



HY11P42 Datasheet

**8-Bit RISC-like Mixed Signal Microcontroller
Embedded 18-Bit $\Sigma\Delta$ ADC**

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1. Features

- 8-bit RISC, 66 instructions included.
- Operating voltage range: 2.2V to 3.6V, operation temperature range: -40°C~85°C.
- External Crystal Oscillator and Internal High Precision RC Oscillator, 6 CPU clock rates enable users to have the most power-saving plan.
 - Active Mode 300uA@2MHz
 - Standby Mode 3uA@28KHz
 - Sleep Mode 1uA
- 2K Word OTP (One Time Programmable) Type program memory, 128 Byte Data Memory.
- Brownout detector and Watch dog Timer, prevents CPU from Crash.
- 18-bit fully differential input Sigma-Delta Analog-to-Digital Converter (A/D)
 - Built-in PGA (Programmable Gain Amplifier) 1/4x·1/2x·1x. ...128x·10 input signal gain selection.
 - Built-in Input zero point adjustment can increase measurement range according to different application.
 - Built-in high impedance input buffer (Not suitable for 4x or upwards input gain).
- ■ Built-in absolute temperature sensor
- 1.0V and 1.2V internal analog circuit common ground that equips with Push-Pull drive ability to provide sensor driving voltage.
- LVD low voltage detection function has 14 steps of voltage detection configuration and external input voltage detection function.
- VDDA can select 4 different output voltages that equip with 10mA low dropout regulator function.
- 8-bit Timer A
- 8-bit Timer C module can generate PWM/PFD waveform.
- EUART module.
- Built-In EPROM (BIE)
- Support 6 stack level

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2. Pin Definition

2.1 SSOP28 Pin Diagram

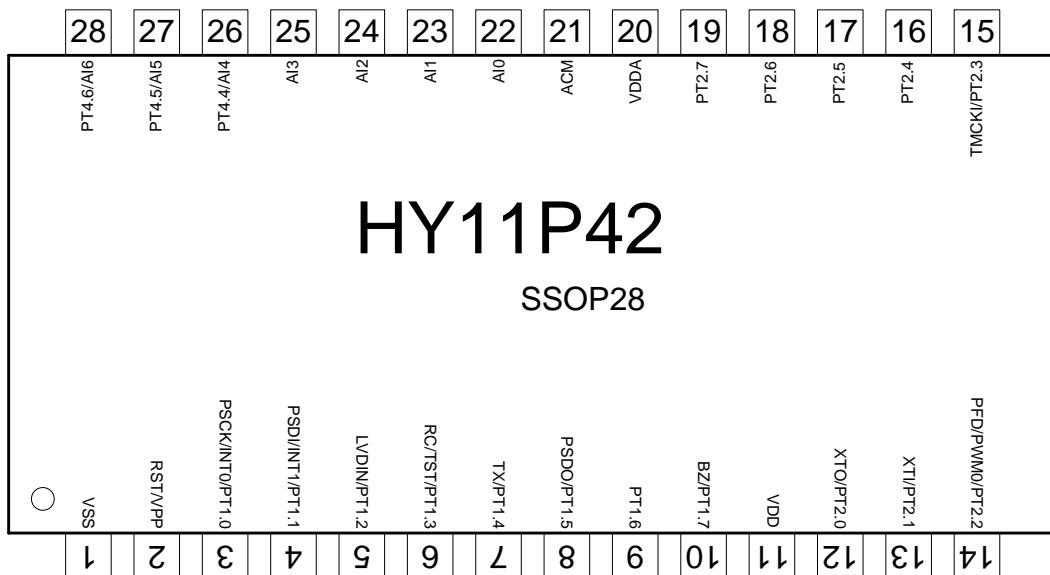


Figure 2-1 HY11P42 SSOP28 Pin Diagram

2.2 TSSOP28 Pin Diagram

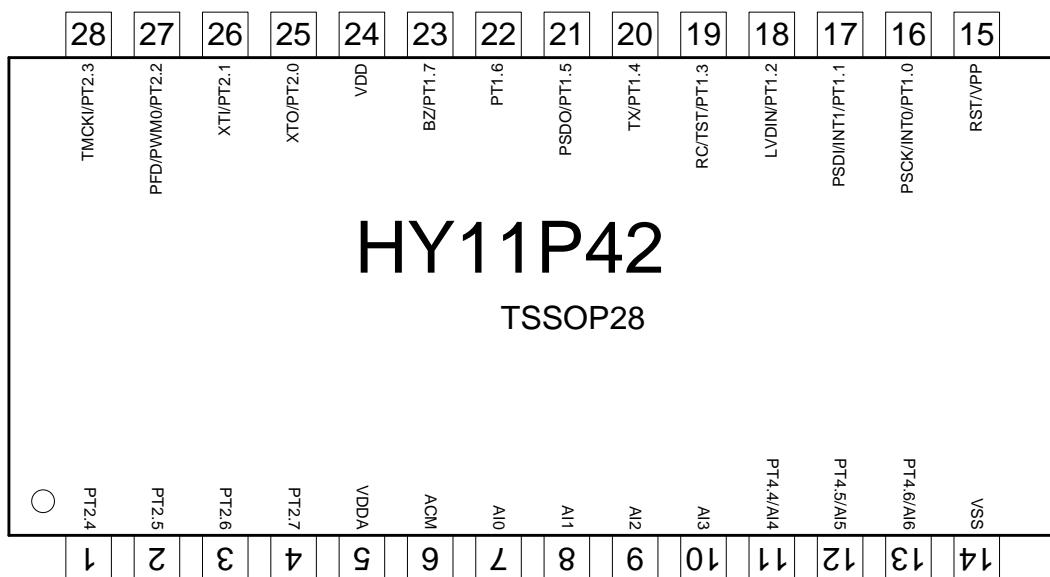


Figure 2-2 HY11P42 TSSOP28 Pin Diagram

Note 1 : VPP and RST use the same pin. Input voltage cannot exceed 5.8V when not programming EPROM.

Note 2 : TST and PT1.3 use the same pin. Input voltage cannot exceed Vdd+0.3V while operating.

Note 3 : If PT1.3 is not configured as external button pin, the anti-interference ability will be enhanced.

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2.3 QFN24 Pin Diagram

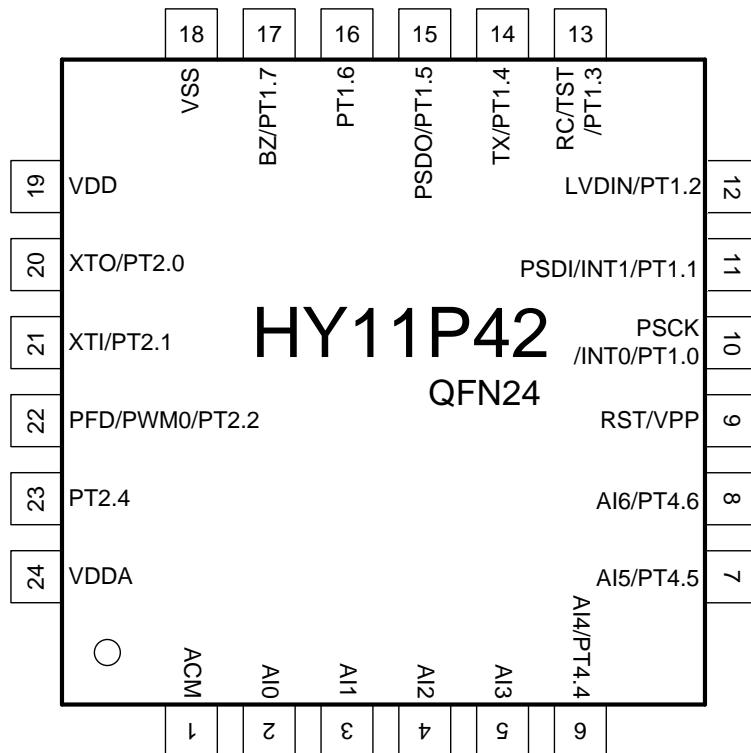


Figure 2-3 HY11P42 N-QFN24 Pin Diagram

Note 1 : VPP and RST use the same pin. Input voltage cannot exceed 5.8V when not programming EPROM.

Note 2 : TST and PT1.3 use the same pin. Input voltage cannot exceed Vdd+0.3V while operating.

Note 3 : If PT1.3 is not configured as external button pin, the anti-interference ability will be enhanced.

2.4 SSOP28 Pinout I/O Description

"I/O" input/output, "I" input, "O" output, "S" Smith Trigger, "C" CMOS features compatible input/output, "P" power supply, "A" analog channel

NO.	Pin Name	Pin characteristic		Description
		Pin Type	Buffer Type	
1	VSS	P	P	Grounding pin for IC operation voltage
2	RST/VPP	RST	I	Reset IC
		VPP	P	EPROM programming voltage input
3	PT1.0/INT0/PSCK	PT1.0	I	Digital input
		INT0	I	Interrupt input INT0
		PSCK	I	OTP programming interface SCK
4	PT1.1/INT1/PSDI	PT1.1	I	Digital input
		INT1	I	Interrupt input INT1
		PSDI	I	OTP programming interface SDI
5	PT1.2/LVDIN	PT1.2	I	Digital input
		LVDIN	A	LVD external signal input port
6	PT1.3/TST/RC	PT1.3	I	Digital input
		RC	I/O	EUART communication interface RC
		TST	I	Test Mode input pin (invalid)
7	PT1.4/TX	PT1.4	I/O	Digital I/O
		TX	I/O	EUART communication interface TX
8	PT1.5/PSDO	PT1.5	I/O	Digital I/O
		PSDO	I/O	OTP programming interface SDO
9	PT1.6	PT1.6	I/O	Digital I/O
10	PT1.7/BZ	PT1.7	I/O	Digital I/O
		BZ	O	Buzzer output
11	VDD	P	P	Power source for IC operation
12	PT2.0/XTO	PT2.0	I/O	Digital I/O

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	XTO	A	A	External oscillator output
13	PT2.1/XTI PT2.1 XTI	I/O A	S A	Digital I/O External oscillator input
14	PT2.2/PWM0/PFD PT2.2 PWM0 PFD	I/O O O	C C C	Digital I/O PWM output port PFD output port
15	PT2.3/TMCKI PT2.3 TMCKI	I/O I	S S	Digital I/O TIMERC clock source input port
16	PT2.4	I/O	S	Digital I/O
17	PT2.5	I/O	S	Digital I/O
18	PT2.6	I/O	C	Digital I/O
19	PT2.7	I/O	C	Digital I/O
20	VDDA	P	P	Regulator output Analog circuit voltage source
21	ACM	P	P	Internal analog circuit grounding pin
22	AI0	A	A	Analog input channel
23	AI1	A	A	Analog input channel
24	AI2	A	A	Analog input channel
25	AI3	A	A	Analog input channel
26	PT4.4/AI4 PT4.4 AI4	I A	C A	Digital input Analog input channel
27	PT4.5/AI5 PT4.5 AI5	I A	C A	Digital input Analog input channel
28	PT4.6/AI6 PT4.6 AI6	I A	C A	Digital input Analog input channel

Table 2-1 Pin Definition and Function Description

2.5 TSSOP28 Pin out I/O Description

"I/O" input/output, "I" input, "O" output, "S" Smith Trigger, "C" CMOS features compatible input/output, "P" power supply, "A" analog channel

NO.	Pin Name	Pin Characteristic		Description
		Pin Type	Buffer Type	
1	PT2.4	I/O	S	Digital I/O
2	PT2.5	I/O	S	Digital I/O
3	PT2.6	I/O	C	Digital I/O
4	PT2.7	I/O	C	Digital I/O
5	VDDA	P	P	Regulator output Analog circuit voltage source
6	ACM	P	P	Internal analog circuit grounding pin
7	AI0	A	A	Analog input channel
8	AI1	A	A	Analog input channel
9	AI2	A	A	Analog input channel
10	AI3	A	A	Analog input channel
11	PT4.4/AI4			
	PT4.4	I	C	Digital input
	AI4	A	A	Analog input channel
12	PT4.5/AI5			
	PT4.5	I	C	Digital input
	AI5	A	A	Analog input channel
13	PT4.6/AI6			
	PT4.6	I	C	Digital input
	AI6	A	A	Analog input channel
14	VSS	P	P	Grounding pin for IC operation voltage
15	RST/VPP			
	RST	I	S	Reset IC
	VPP	P	P	EPROM programming voltage input
16	PT1.0/INT0/PSCK			
	PT1.0	I	S	Digital input
	INT0	I	S	Interrupt input INT0
	PSCK	I	S	OTP programming interface SCK
17	PT1.1/INT1/PSDI			
	PT1.1	I	S	Digital input
	INT1	I	S	Interrupt input INT1
	PSDI	I	S	OTP programming interface SDI

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18	PT1.2/LVDIN PT1.2 LVDIN	I A	S A	Digital input LVD external signal input port
19	PT1.3/TST/RC PT1.3 RC TST	I I/O I	S S S	Digital input EUART communication interface RC Test Mode input pin (invalid)
20	PT1.4/TX PT1.4 TX	I/O I/O	S S	Digital I/O EUART communication interface TX
21	PT1.5/PSDO PT1.5 PSDO	I/O I/O	S C	Digital I/O OTP programming interface SDO
22	PT1.6 PT1.6	I/O	S	Digital I/O
23	PT1.7/BZ PT1.7 BZ	I/O O	S C	Digital I/O Buzzer output
24	VDD	P	P	Power source for IC operation
25	PT2.0/XTO PT2.0 XTO	I/O A	S A	Digital I/O External oscillator output
26	PT2.1/XTI PT2.1 XTI	I/O A	S A	Digital I/O External oscillator input
27	PT2.2/PWM0/PFD PT2.2 PWM0 PFD	I/O O O	C C C	Digital I/O PWM output port PFD output port
28	PT2.3/TMCKI PT2.3 TMCKI	I/O I	S S	Digital I/O TIMERC clock source input port

Table 2-2 Pin Definition and Function Description

2.6 QFN24 Pin out I/O Description

"I/O" input/output, "I" input, "O" output, "S" Smith Trigger, "C" CMOS features compatible input/output, "P" power supply, "A" analog channel

NO.	Pin Name	Pin Characteristic		Description
		Pin Type	Buffer Type	
1	ACM	P	P	Internal analog circuit grounding pin
2	AI0	A	A	Analog input channel
3	AI1	A	A	Analog input channel
4	AI2	A	A	Analog input channel
5	AI3	A	A	Analog input channel
6	PT4.4/AI4	PT4.4 AI4	I A	Digital input Analog input channel
7	PT4.5/AI5			
8	PT4.6/AI6	PT4.6 AI6	I A	Digital input Analog input channel
9	RST/VPP			
	RST	I	S	Reset IC
	VPP	P	P	EPROM programming voltage input
10	PT1.0/INT0/PSCK	PT1.0 INT0 PSCK	I	Digital input Interrupt input INT0 OTP programming interface SCK
11	PT1.1/INT1/PSDI			
	PT1.1			
	INT1			
	PSDI			
12	PT1.2/LVDIN	PT1.2 LVDIN	I A	Digital input LVDIN external signal input port
13	PT1.3/TST/RC	PT1.3 RC TST	I/O S S	Digital input EUART communication interface RC Test Mode input pin (invalid)
14	PT1.4/TX			

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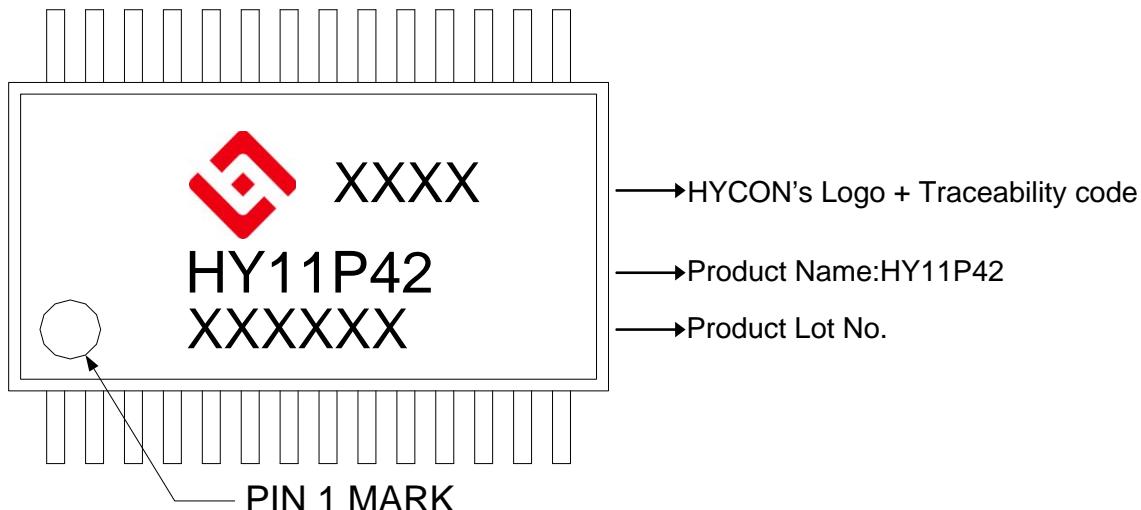
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	PT1.4 TX	I/O I/O	S S	Digital I/O EUART communication interface TX
15	PT1.5/PSDO PT1.5 PSDO	I/O I/O	S C	Digital I/O OTP programming interface SDO
16	PT1.6 PT1.6	I/O	S	Digital I/O
17	PT1.7/BZ PT1.7 BZ	I/O O	S C	Digital I/O Buzzer output
18	VSS	P	P	Grounding pin for IC operation voltage
19	VDD	P	P	Power source for IC operation
20	PT2.0/XTO PT2.0 XTO	I/O A	S A	Digital I/O External oscillator output
21	PT2.1/XTI PT2.1 XTI	I/O A	S A	Digital I/O External oscillator input
22	PT2.2/PWM0/PFD PT2.2 PWM0 PFD	I/O O O	C C C	Digital I/O PWM output port PFD output port
23	PT2.4	I/O	S	Digital I/O
24	VDDA	P	P	Regulator output Analog circuit voltage source

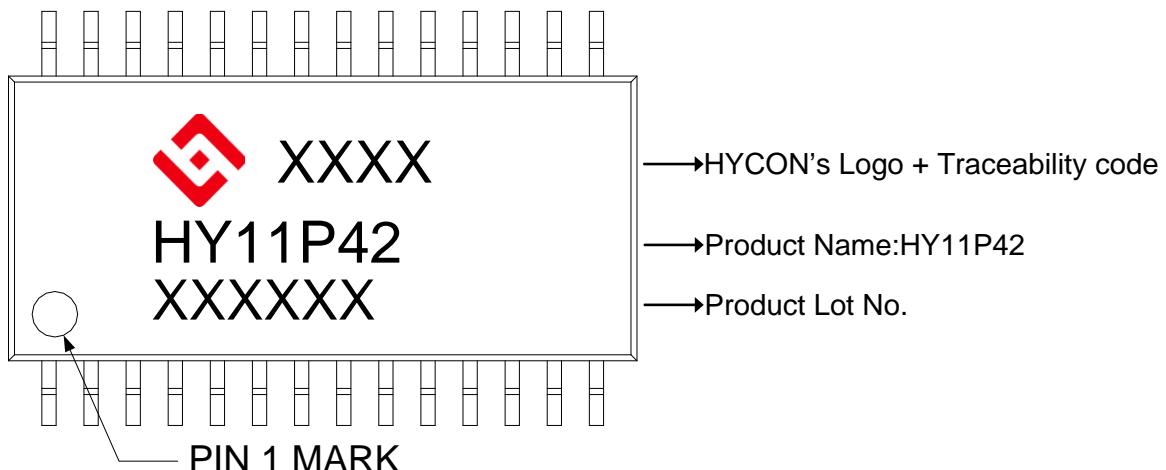
Table 2-3 Pin Definition and Function Description

2.7 Package marking information

2.7.1 SSOP28 Package marking information



2.7.2 TSSOP28 Package marking information



2.7.3 QFN24 Package marking information



→ HYCON's Logo + Traceability code

→ Product Name: HY11P42

→ Product Lot No.

3. Application Circuit

3.1 Bridge Sensor I

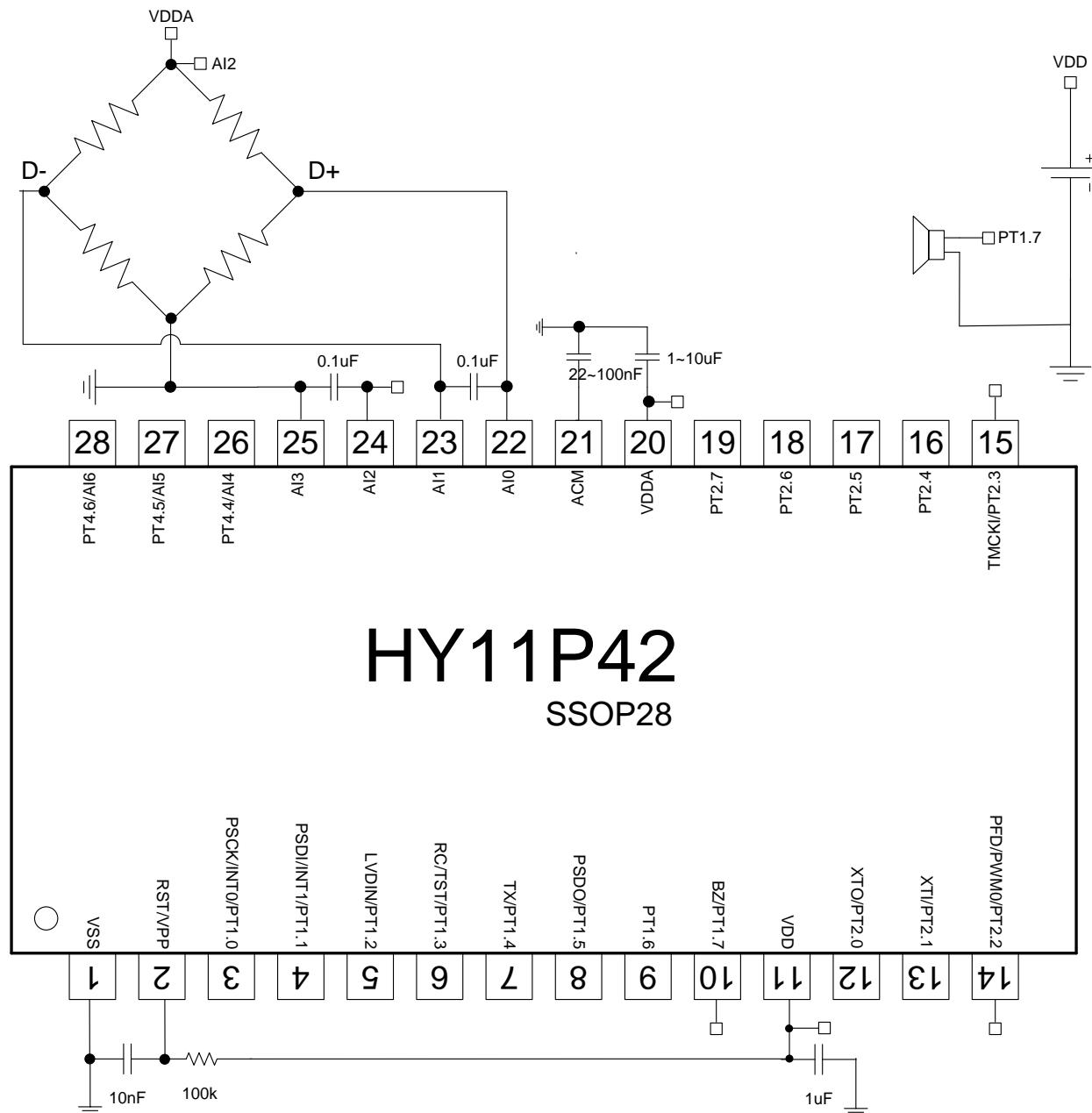


Figure 3-1 Application Circuit for Bridge Sensors

Note 1: DCSET[2:0] can conduct bias adjustment of Load Cell zero point voltage address

Note 2: BIE function can be used to save calibration parameters.

3.2 Bridge Sensor II

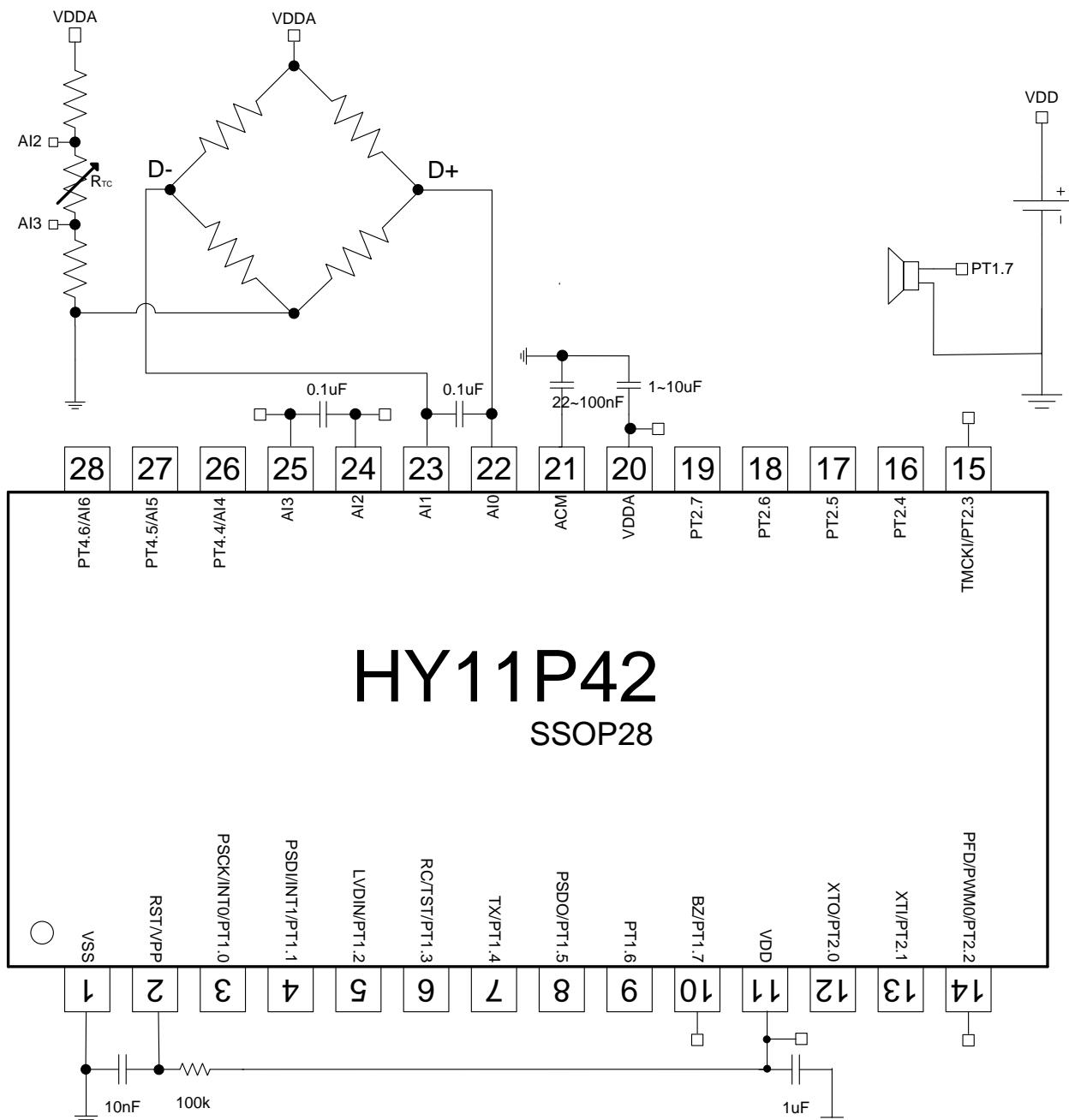


Figure 3-2 Application Circuit of Temperature Compensation Bridge Sensor

Note 1: Using external reference voltage to design temperature compensation resistor NTC basic circuit

Note 2: DCSET[2:0] can conduct bias adjustment of Load Cell zero point voltage address

Note 3: BIE function can be used to save calibration parameters.

3.3 4-20mA Two-Wire Current Panel Meter

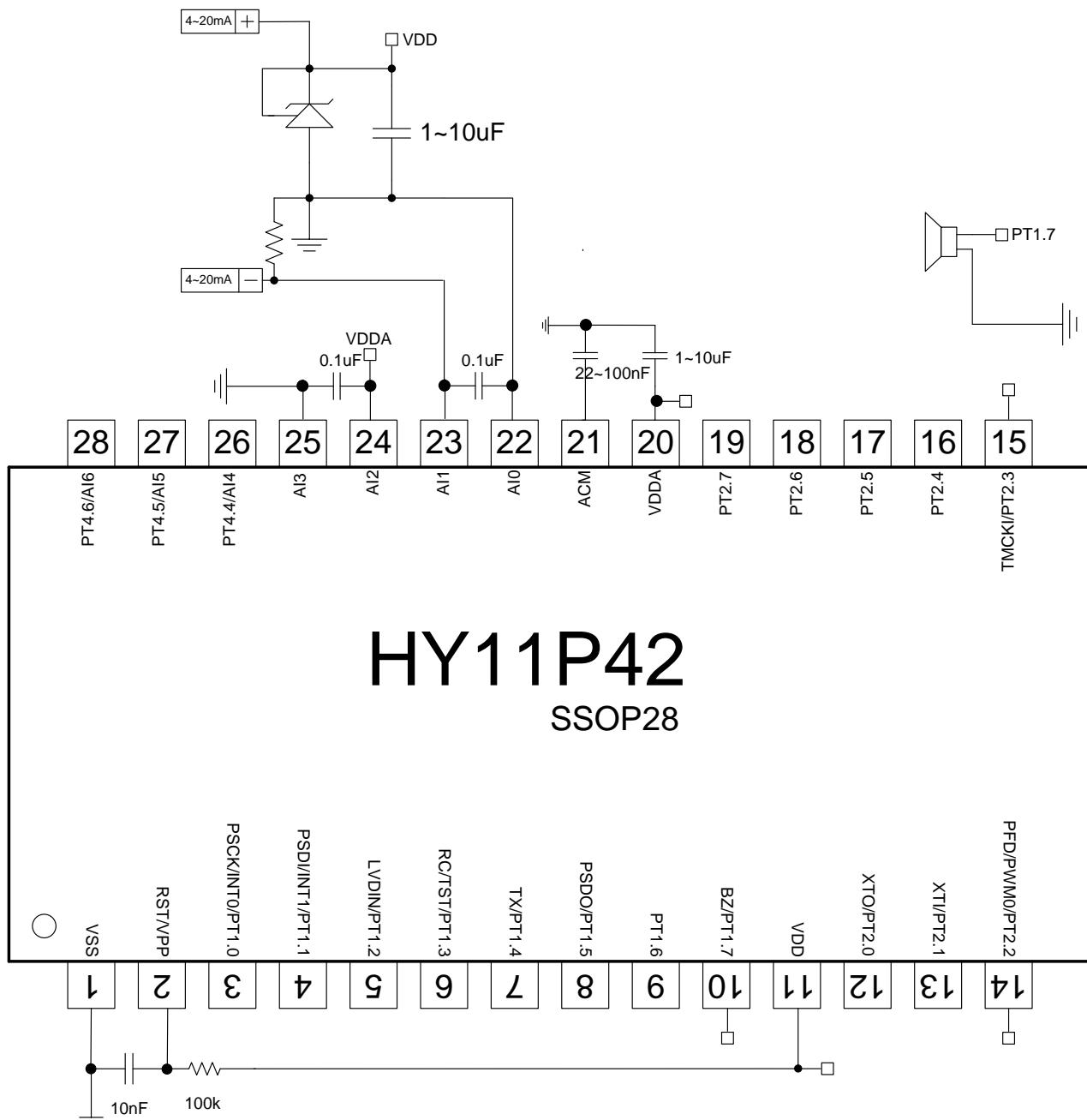


Figure 3-3 4-20mA Panel Meter that Unneeded to Connect External Power Supply

Note 1: DCSET[2:0] can carry out bias adjustment of Load Cell zero point voltage address

Note 2: BIE function can be used to save calibration parameters.

4. Function Outline

4.1 Internal Block Diagram

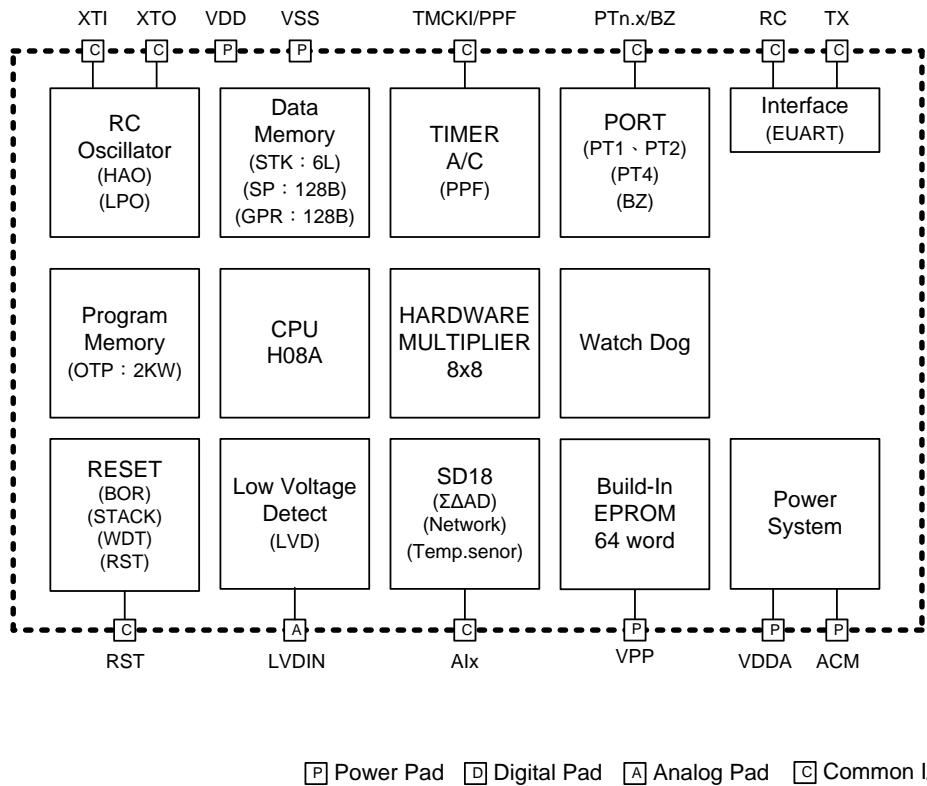


Figure 4-1 HY11P42 Internal Block Diagram

4.2 Related Description and Supporting Documents

IC Function Related Operating Instruction

DS-HY11P42-Vxx	HY11P42 Data Sheet
UG-HY11S14-Vxx	HY11P Series Users' Manual
APD-CORE002-Vxx	H08A Instruction Description

Development Tool Related Operating Instruction

APD-HYIDE006-Vxx	HY11xxx Series Development Tool Software Instruction Manual
APD-HYIDE005-Vxx	HY11xxx Series Development Tool Hardware Instruction Manual
APD-OTP001-Vxx	OTP Products Programming Pin Manual Product

Production Related Operating Instruction

APD-HYIDE004-Vxx	HY1xxxx Series Production Line Specialized Programmer Manual
BDI-HY11P42-Vxx	HY11P42 Individual Product Die Bonding Information

4.3 SD18 Network

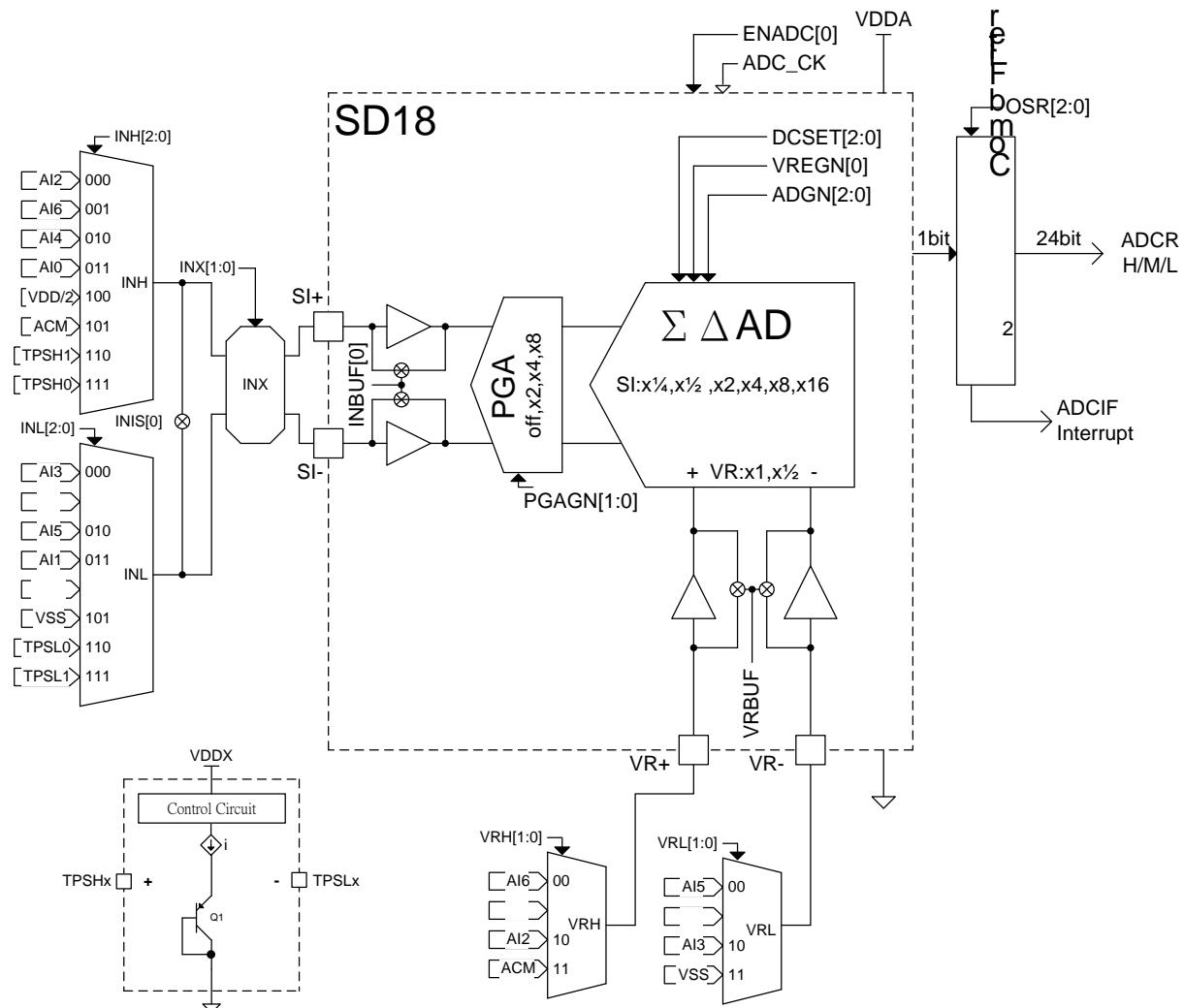


Figure 4-2 SD18 Network

5. Register List

Table 5-1 HY11P42 Register List

6. Electrical Characteristics

Absolute maximum ratings over operating free-air temperature (unless otherwise noted)

Voltage applied at V_{DD} to V_{SS}	-0.2 V to 4.0 V
Voltage applied to any pin	-0.2 V to V_{DD} + 0.3 V
Voltage applied to RST/VPP pin	-0.2 V to 6.9 V
Voltage applied to TST/PT1.3 pin	-0.2 V to V_{DD} + 1 V
Diode current at any device terminal	± 2 mA
Storage temperature, Tstg: (unprogrammed device)	-55°C to 150°C
(programmed device)	-40°C to 85°C
Total power dissipation.....	0.5w
Maximum output current sink by any PORT1 to PORT3 I/O pin.....	.25mA

6.1 Recommended operating conditions

$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$, unless otherwise noted

Sym.	Parameter		Test Conditions		Min.	Typ.	Max.	unit	
V_{DD}	Supply Voltage		All digital peripherals and CPU		2.2	3.6	3.6	V	
			Analog peripherals		2.4	3.6	3.6		
V_{SS}	Supply Voltage				0	0	0		
XT	External	Watch crystal	$V_{DD} = 2.2\text{V}, ENXT[0]=1$	XTSP[0]=0, XTHSP[0]=0	32.768K			Hz	
	Oscillator	Ceramic resonator		XTSP[0]=1, XTHSP[0]=0	450K				
	Frequency	Crystal		XTSP[0]=1, XTHSP[0]=0	1M				

6.2 Internal RC Oscillator

$T_A = 25^\circ C, V_{DD} = 3.0V$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
HAO	High Speed Oscillator frequency	$ENHAO[0]=1$	1.7	2.0	2.3	MHz
LPO	Low Power Oscillator frequency	V_{DD} supply voltage be enable LPO	22	28	35	KHz

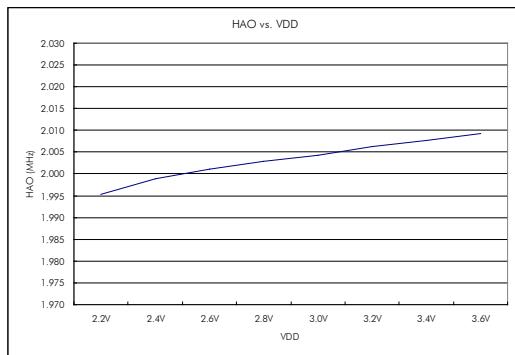


Figure 6.2-1 HAO vs. VDD

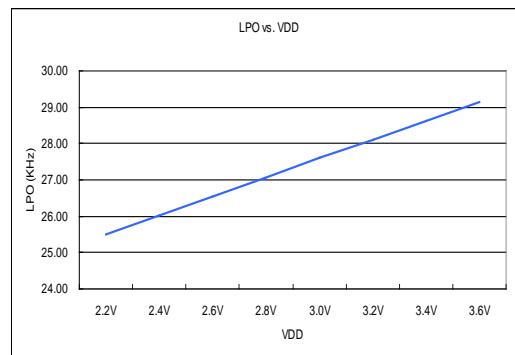


Figure 6.2-2 LPO vs. VDD

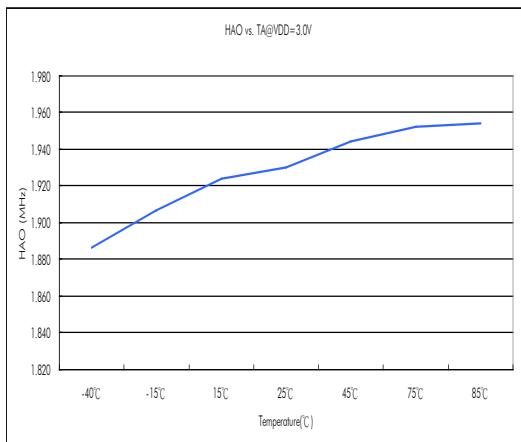


Figure 6.2-3 HAO vs. Temperature

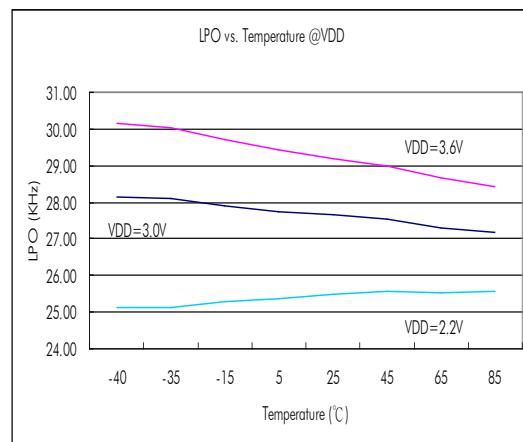


Figure 6.2-4 LPO vs. Temperature

6.3 Supply current into VDD excluding peripherals current

$T_A = 25^\circ\text{C}$, $V_{DD} = 3.0\text{V}$, $\text{OSC_LPO} = 28\text{KHz}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
I_{AM1}	Active mode 1	$\text{OSC_CY} = 8\text{MHz}$, $\text{OSC_HAO} = \text{off}$, $\text{CPU_CK} = 8\text{MHz}$		1.2	2	mA
I_{AM2}	Active mode 2	$\text{OSC_CY} = \text{off}$, $\text{OSC_HAO} = 2\text{MHz}$, $\text{CPU_CK} = 2\text{MHz}$		0.32	0.55	mA
I_{AM3}	Active mode 3	$\text{OSC_CY} = \text{off}$, $\text{OSC_HAO} = 2\text{MHz}$, $\text{CPU_CK} = 1\text{MHz}$		0.18	0.3	mA
I_{LP1}	Low Power 1	$\text{OSC_CY} = 32768\text{Hz}$, $\text{OSC_HAO} = \text{off}$, $\text{CPU_CK} = 16384\text{Hz}$		7	12	uA
I_{LP2}	Low Power 2	$\text{OSC_CY} = \text{off}$, $\text{OSC_HAO} = \text{off}$, $\text{CPU_CK} = \text{LPO}$, Idle state		1.65	3	uA
I_{LP3}	Low Power 3	$\text{OSC_CY} = \text{off}$, $\text{OSC_HAO} = \text{off}$, $\text{CPU_CK} = \text{off}$, Sleep state		0.65	1.2	uA

OSC_CY : External Oscillator frequency.

OSC_HAO : Internal High Accuracy Oscillator frequency.

CPU_CK : CPU core work frequency.

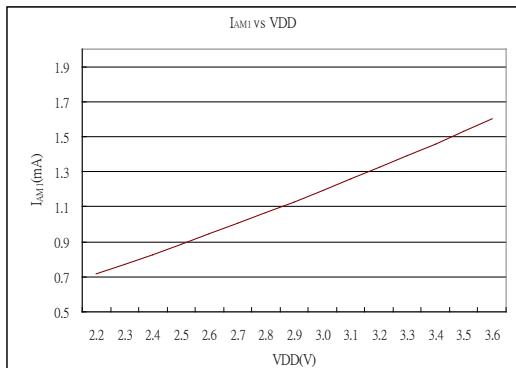


Figure 6.3-1 I_{AM1} vs. VDD

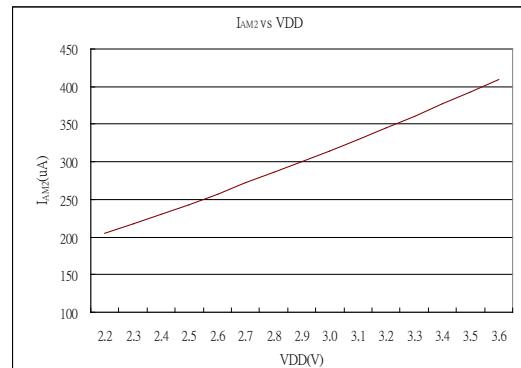


Figure 6.3-2 I_{AM2} vs. VDD

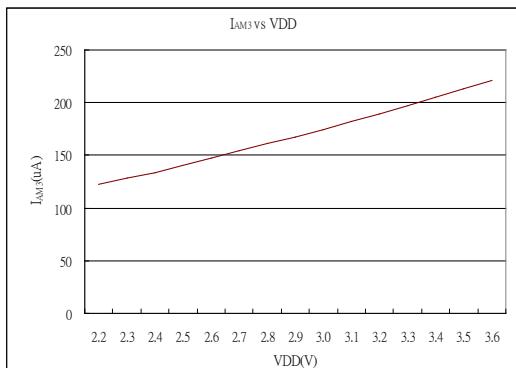


Figure 6.3-3 I_{AM3} vs. VDD

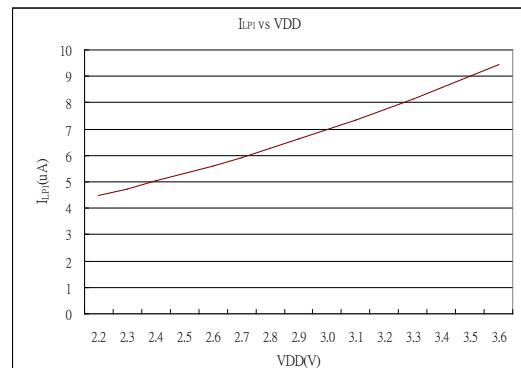
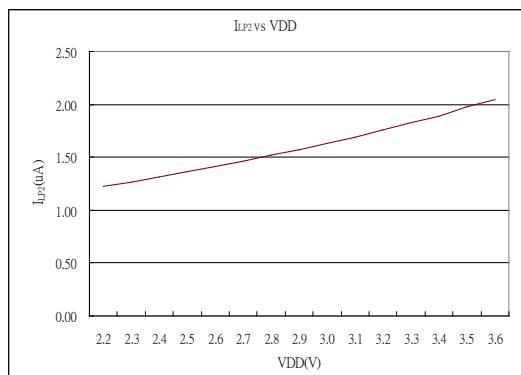
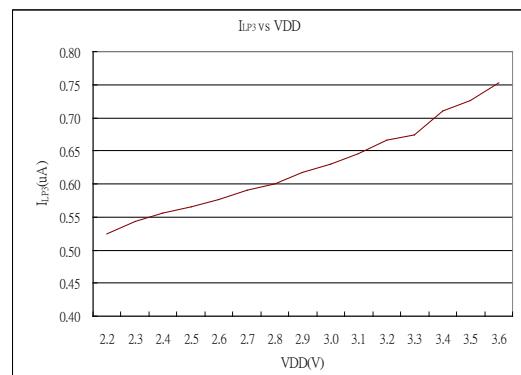
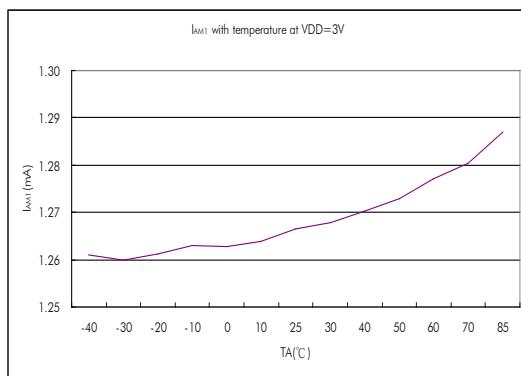
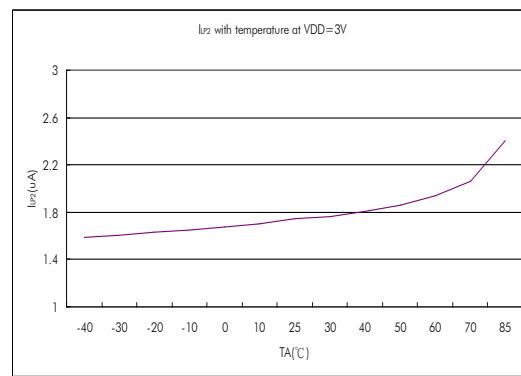
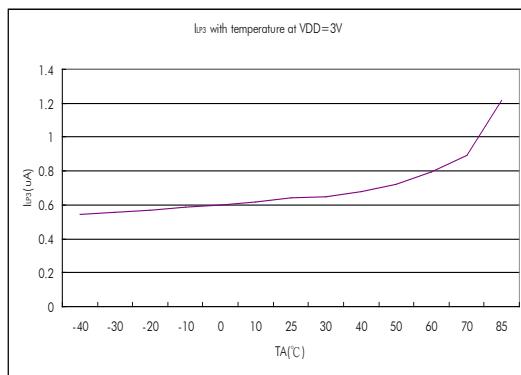


Figure 6.3-4 I_{LP1} vs. VDD

Figure 6.3-5 I_{LP2} vs. VDDFigure 6.3-6 I_{LP3} vs. VDDFigure 6.3-7 I_{AM1} vs. TemperatureFigure 6.3-8 I_{LP2} vs. TemperatureFigure 6.3-9 I_{LP3} vs. Temperature

6.4 Port1~5

$T_A = 25^\circ C, V_{DD} = 3.0V$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
Input voltage and Schmitt trigger and leakage current and timing						
V_{IH}	High-Level input voltage		2.1			V
V_{IL}	Low-Level input voltage		0.9			
V_{hys}	Input Voltage hysteresis($V_{IH} - V_{IL}$)		0.8			V
I_{LKG}	Leakage Current		0.1			uA
R_{PU}	Port pull high resistance		180			k Ω
Output voltage and current and frequency						
V_{OH}	High-level output voltage	$I_{OH}=10mA$	$V_{DD} - 0.3$			V
V_{OL}	Low-level output voltage	$I_{OL}=-10mA$				

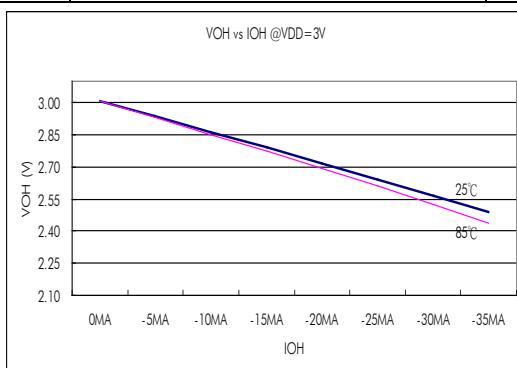


Figure 6.4-1 V_{OH} vs. I_{OH} @ $VDD=3.0V$

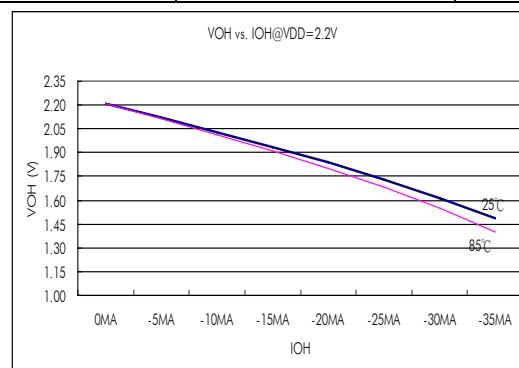


Figure 6.4-2 V_{OH} vs. I_{OH} @ $VDD=2.2V$

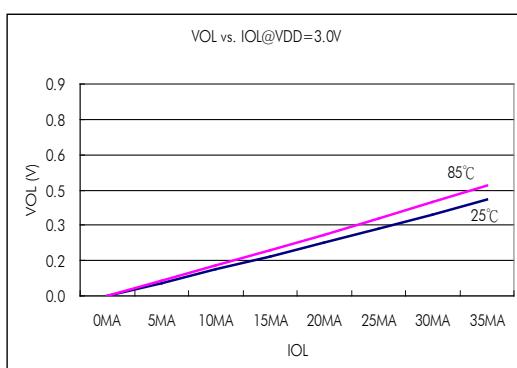


Figure 6.4-3 V_{OL} vs. I_{OL} @ $VDD=3.0V$

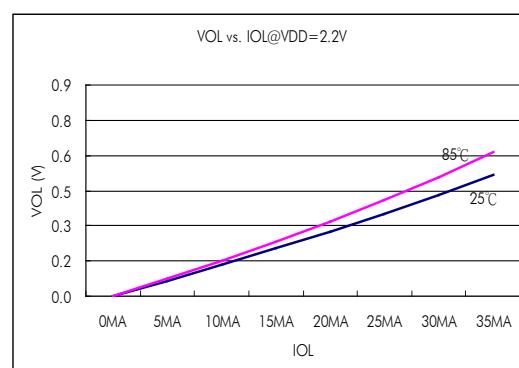


Figure 6.4-4 V_{OL} vs. I_{OL} @ $VDD=2.2V$

6.5 Reset (Brownout, External RST pin, Low Voltage Detect)

$T_A = 25^\circ C, V_{DD} = 3.0V$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
BOR	Pulse length needed to accepted reset internally, t_{d-LVR}		2			us
	V_{DD} Start Voltage to accepted reset internally ($L \rightarrow H$), V_{LVR}		1.6	1.85	2.1	V
	Hysteresis, $V_{HYS-LVR}$		70			mV
RST	Pulse length needed as RST/VPP pin to accepted reset internally, t_{d-RST}		2			us
	Input Voltage to accepted reset internally		0.9			V
	Hysteresis, $V_{HYS-RST}$		0.8			V
LVD	Operation current, I_{LVD}		10	15		uA
	External input voltage to compare reference voltage		1.2			V
	Compare reference voltage temperature drift	$T_A = -40^\circ C \sim 85^\circ C$	100			ppm/ $^\circ C$
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1110b$		3.3			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1101b$		3.2			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1100b$		3.1			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1011b$		3.0			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1010b$		2.9			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1001b$		2.8			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=1000b$		2.7			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0111b$		2.6			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0110b$		2.5			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0101b$		2.4			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0100b$		2.3			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0011b$		2.2			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0010b$		2.1			
	Detect V_{DD} voltage rang by user option, $V_{SVS} VLDx[3:0]=0001b$		2.0			
BOR : Brownout Reset						
LVR : Low Voltage Reset of BOR						
LVD : Low Voltage Detect						
RST : External Reset pin						

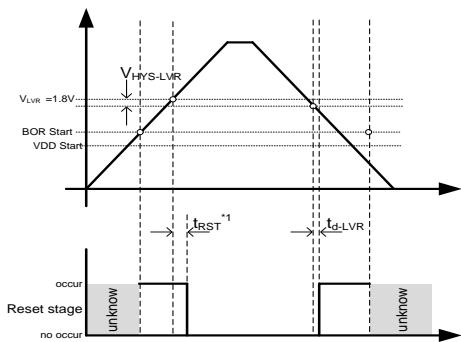


Figure 6.5-1 BOR Reset diagram

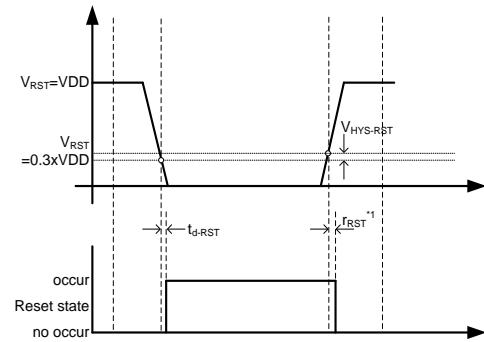


Figure 6.5-2 RST Reset diagram

*¹ t_{RST} : Please see BOR Introduce of HY11Pxx series User's Guide (UG-HY11S14-Vxx).

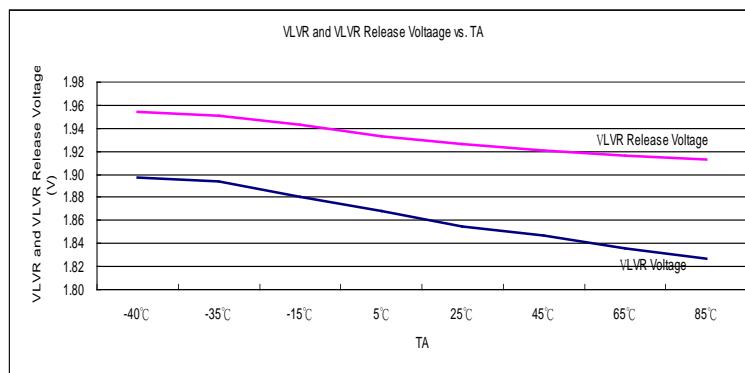


Figure 6.5-3 LVR vs. Temperature

6.6 Power System

$T_A = 25^\circ\text{C}$, $V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
VDDA	VDDA operation current, I_{VDDA}	$I_L = 0\text{mA}$		$VDDAX[1:0]=00b$		22	uA
	Select VDDA output voltage	$I_L = 0.1\text{mA}$, $VDD \geq VDDA + 0.2\text{V}$	$VDDAX[1:0]=00b$		3.3		V
			$VDDAX[1:0]=01b$		2.9		V
			$VDDAX[1:0]=10b$		2.6		V
			$VDDAX[1:0]=11b$		2.4		V
	Dropout voltage	$I_L = 10\text{mA}$	$VDDAX[1:0]=00b$		135		mV
			$VDDAX[1:0]=01b$		150		mV
			$VDDAX[1:0]=10b$		165		mV
			$VDDAX[1:0]=11b$		180		mV
	Temperature drift	$VDDAX[1:0]=11b$		$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$		50	ppm/ $^\circ\text{C}$
	V_{DD} Voltage drift	$I_L = 0.1\text{mA}$		$V_{DD}=2.5\text{V} \sim 3.6\text{V}$		± 0.2	%/V
ACM	ACM operation current, I_{ACM}	$I_L = 0\text{mA}$		20		uA	
	Output voltage, V_{ACM}	ENACM[0]=1, *1	$I_L = 0\text{uA}$		1.0		V
	Output voltage with Load		$I_L = \pm 200\text{uA}$		0.98	1.02	V_{ACM}
	Output voltage, V_{ACM}	ENACM[0]=1, *2	$I_L = 0\text{uA}$		1.2		V
	Output voltage with Load		$I_L = \pm 200\text{uA}$		0.98	1.02	V_{ACM}
	Temperature drift	ENACM[0]=1, $I_L = 10\text{uA}$	$T_A = -40^\circ\text{C} \sim 85^\circ\text{C}$		50		ppm/ $^\circ\text{C}$
	VDDA Voltage drift				100		uV/V

VDDA : Adjust Voltage Regulator

ACM : Analog Common Mode Voltage

*1: $V_{ACM} = 1.0\text{V}$ is just for $VDDAX[1:0]=1xb$ mode. (at A/D differential voltage reference < 1.4V)

*2: $V_{ACM} = 1.2\text{V}$ is just for $VDDAX[1:0]=0xb$ mode. (at A/D differential voltage reference > 1.4V)

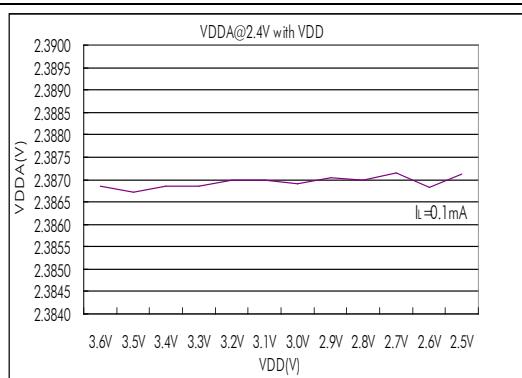


Figure 6.6-1 VDDA $I_L=0.1\text{mA}$ vs. VDD

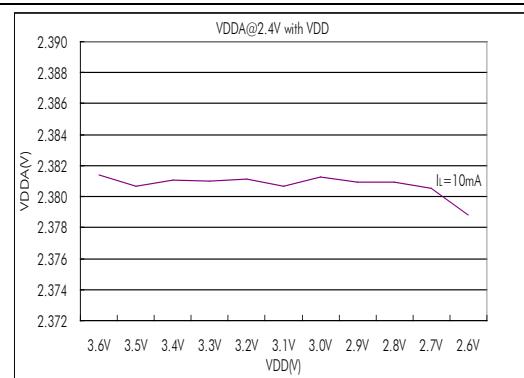


Figure 6.6-2 VDDA $I_L=10\text{mA}$ vs. VDD

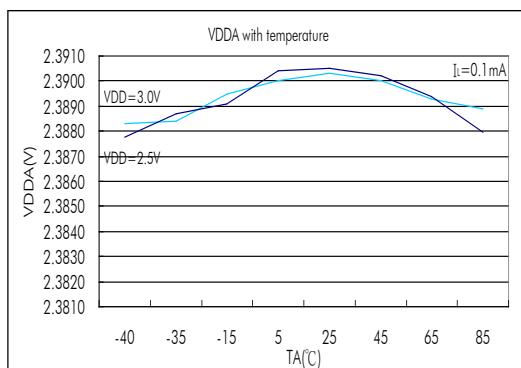


Figure 6.6-3 VDDA $I_L=0.1\text{mA}$ vs. Temperature

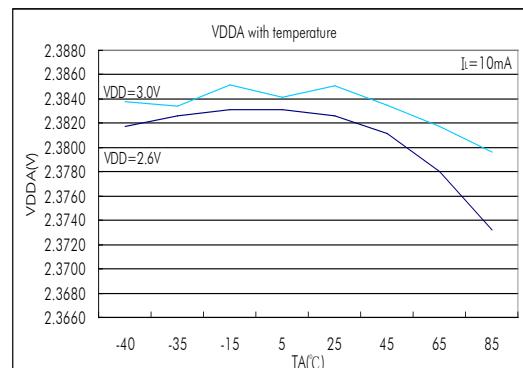


Figure 6.6-4 VDDA $I_L=10\text{mA}$ vs. Temperature

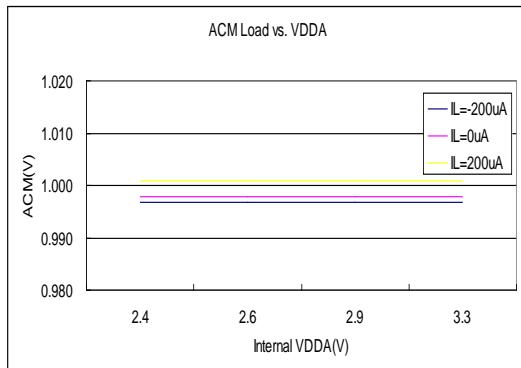


Figure 6.6-5 ACM Load vs. VDDA (a)

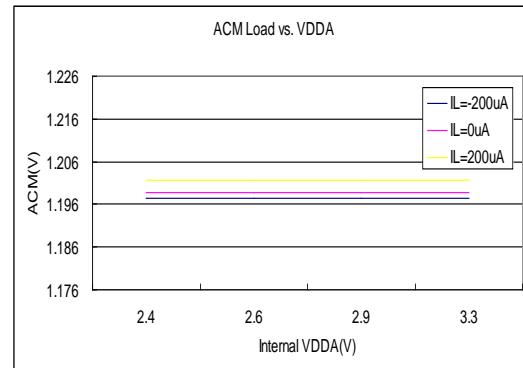


Figure 6.6-5 ACM Load vs. VDDA (b)

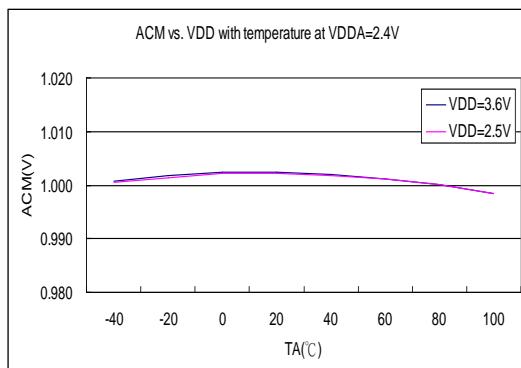


Figure 6.6-6 ACM vs. Temperature (a)

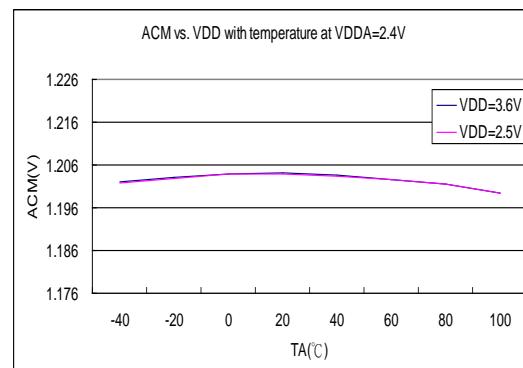


Figure 6.6-6 ACM vs. Temperature (b)

6.7 SD18, Power Supply and Recommended Operating Conditions

$T_A = 25^\circ C$, $V_{DD} = 3.0V$, $VDDA=2.4V$, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit		
V_{SD18}	Supply Voltage at VDDA	$ENVDDA[0]=0$		2.4	3.6		V		
f_{SD18}	Modulator sample frequency, ADC_CK			25	250	300	KHz		
	Over Sample Ratio, OSR			256	32768				
I_{SD18}	Operation supply current without PGA	ENADC[0]=1 INBUF[0]=1,VRBUF[0]=0		168			uA		
		ENADC[0]=1 INBUF[0]=0,VRBUF[0]=1		150					
		ENADC[0]=1 INBUF[0]=0,VRBUF[0]=0		120					

6.7.1 PGA, Power Supply and Recommended Operating Conditions

$T_A = 25^\circ C$, $V_{DD} = 3.0V$, $VDDA=2.4V$, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit
V_{PGA}	Supply Voltage at VDDA	$ENVDDA[0]=0$		2.4	3.6		V
I_{PGA}	Operation supply current	$PGAGN[1:0]=<01>$ or $<1x>$			320		uA
G_{PGA}	Gain temperature drift	$T_A = -40^\circ C \sim 85^\circ C$	GAIN=128			5	ppm/ $^\circ C$

6.7.2 SD18, Performance II ($f_{SD18}=250KHz$)

$T_A = 25^\circ C$, $V_{DD} = 3.0V$, $VDDA=2.9V$, $V_{VR}=1.0V$, $GAIN=1$ without PGA, unless otherwise noted

Sym.	Parameter	Test Conditions		Min.	Typ.	Max.	unit				
INL	Integral Nonlinearity(INL)	$VDDA=2.4V, V_{VR}=1.0V, \Delta SI=\pm 200mV$		± 0.003		± 0.01	%FSR				
		$VDDA=2.4V, V_{VR}=1.0V, \Delta SI=\pm 450mV$									
	No Missing Codes ³	$ADC_CK=250KHz, OSR[2:0]=010b$		23			Bits				
G_{SD18}	Temperature drift Gain 1~x16 (INBUF[0]=0b,) Gain 1~x4 (INBUF[0]=1b,)	INBUF[0]=0b,VRBUF[0]=0b		$T_A = -40^\circ C \sim 85^\circ C$	2	ppm/ $^\circ C$					
		INBUF[0]=1b,VRBUF[0]=0b									
		INBUF[0]=0b,VRBUF[0]=1b									
		INBUF[0]=1b,VRBUF[0]=1b									
E_{OS}	Offset error of Full Scale Rang input voltage range with Chopper and Buffer(INBUF,VRBUF)	$\Delta AI=0V$ $\Delta VR=0.9V$ $DCSET[2:0]=<000>$		Gain=2	1		%FSR				
	Offset error of Full Scale Rang input voltage range with Chopper without Buffer(INBUF,VRBUF)	$*\Delta AI$ is external short		Gain=2	1						

HY11P42

Embedded 18-Bit $\Sigma\Delta$ ADC

8-Bit RISC-like Mixed Signal Microcontroller

HYCON
HYCON TECHNOLOGY

	Offset temperature drift with chopper without Buffer (INBUF,VRBUF).		GAIN=1 GAIN=2 GAIN=4 GAIN=16	2 1 0.5 0.15	uV/°C
	Offset temperature drift with chopper and Buffer (INBUF,VRBUF)		GAIN=1 GAIN=2 GAIN=4	2 1 0.5	
	Offset temperature drift with chopper without Buffer (INBUF,VRBUF).		GAIN=128	0.02	
CM _{SD18}	Common-mode rejection	V _{CM} =0.7V to 1.7V, V _{VR} =1.0V,without PGA	V _{SI} =0V, GAIN=1	90	dB
		V _{CM} =0.7V to 1.7V, V _{VR} =1.0V,	V _{SI} =0V, GAIN=16	75	
PSRR	DC power supply rejection	VDDA=3.0V,ΔVDDA=±100mV, V,V _{VR} =1.0V, V _{SI} =1.2V,V _{SL} =1.2V,	GAIN=1 PGA=off	75	dB
		GAIN=16			

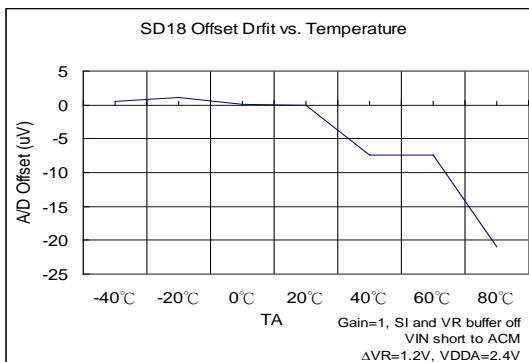


Figure 6.7-1(a) SD18 Offset Temperature Drift

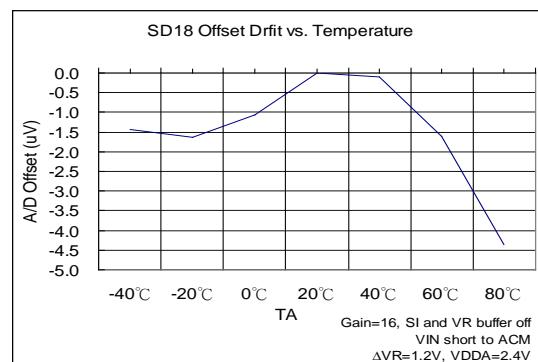


Figure 6.7-1(b) SD18 Offset Temperature Drift

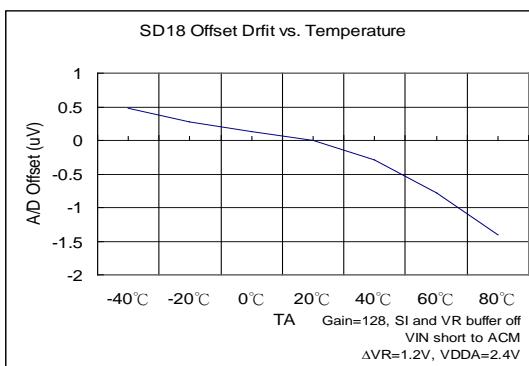


Figure 6.7-1(c) SD18 Offset Temperature Drift

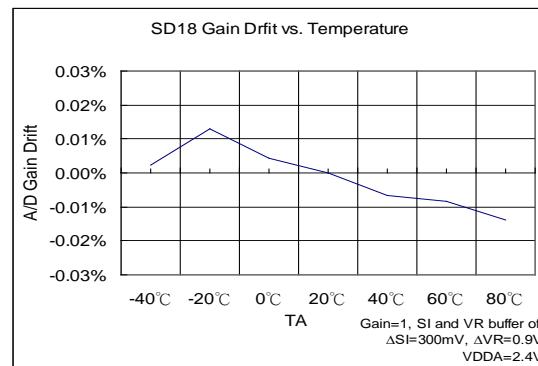


Figure 6.7-2(a) SD18 Gain Drift with Temperature

HY11P42

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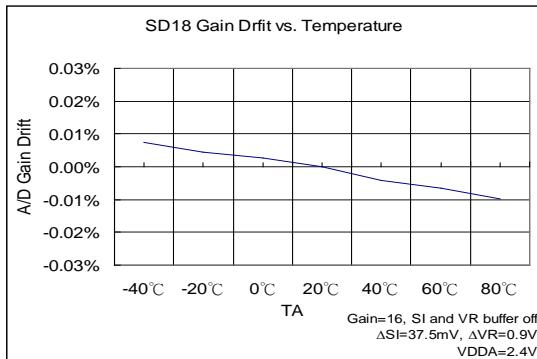


Figure 6.7-2(b) SD18 Gain Drift with Temperature

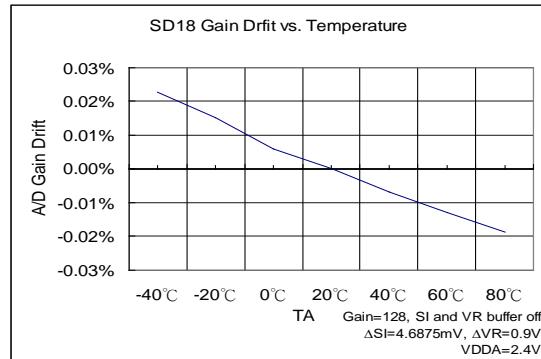


Figure 6.7-2(c) SD18 Gain Drift with Temperature

6.7.3 SD18, Temperature Sensor $T_A = 25^\circ\text{C}$, $V_{DD} = 3.0\text{V}$, $VDDA=2.4\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
TC_S	Sensor temperature drift			178		$\mu\text{V}/^\circ\text{C}$
KT	Absolute Temperature Scale 0°K	$\text{INBUF}[0]=1$		-289		$^\circ\text{C}$
TC_{ERR}	One point calibrate error temperature	Calibration at 25°C of $-40^\circ\text{C} \sim 85^\circ\text{C}$		± 2		$^\circ\text{C}$

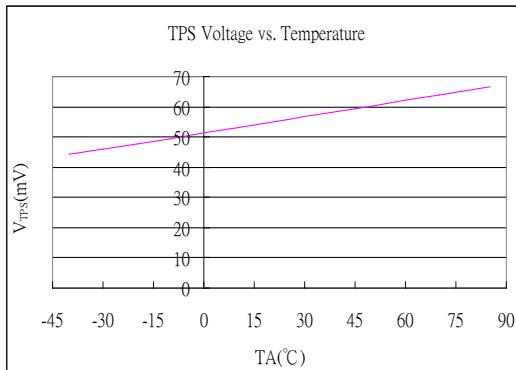


Figure 6.7-3 TPS Output Voltage vs. Temperature Drift

6.7.4 SD18 Noise Performance

$T_A = 25^\circ C, V_{DD} = 3.0V, VDDA=2.4V$, unless otherwise noted

HY11P42 provides important input noise specification that aims at SD18. Table6.7-4(a) and Table6.7-4(b) lists out the relations of typical noise specification, Gain, Output rate, and maximum input voltage of single end. Test condition configuration and external input signal short, voltage reference: 1.2V and 1024 records were sampled.

ENOB(RMS) with OSR/GAIN at A/D Clock=250Khz, VDDA=2.4V, VREF=1.2V												
Max. Vin(mV) =0.9*VREF ⁽¹⁾	OSR				256	512	1024	2048	4096	8192	16384	32768
	Output rate(HZ)				977	488	244	122	61	31	15	8
	Gain	=	PGA	x	ADGN							
± 2400	0.25	=	1	x	0.25	16.3	17.4	17.9	18.5	19.0	19.5	20.0
± 2160	0.5	=	1	x	0.5	16.3	17.3	17.9	18.4	18.9	19.4	19.8
± 1080	1	=	1	x	1	16.2	17.2	17.8	18.3	18.8	19.3	19.7
± 540	2	=	1	x	2	16.1	17.1	17.6	18.2	18.7	19.2	19.6
± 270	4	=	1	x	4	16.0	16.9	17.5	18.0	18.5	18.9	19.4
± 135	8	=	1	x	8	15.9	16.6	17.2	17.7	18.2	18.7	19.2
± 68	16	=	1	x	16	15.6	16.3	16.8	17.3	17.7	18.3	18.8
± 34	32	=	2	x	16	14.8	15.3	15.9	16.4	16.9	17.4	17.8
± 17	64	=	4	x	16	14.5	15.0	15.5	16.0	16.5	17.0	17.5
± 8	128	=	8	x	16	14.0	14.6	15.1	15.6	16.0	16.6	17.0

(1) Max.Vin (mV) is the max. input voltage of single end to ground (VSS).

Table6.7-4(a) SD18 ENOB Table

RMS Noise(uV) with OSR/GAIN at A/D Clock=250Khz, VDDA=2.4V, VREF=1.2V												
Max. Vin(mV) =0.9*VREF	OSR				256	512	1024	2048	4096	8192	16384	32768
	Output rate(HZ)				977	488	244	122	61	31	15	8
	Gain	=	PGA	x	ADGN							
± 2400	0.25	=	1	x	0.25	121.08	57.40	38.74	26.66	18.39	13.21	9.49
± 2160	0.5	=	1	x	0.5	61.63	29.23	19.21	13.51	9.78	7.02	5.12
± 1080	1	=	1	x	1	32.21	15.70	10.25	7.31	5.19	3.77	2.80
± 540	2	=	1	x	2	16.59	8.54	5.91	4.06	2.86	2.06	1.48
± 270	4	=	1	x	4	9.00	4.84	3.33	2.37	1.67	1.19	0.87
± 135	8	=	1	x	8	5.04	2.97	2.02	1.44	1.01	0.73	0.51
± 68	16	=	1	x	16	3.03	1.84	1.29	0.92	0.70	0.46	0.33
± 34	32	=	2	x	16	2.61	1.81	1.27	0.89	0.62	0.45	0.32
± 17	64	=	4	x	16	1.66	1.13	0.80	0.56	0.41	0.29	0.20
± 8	128	=	8	x	16	1.13	0.77	0.55	0.38	0.28	0.19	0.14

Table6.7-4(b) SD18 RMS Noise Table

The RMS noise is referred to the input. The Effective Number of Bits (ENOB(RMS Bit)) is defined as:

$$\text{ENOB(RMS)} = \frac{\ln\left(\frac{\text{FSR}}{\text{RMS Noise}}\right)}{\ln(2)}$$

$$\text{RMS Noise} = \frac{\left(2 \times \text{VREF} \times \sqrt{\sum_{k=1}^{1024} (\text{ADO}[k] - \text{Average})^2}\right)}{2^{23}}$$

Where FSR (Full - Scale Range) = $2 \times \text{VREF}/\text{Gain}$.

$$\text{Average} = \frac{\sum_{k=1}^{1024} (\text{ADO}[k])}{1024}$$

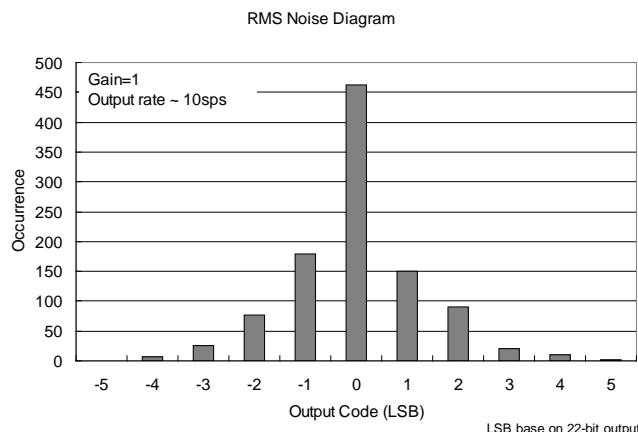


Figure 6.7-4(a) RMS Noise Diagram

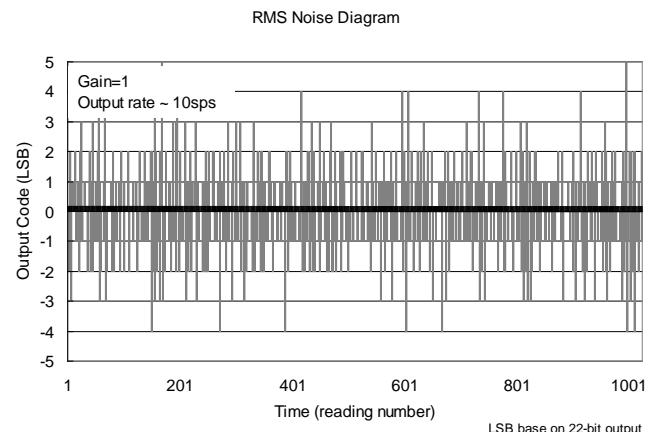


Figure 6.7-4(b) Output Code Diagram

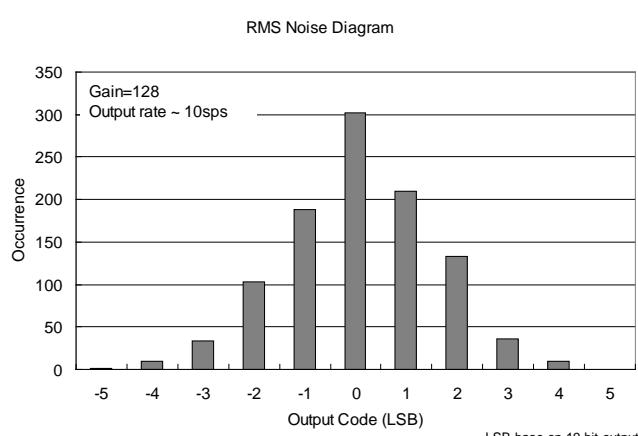


Figure 6.7-4(c) RMS Noise Diagram

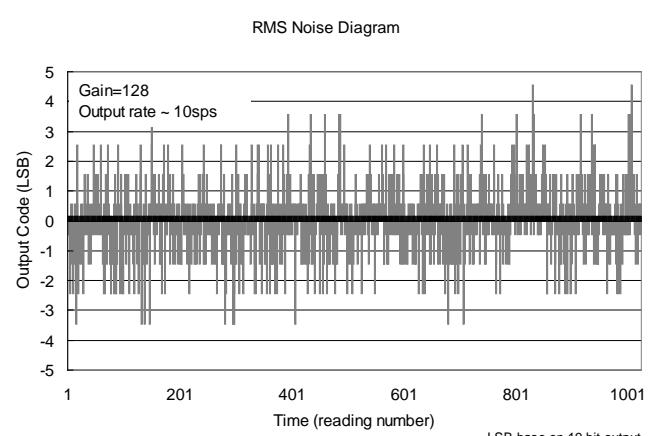


Figure 6.7-4(d) Output Code Diagram

6.8 Built-in EPROM (BIE)

$T_A = 25^\circ\text{C}$, $V_{DD} = 3.0\text{V}$, unless otherwise noted

Sym.	Parameter	Test Conditions	Min.	Typ.	Max.	unit
V_{BIE}	Supply Voltage		6.0	6.5		V
I_{BIE}	Operation supply current		5			mA
V_{SS}	Supply Voltage		0			V

7. Ordering Information

Device No. ¹	Package Type	Pins	Package Drawing		Code ²	Shipment Packing Type	Unit Q'ty	Material Composition	MSL ³
HY11P42-D000	Die	-	D	000	000	-	200	Green ⁴	-
HY11P42-E028	SSOP	28	E	028	000	Tube	48	Green ⁴	MSL-3
HY11P42-E028	SSOP	28	E	028	000	Tape & Reel	2000	Green ⁴	MSL-3
HY11P42-N024	QFN	24	N	024	000	Tray	490	Green ⁴	MSL-3
HY11P42-T028	TSSOP	28	T	028	000	Tube	50	Green ⁴	MSL-3
HY11P42-T028	TSSOP	28	T	028	000	Tape & Reel	4000	Green ⁴	MSL-3

¹ Device No.: Model No. – Package Type Description – Code (Blank Code/ Standard/ Customized Programming Code)

Ex: Your customized programming code is 008 and you require die shipment.

The device No. will be HY11P42-D000-008

Ex: You request blank code in die package.

The device No. will be HY11P42-D000

Ex: You request blank code in SSOP28 package.

The device No. will be HY11P42-E028

And please clearly indicate the shipment packing type when placing orders.

Ex: Your customized programming code is 009 and you require products in TSSOP28 package.

The device No. will be HY11P42-T028-009.

And please clearly indicate the shipment packing type when placing orders.

² Code:

“001”~ “999” is standard or customized programming code. Blank code does not have these numbers.

³ MSL:

The Moisture Sensitivity Level ranking conforms to IPC/JEDEC J-STD-020 industry standard categorization. The products are processed, packed, transported and used with reference to IPC/JEDEC J-STD-033.

⁴ Green (RoHS & no Cl/Br):

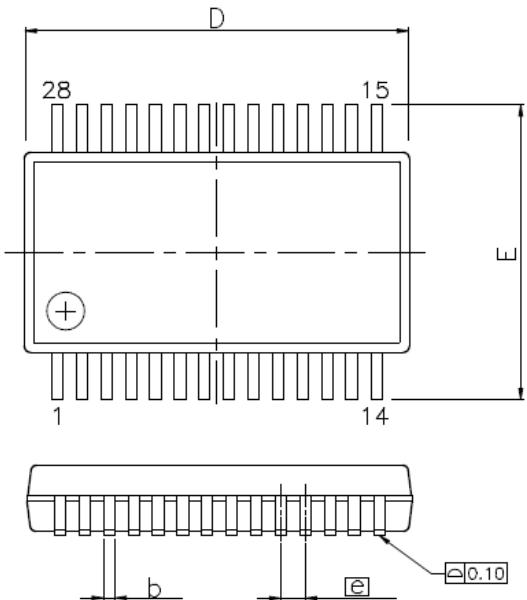
HYCON products are Green products that compliant with RoHS directive and are

Halogen free (Br<900ppm or Cl<900ppm or (Br+Cl)<1500ppm).

8. Package Information

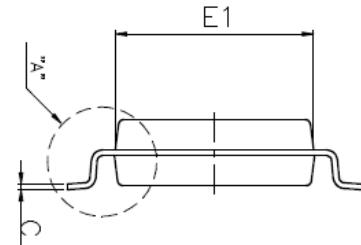
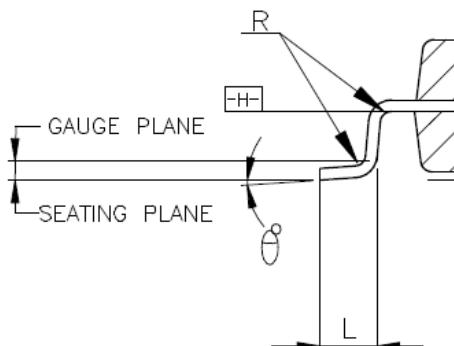
8.1 SSOP28 (E028)

8.1.1 Package Dimensions SSOP28(209mil)

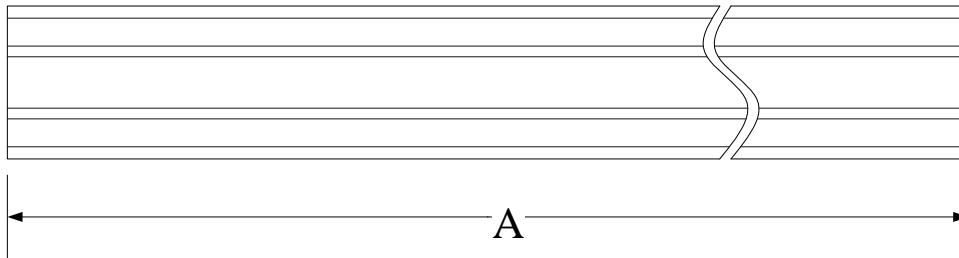


SYMBOLS	MIN.	NOM.	MAX.
A	—	—	2.0
A1	0.05	—	—
A2	1.65	1.75	1.85
b	0.22	—	0.38
c	0.09	—	0.25
D	10.05	10.20	10.50
E	7.65	7.80	7.90
E1	5.00	5.30	5.60
e	0.65 BSC		
L	0.55	0.75	0.95
R	0.09	—	—
θ°	0°	4°	8°

UNIT : MM



JEDEC MO-150 compliant

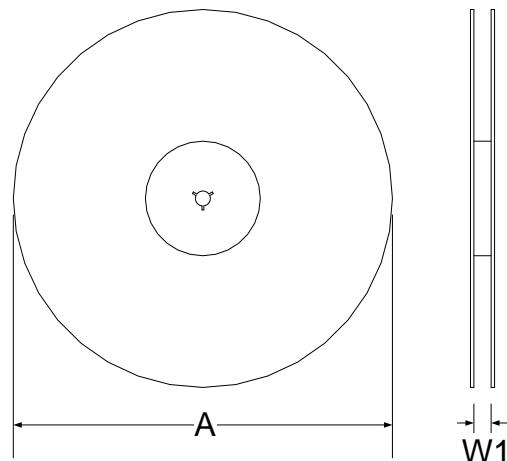
8.1.2 Tube Dimensions SSOP28(209mil)**Unit : mm**

SYMBOLS	A	B	C
Spec.	510±1.5	10.20±0.10	3.75±0.10

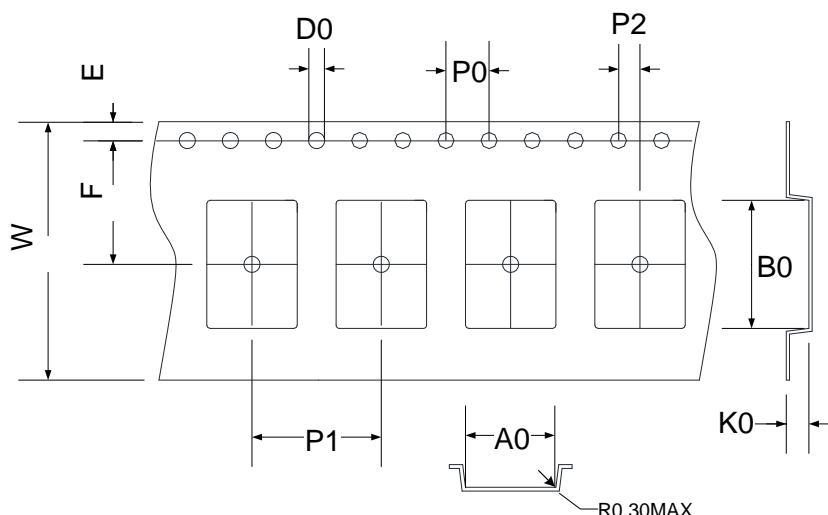
8.1.3 Tape & Reel Information SSOP28(209mil)

8.1.3.1 Reel Dimensions

Unit: mm



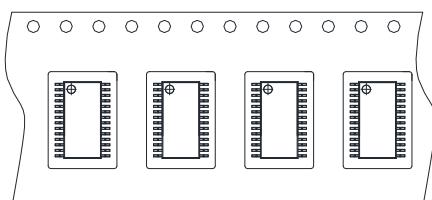
8.1.3.2 Carrier Tape Dimensions



SYMBOLS	Reel Dimensions		Carrier Tape Dimensions									
	A	W1	A0	B0	K0	P0	P1	P2	E	F	D0	W
Spec.	330	24.5	8.40	10.65	2.40	4.00	12.00	2.00	1.75	11.50	1.50	24.00
Tolerance	+6/-3	+1.5/-0	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.30

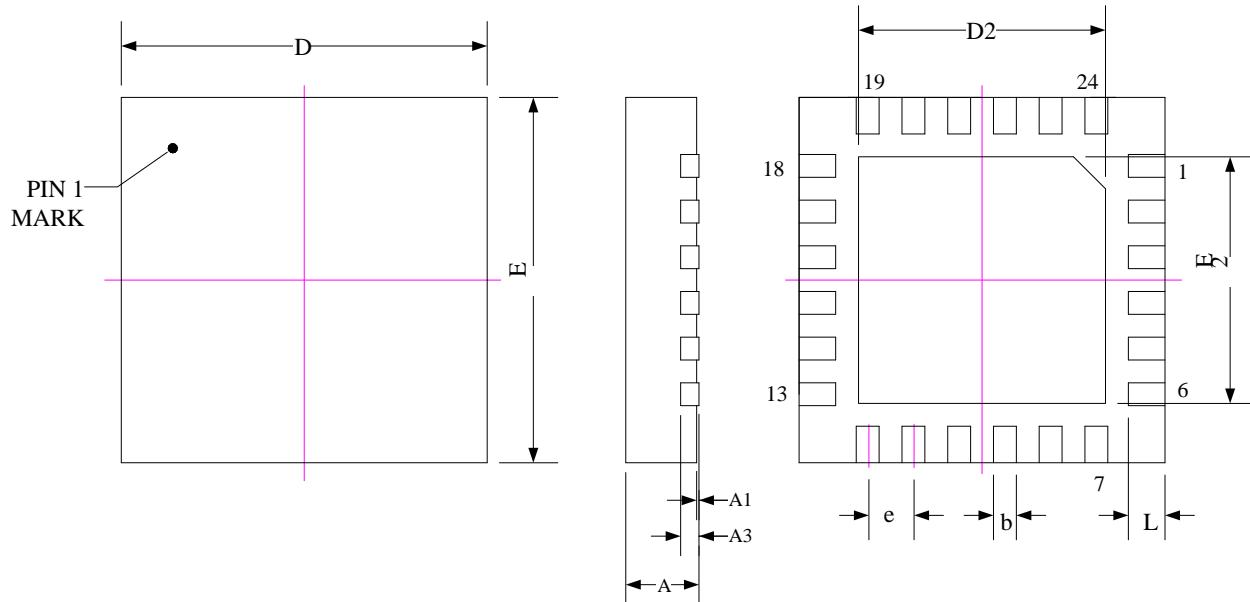
Note: 10 Sprocket hole pitch cumulative tolerance is ± 0.20 mm.

8.1.3.3 Pin1 direction



8.2 QFN24(N024)

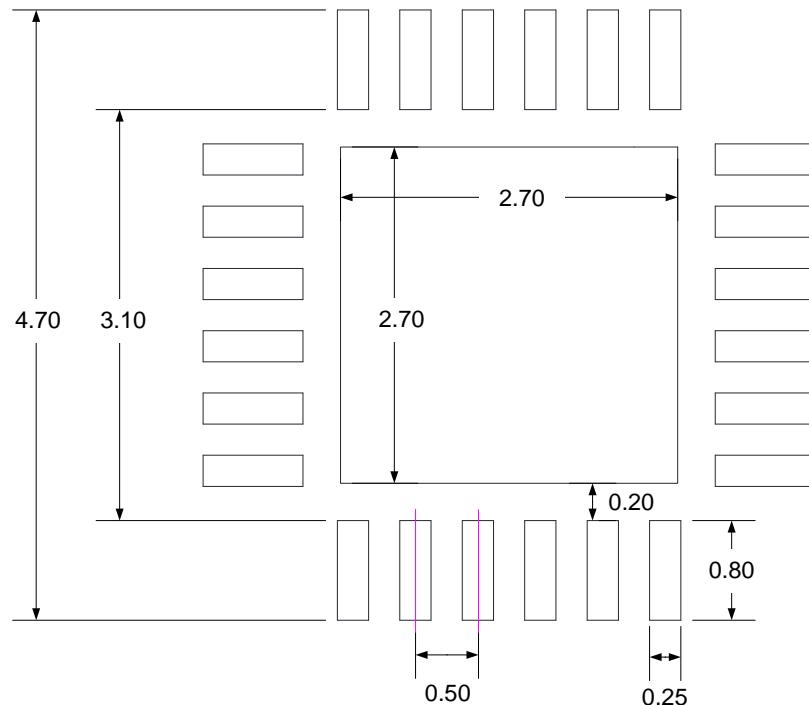
8.2.1 Package Dimensions QFN24(4x4)



SYMBOLS	MIN	NOM	MAX
A	0.70	0.75	0.80
A1	0.00	0.02	0.05
A3	0.20 REF.		
b	0.18	0.25	0.30
D	3.90	4.00	4.10
E	3.90	4.00	4.10
D2	2.60	2.70	2.80
E2	2.60	2.70	2.80
L	0.35	0.40	0.45
e	0.50 BASIC		

Note:

1. All dimensions refer to JEDEC OUTLINE MO-220.
2. Do not include Mold Flash or Protrusions.
3. Unit: mm.

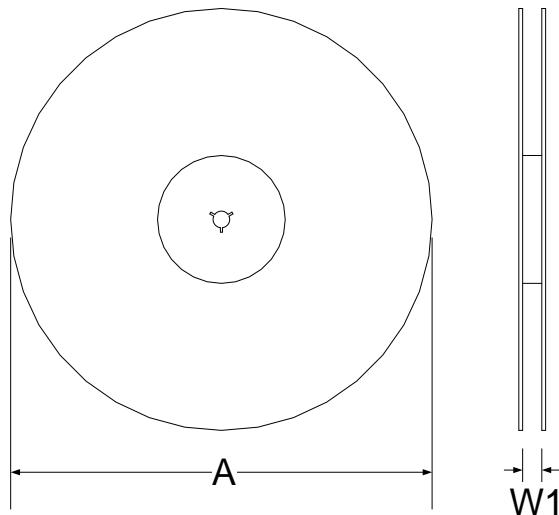
8.2.2 Package Dimensions QFN24(4x4)

Note:

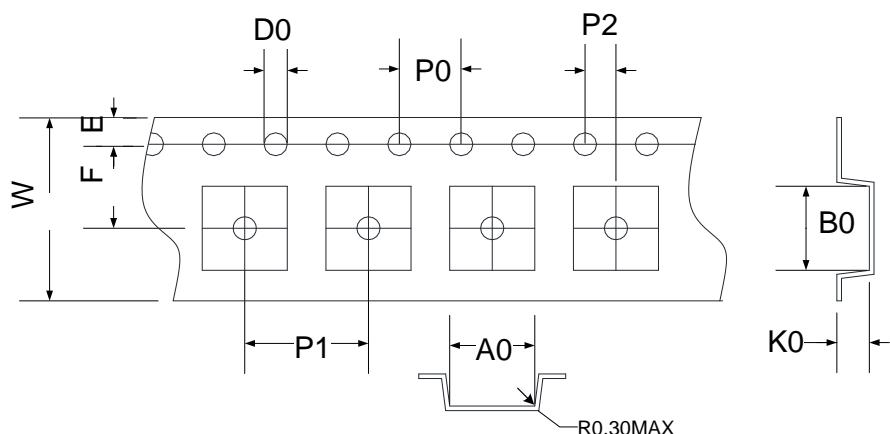
1. Publication IPC-7351 is recommended for alternate designs.
2. https://www.hycontek.com/wp-content/uploads/QFN_DFN_PCB.pdf
3. Unit: mm.

8.2.3 Tape & Reel Information QFN24(4x4)

8.2.3.1 Reel Dimensions



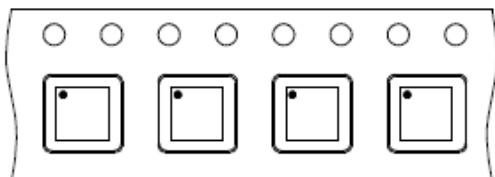
8.2.3.2 Carrier Tape Dimensions



SYMBOLS	Reel Dimensions		Carrier Tape Dimensions										
	A	W1	A0	B0	K0	P0	P1	P2	E	F	D0	W	
Spec.	330	12.5	4.35	4.35	1.10	4.00	8.00	2.00	1.75	5.50	1.50	12.00	
Tolerance	+6/-3	+1.5/-0	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.05	± 0.10	± 0.05	+0.1/-0	± 0.30

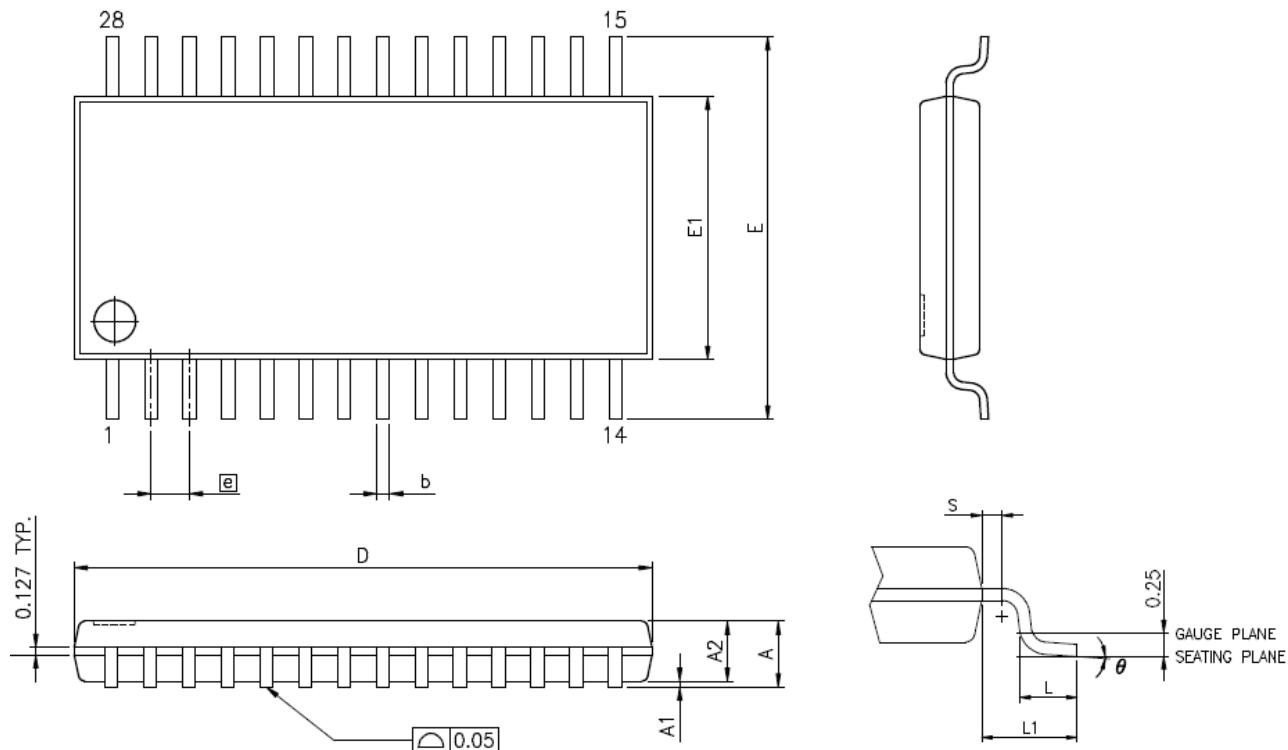
Note: 10 Sprocket hole pitch cumulative tolerance is ± 0.20 mm.

8.2.3.3 Pin1 direction



8.3 TSSOP28(T028)

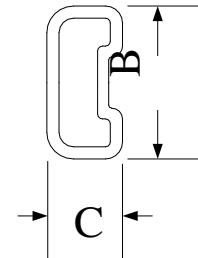
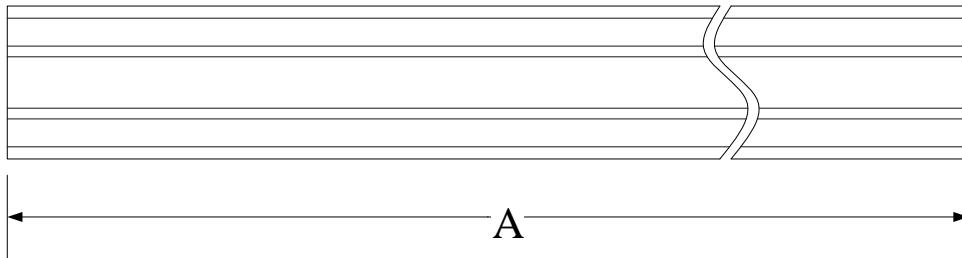
8.3.1 Package Dimensions TSSOP28(173mil)



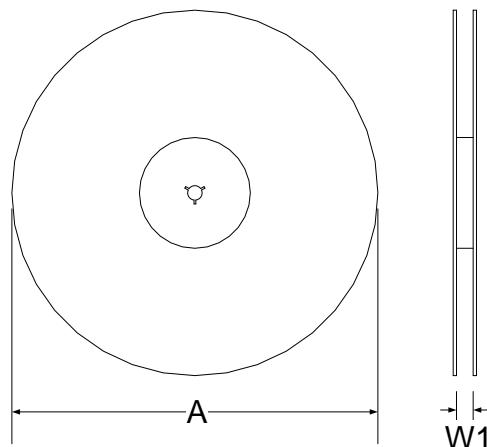
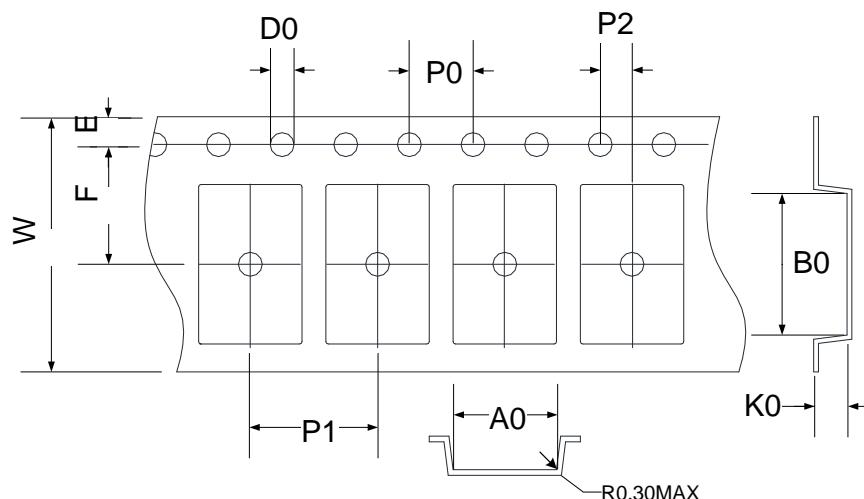
SYMBOLS	MIN.	NOM.	MAX.
A	—	—	1.20
A1	0.00	—	0.15
A2	0.80	1.00	1.05
b	0.19	—	0.30
D	9.60	9.70	9.80
E1	4.30	4.40	4.50
E	6.40 BSC		
	0.65 BSC		
L1	1.00 REF		
L	0.45	0.60	0.75
S	0.20	—	—
θ	0°	—	8°

Note:

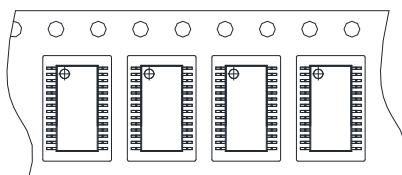
1. All dimensions refer to JEDEC OUTLINE MO-153.
2. Do not include Mold Flash or Protrusions.
3. Unit: mm.

8.3.2 Tube Dimensions TSSOP28(173mil)**Unit : mm**

SYMBOLS	A	B	C
Spec.	515.0±1.5	8.45±0.1	3.0+0.05/-0.10

8.3.3 Tube Dimensions TSSOP28(173mil)**Unit : mm****8.3.3.1 Reel Dimensions****8.3.3.2 Carrier Tape Dimensions**

SYMBOLS	Reel Dimensions		Carrier Tape Dimensions									
	A	W1	A0	B0	K0	P0	P1	P2	E	F	D0	W
Spec.	330	16.5	6.80	10.20	1.60	4.00	8.00	2.00	1.75	7.50	1.50	16.00
Tolerance	+6/-3	+1.5/-0	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.10	± 0.30

Note: 10 Sprocket hole pitch cumulative tolerance is ± 0.20 mm.**8.3.3.3 Pin1 direction**

9. Revision Record

Major differences are stated hereinafter:

Version	Page	Revision Summary
V03	All	First Edition
V07	6	Add in 2.2 TSSOP28 Pin Diagram
	8~9	2.4 SSOP28 Pin out I/O Description order revision
	10~11	Chapter 3 Application Circuit revision
	13	4.1 Internal Block Diagram & 4.2 Related Description and Supporting Documents
	14	revision
	15	4.3 SD18 Network revision
	32	Chapter 5 Register List revision
	35	Chapter 7 Ordering Information revision Add in 8.3 TSSOP28(T028)
V08	5~9,14~17,19	Delete the related description and figures of Serial Communication SPI module.
	10~11	Add in 2.5 TSSOP28 Pin out I/O Description
	12~13	Add in 2.6 QFN24 Pin out I/O Description
V10	21	Update Internal RC Oscillator frequency spec
V11	14~15	Add Package marking information
	38	Update "MSL" and "Green" Description
	39~47	Update "Package Outline Drawing" and "PACKING IMFORMATION"