VREF ⁽¹⁾ | OSR | | | | | 256 | 512 | 1024 | 2048 | 4096 | 8192 | 16384 | 32768 |
| | Output rate(HZ) | | | | | 977 | 488 | 244 | 122 | 61 | 31 | 15 | 8 |
| | Gain | = | PGA | x | ADGN | | | | | | | | |
| ±2400 | 0.25 | = | 1 | x | 0.25 | 16.3 | 17.4 | 17.9 | 18.5 | 19.0 | 19.5 | 20.0 | 20.4 |
| ±2160 | 0.5 | = | 1 | x | 0.5 | 16.3 | 17.3 | 17.9 | 18.4 | 18.9 | 19.4 | 19.8 | 20.2 |
| ±1080 | 1 | = | 1 | x | 1 | 16.2 | 17.2 | 17.8 | 18.3 | 18.8 | 19.3 | 19.7 | 20.1 |
| ±540 | 2 | = | 1 | x | 2 | 16.1 | 17.1 | 17.6 | 18.2 | 18.7 | 19.2 | 19.6 | 20.0 |
| ±270 | 4 | = | 1 | x | 4 | 16.0 | 16.9 | 17.5 | 18.0 | 18.5 | 18.9 | 19.4 | 19.8 |
| ±135 | 8 | = | 1 | x | 8 | 15.9 | 16.6 | 17.2 | 17.7 | 18.2 | 18.7 | 19.2 | 19.6 |
| ±68 | 16 | = | 1 | x | 16 | 15.6 | 16.3 | 16.8 | 17.3 | 17.7 | 18.3 | 18.8 | 19.3 |
| ±34 | 32 | = | 2 | x | 16 | 14.8 | 15.3 | 15.9 | 16.4 | 16.9 | 17.4 | 17.8 | 18.3 |
| ±17 | 64 | = | 4 | x | 16 | 14.5 | 15.0 | 15.5 | 16.0 | 16.5 | 17.0 | 17.5 | 18.0 |
| ±8 | 128 | = | 8 | x | 16 | 14.0 | 14.6 | 15.1 | 15.6 | 16.0 | 16.6 | 17.0 | 17.5 |

(1) Max.Vin (mV) is the max. input voltage of single end to ground (VSS).

Table 6.9-4(a) SD18 ENOB Table

| RMS Noise(uV) with OSR/GAIN at A/D Clock=250Khz, VDDA=2.4V, VREF=1.2V | | | | | | | | | | | | | |
|--|-----------------|---|-----|---|------|--------|-------|-------|-------|-------|-------|-------|-------|
| Max. Vin(mV) =0.9*VREF | OSR | | | | | 256 | 512 | 1024 | 2048 | 4096 | 8192 | 16384 | 32768 |
| | Output rate(HZ) | | | | | 977 | 488 | 244 | 122 | 61 | 31 | 15 | 8 |
| | Gain | = | PGA | x | ADGN | | | | | | | | |
| ±2400 | 0.25 | = | 1 | x | 0.25 | 121.08 | 57.40 | 38.74 | 26.66 | 18.39 | 13.21 | 9.49 | 6.98 |
| ±2160 | 0.5 | = | 1 | x | 0.5 | 61.63 | 29.23 | 19.21 | 13.51 | 9.78 | 7.02 | 5.12 | 3.91 |
| ±1080 | 1 | = | 1 | x | 1 | 32.21 | 15.70 | 10.25 | 7.31 | 5.19 | 3.77 | 2.80 | 2.13 |
| ±540 | 2 | = | 1 | x | 2 | 16.59 | 8.54 | 5.91 | 4.06 | 2.86 | 2.06 | 1.48 | 1.12 |
| ±270 | 4 | = | 1 | x | 4 | 9.00 | 4.84 | 3.33 | 2.37 | 1.67 | 1.19 | 0.87 | 0.65 |
| ±135 | 8 | = | 1 | x | 8 | 5.04 | 2.97 | 2.02 | 1.44 | 1.01 | 0.73 | 0.51 | 0.39 |
| ±68 | 16 | = | 1 | x | 16 | 3.03 | 1.84 | 1.29 | 0.92 | 0.70 | 0.46 | 0.33 | 0.24 |
| ±34 | 32 | = | 2 | x | 16 | 2.61 | 1.81 | 1.27 | 0.89 | 0.62 | 0.45 | 0.32 | 0.23 |
| ±17 | 64 | = | 4 | x | 16 | 1.66 | 1.13 | 0.80 | 0.56 | 0.41 | 0.29 | 0.20 | 0.14 |
| ±8 | 128 | = | 8 | x | 16 | 1.13 | 0.77 | 0.55 | 0.38 | 0.28 | 0.19 | 0.14 | 0.10 |

Table 6.9-4(b) SD18 RMS Noise Table

The RMS noise are referred to the input. The Effective Number of Bits (ENOB(RMS Bit)) is defined as :

$$\text{ENOB(RMS)} = \frac{\ln\left(\frac{\text{FSR}}{\text{RMS Noise}}\right)}{\ln(2)}$$

$$\text{RMS Noise} = \frac{\left(2 \times \text{VREF} \times \sqrt{\sum_{k=1}^{1024} (\text{ADO}[k] - \text{Average})^2}\right)}{2^{23}}$$

Where FSR (Full- Scale Range)= $2 \times \text{VREF}/\text{Gain}$.

$$\text{Average} = \frac{\sum_{k=1}^{1024} (\text{ADO}[k])}{1024}$$

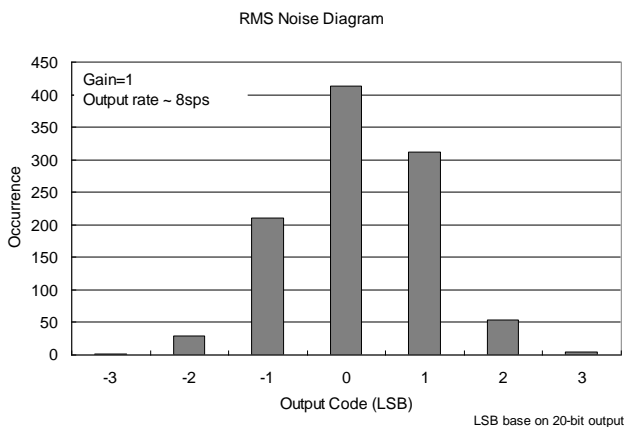


Figure 6.9-4(a) RMS Noise Diagram

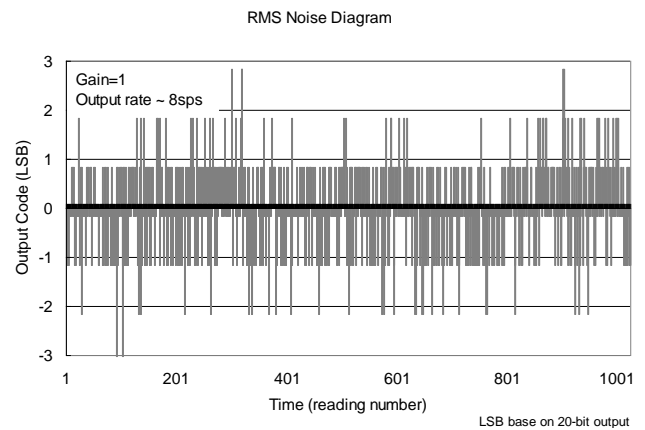


Figure 6.9-4(b) Output Code Diagram

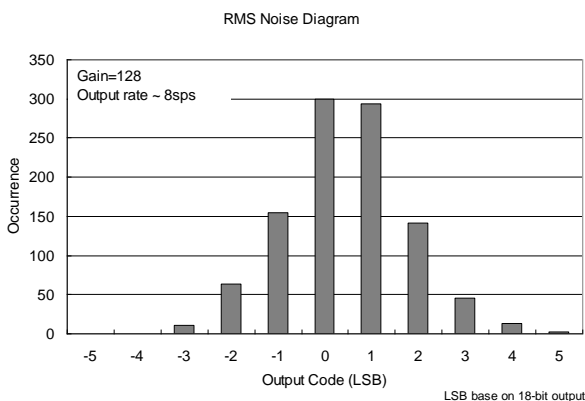


Figure 6.9-4(c) RMS Noise Diagram

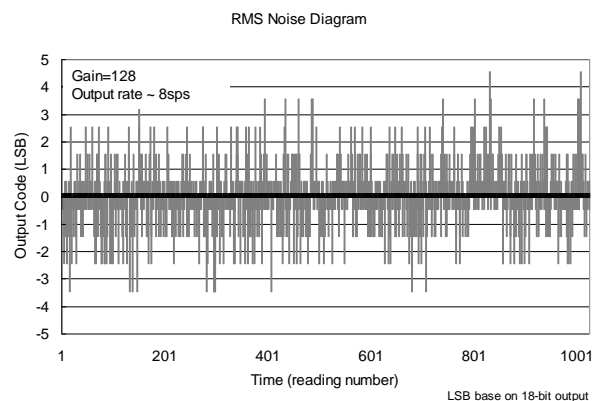


Figure 6.9-4(d) Output Code Diagram

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7. Ordering Information

| Device No. ¹ | Package Type | Pins | Package Drawing | | Code ² | Shipment Packing Type | Unit Q'ty | Material Composition | MSL ³ |
|-------------------------|--------------|------|-----------------|-----|-------------------|-----------------------|-----------|----------------------|------------------|
| | | | D | 000 | | | | | |
| HY11P13-D000 | Die | - | D | 000 | 000 | - | 100 | Green ⁴ | - |
| HY11P13-L064 | LQFP | 64 | L | 064 | 000 | Tray | 160 | Green ⁴ | MSL-3 |
| HY11P13-LS64 | LQFP | 64 | L | S64 | 000 | Tray | 250 | Green ⁴ | MSL-3 |

¹ **Device No. Model No. – Package Type Description – Code** (Blank Code/ Standard/ Customized Programming Code)

Ex: Your customized programming code is 008 and you require die shipment.

The device No. will be HY11P13-D000-008.

Ex: You request blank code in die package.

The device No. will be HY11P13-D000.

Ex: You request blank code in LQFP 64 package.

The device No. will be HY11P13-L064.

And please clearly indicate the shipment packing type when placing orders.

Ex: Your customized programming code is 009 and you require products in LQFP 64 package.

The device No. will be HY11P13-LS64-009.

And please clearly indicate the shipment packing type when placing orders.

² **Code**

“001”~ “999” is standard or customized programming code. Blank code does not have these numbers.

³ **MSL**

The Moisture Sensitivity Level ranking conforms to IPC/JEDEC J-STD-020 industry standard categorization. The products are processed, packed, transported and used with reference to IPC/JEDEC J-STD-033.

⁴ **Green (RoHS & no Cl/Br)**

HYCON products are Green products that are compliant with RoHS directive, SVHC under REACH and Halogen free.

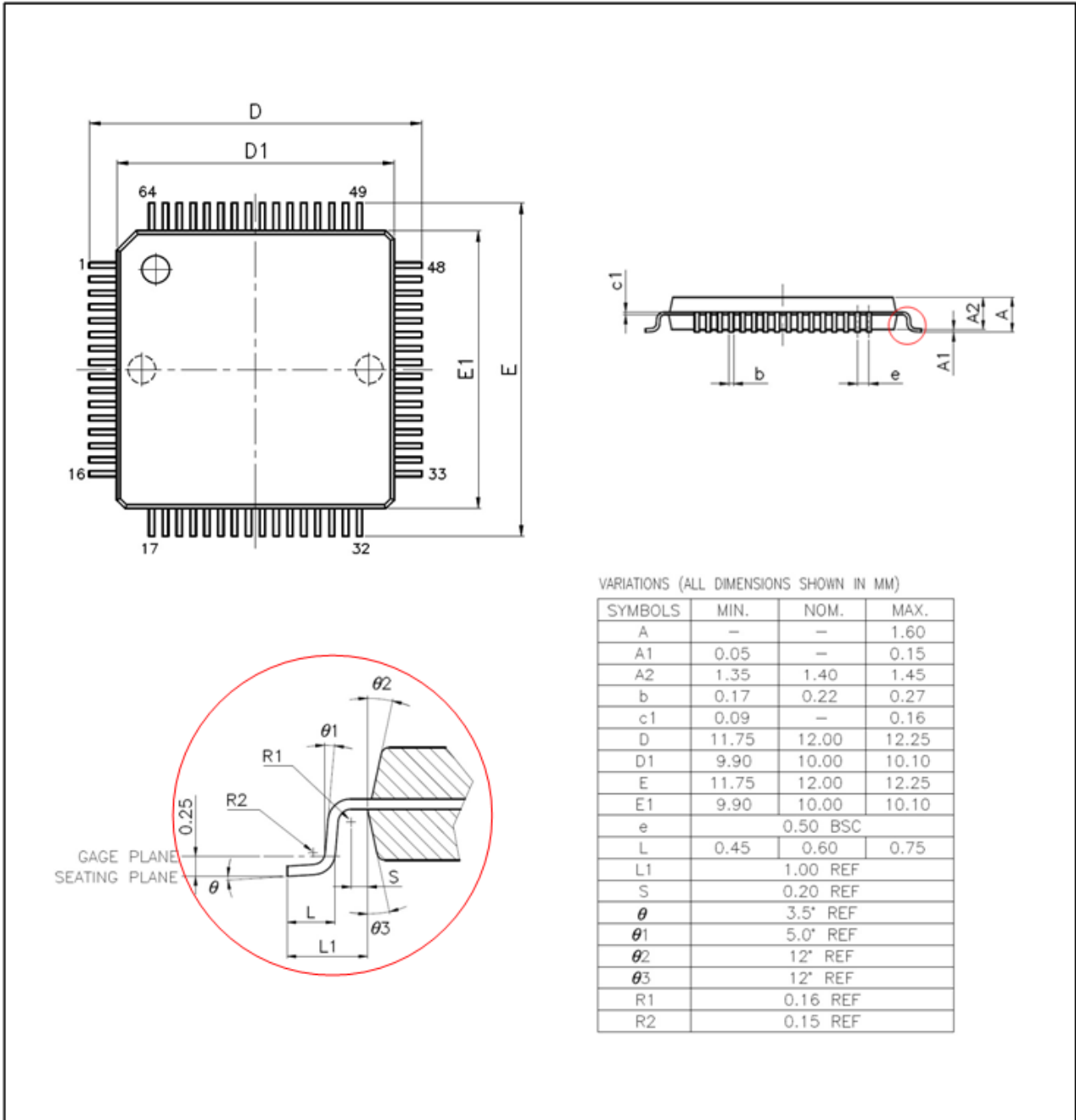
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8. Package Information

8.1. LQFP64 (L064)



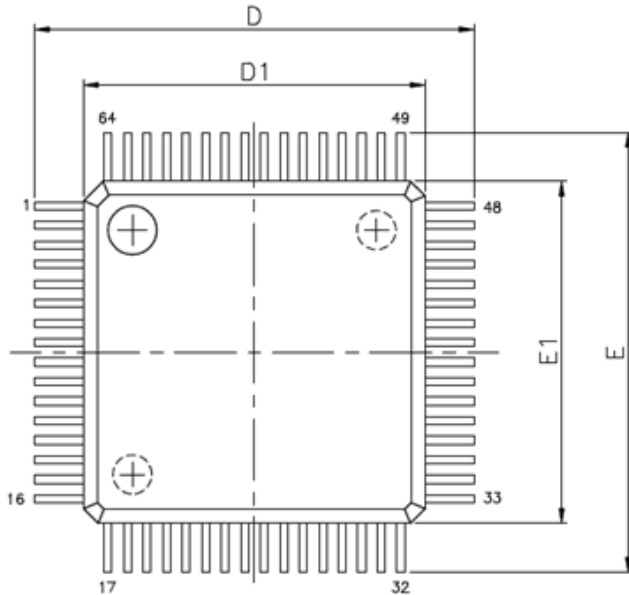
JEDEC MS-026 compliant

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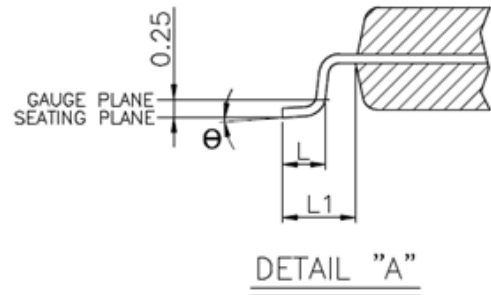
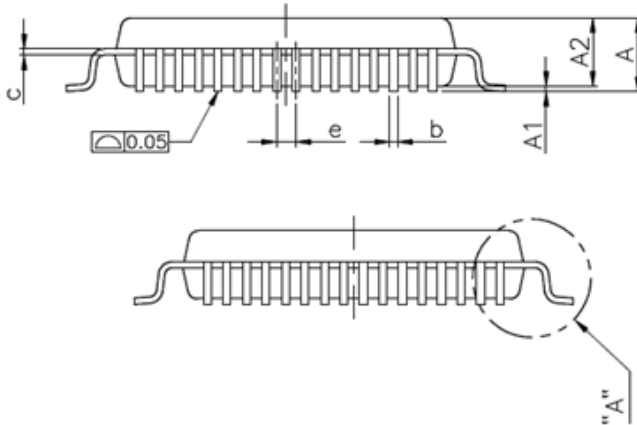


8.2. LQFP64(LS64)



VARIATIONS (ALL DIMENSIONS SHOWN IN MM)

| SYMBOLS | MIN. | NOM. | MAX. |
|----------|----------|------|------|
| A | — | — | 1.60 |
| A1 | 0.05 | — | 0.15 |
| A2 | 1.35 | 1.40 | 1.45 |
| b | 0.13 | 0.18 | 0.23 |
| c | 0.09 | — | 0.20 |
| D | 9.00 BSC | | |
| D1 | 7.00 BSC | | |
| e | 0.40 BSC | | |
| E | 9.00 BSC | | |
| E1 | 7.00 BSC | | |
| L | 0.45 | 0.60 | 0.75 |
| L1 | 1.00 REF | | |
| θ | 0° | 3.5° | 7° |



JEDEC MS-026 compliant

9. Revisions

The following describes the major changes made to the document, excluding the punctuation and font changes.

| Version | Page | Summary of Changes |
|---------|-------|--|
| V04 | ALL | First edition |
| V06 | | With reference to documentation: DS-HY11P13-V06_TC |
| | 4 | Features revision |
| | 6~8 | Table 2-1 Pin Definition and Function Description revision |
| | 8~13 | Chapter 3 Application Circuit revision |
| | 24~25 | Chapter 6.6 Power System revision |
| | 26 | Chapter 6.8 Low Noise OPAMP revision |
| | 28~30 | Chapter 6.9.2 SD18, Performance II revision |
| V07 | 15~16 | Chapter 5 Register List revision |
| V08 | 4 | Features revision |
| | 9~10 | Chapter 3.1 & 3.2 content revision |
| | 24~25 | Chapter 6.6 Power System revision |
| V09 | 1 | Cover Revised |
| | 5 | Feature revised, delete 1/2bias description |
| | 6 | Add in Note 3 description |
| | 10~14 | Revised application circuit, added in RC circuit of RST |
| | 15 | Revised Internal Block Diagram |
| V13 | 4 | Revise Chapter 1 content |
| | 10 | Revise Figure 3-2 |
| | 11 | Revise Figure 3-3 |
| | 15 | Revise Development Tool Related Operating Instruction serial |
| | 16 | numbers |
| | 19 | Add in SD18 Network chapter |
| | 26 | Revise Chapter 6 |
| | 28 | Revise temp. drift spec of power system |
| | 34~35 | Reduce LCD current spec. |
| | 36 | Add in the chapter of SD18 Noise Performance |
| | 38 | Chapter 7 Ordering information revision |
| | | Add in package information – 8.2 LQFP64(LS64) |
| V14 | 17 | Added in 4.4 Low Noise OPAMP Network |
| V15 | 5 | Add in Function List |
| | 10 | Update Package marker information |

HY11P13

Embedded 18-Bit $\Sigma\Delta$ ADC

8-Bit RISC-like Mixed Signal Microcontroller



38 Update Green (RoHS & no Cl/Br)